

ALERT: Awareness and Localization of Explosives-Related Threats



Fusing Millimeter-Wave Technologies for Advanced Imaging Technology

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Conclusions

- Established detection regime and parameters
- Described why fusion necessary
- Showed potential challenges and considerations with fusion with mm-waves
- Described the ALERT AIT Testbed (ScanBED)
- Explained how advanced simulation and modeling saves lots of time and money
- Presented a specific example of the potential of fusing x-ray backscatter with mm-wave sensing
- Described the plans for ScanBED multi-modal fusion



Outline

- What detection regime is examined?
- Why is fusion necessary?
- Why is fusion problematic?
- What must be considered for fusing with mm-waves?
- What is the ALERT AIT Testbed (ScanBED)?
- How can advanced simulation and modeling save lots of money?
- What is the specific potential of fusing x-ray backscatter with mm-wave?
- What are our plans for ScanBED multi-modal fusion?

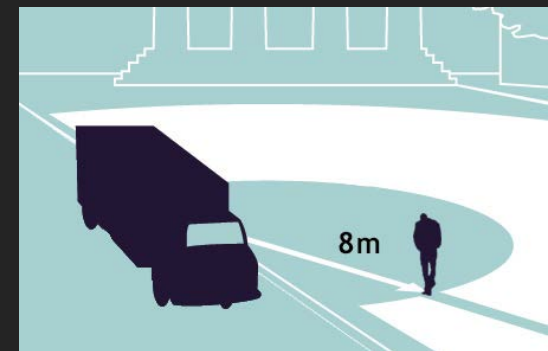


Advanced Imaging Technology Problem Space

- Intimately near targets (< 3 m)
 - Portal sensors
 - Non-invasive examination
 - Fast sensing, real time processing
 - 99.997% detection probability
 - *Manageable* false alarm rate
 - Safe
 - Publicly acceptable



[Mm- wave sensing can also be fused with X-ray, THZ, video, trace for Mid-range targets (3 to 10m)]



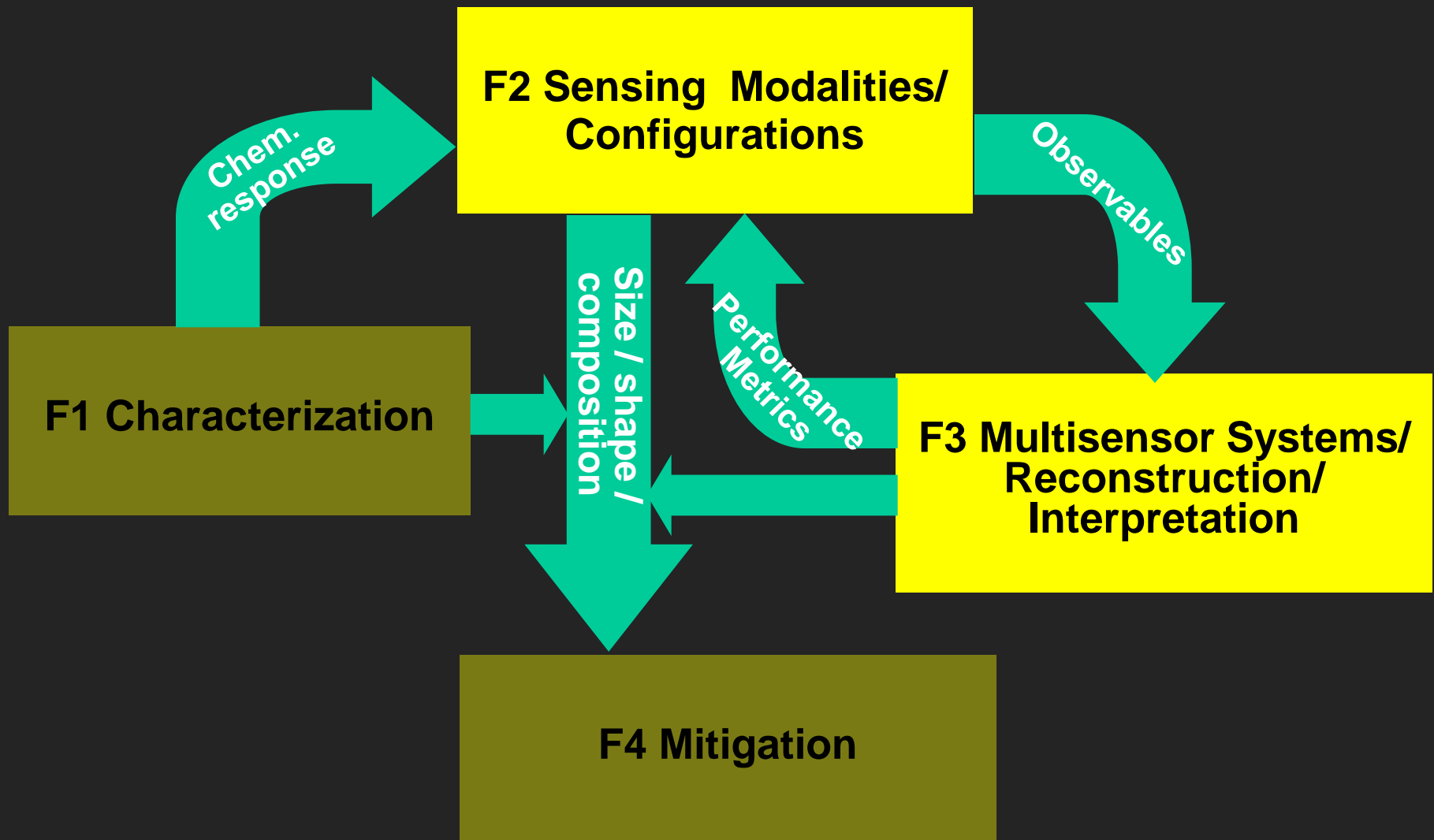


Detecting and Identifying Explosives

- Sense within hidden / concealed / shielded / non-stationary environments
- Optical imaging to detect suspicious **shapes/size** (**video, patterned video**)
- **Wave-based** imaging to detect suspicious **shapes/size** (**mm-wave radar, X-ray, THz, acoustics**)
- **Chemical trace** detection of suspicious materials (**Mass Spec., Ion Mobility Spec., Gas Chrom., “Artificial Dog Nose”**)
- **Material ID** spectral response to characterize molecular structure (**Hyperspectral, IR, UV, THz, NQR, LIBS , NMR**)



Sensing Thrust couples with Systems Thrust in ALERT Center



Coordination both across discipline and among thrusts is essential



Fusion is Necessary

No non-invasive sensor is capable of unequivocal identification of all concealed threats in reasonable time

- Shape-based detection cannot determine composition: **false alarms for canonical or non-specific shapes**
- Chemical sensors cannot penetrate concealing layers: **thick covering hides threat**
- Material composition sensors are non-local or must be repeated: **slow**
- Various modalities are **dangerous** (not eye-safe), **ionizing** (x-ray)
- Sensors that are effective in the lab **fail in the field**



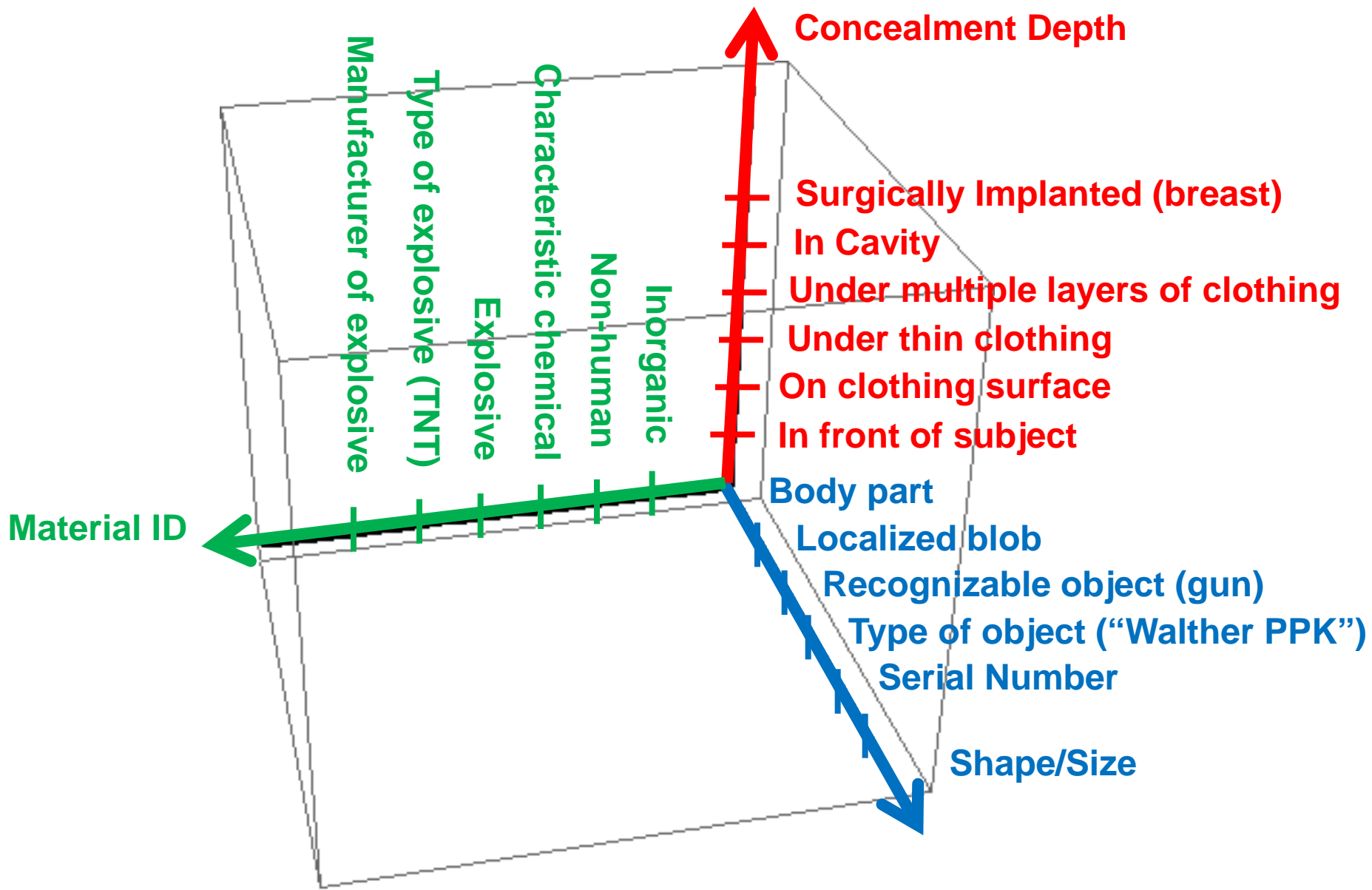
Fusion is Problematic

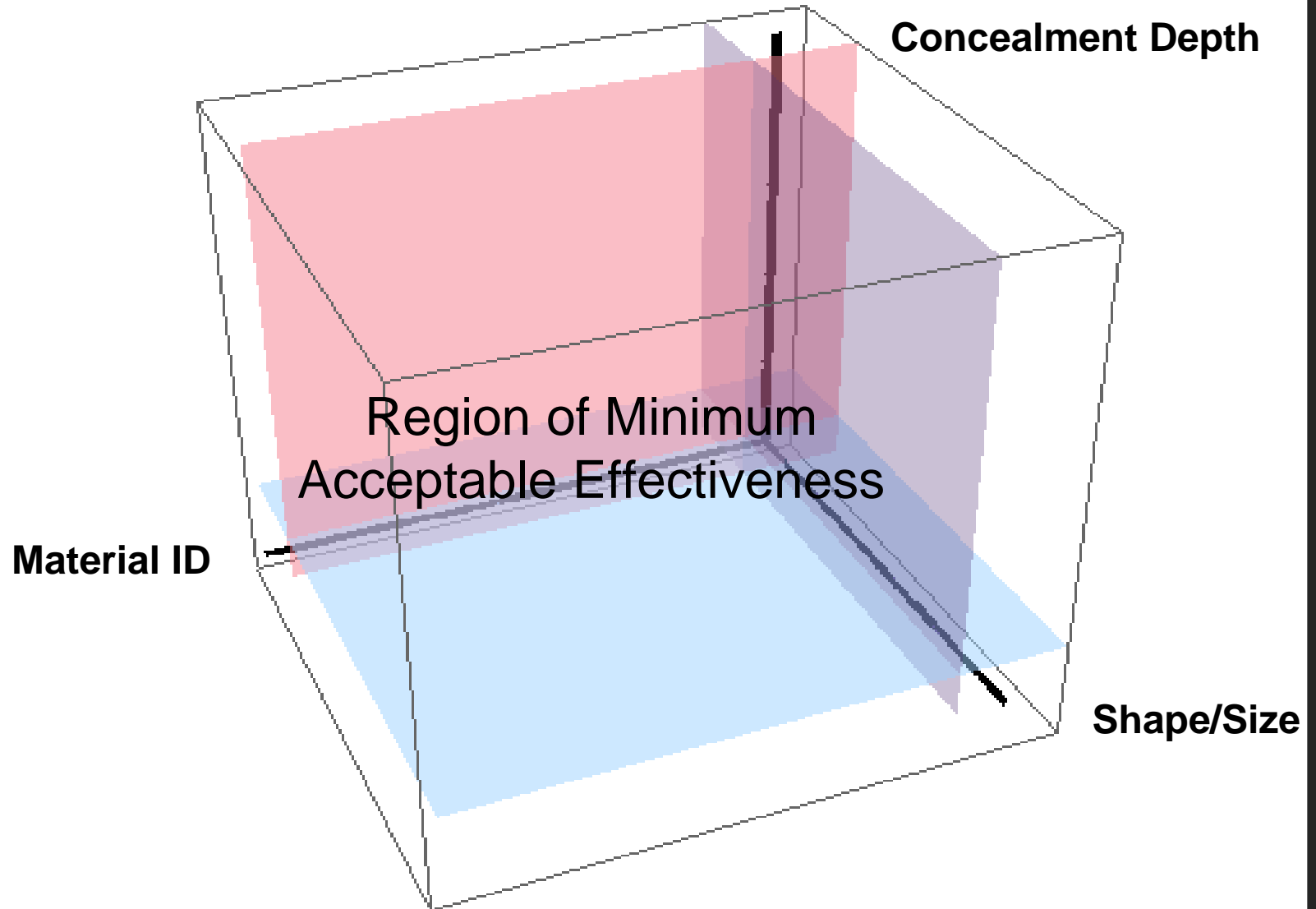
- More sensors do not guarantee more *useful* information
 - If second sensor is too similar: no addition information
 - If second sensor is too noisy: can obscure information
 - If second sensor is contradictory: hard to decide (3 clocks)
- Orthogonality of sensor information is worthwhile, but only if added information is useful for detection
 - Form factor is challenging
 - One physically sensor blocks others
 - Sensors interfere
- Additional sensors increases cost
 - Must justify higher cost for marginal additional information
 - Is a higher performance single sensor better than multiple fused sensors?

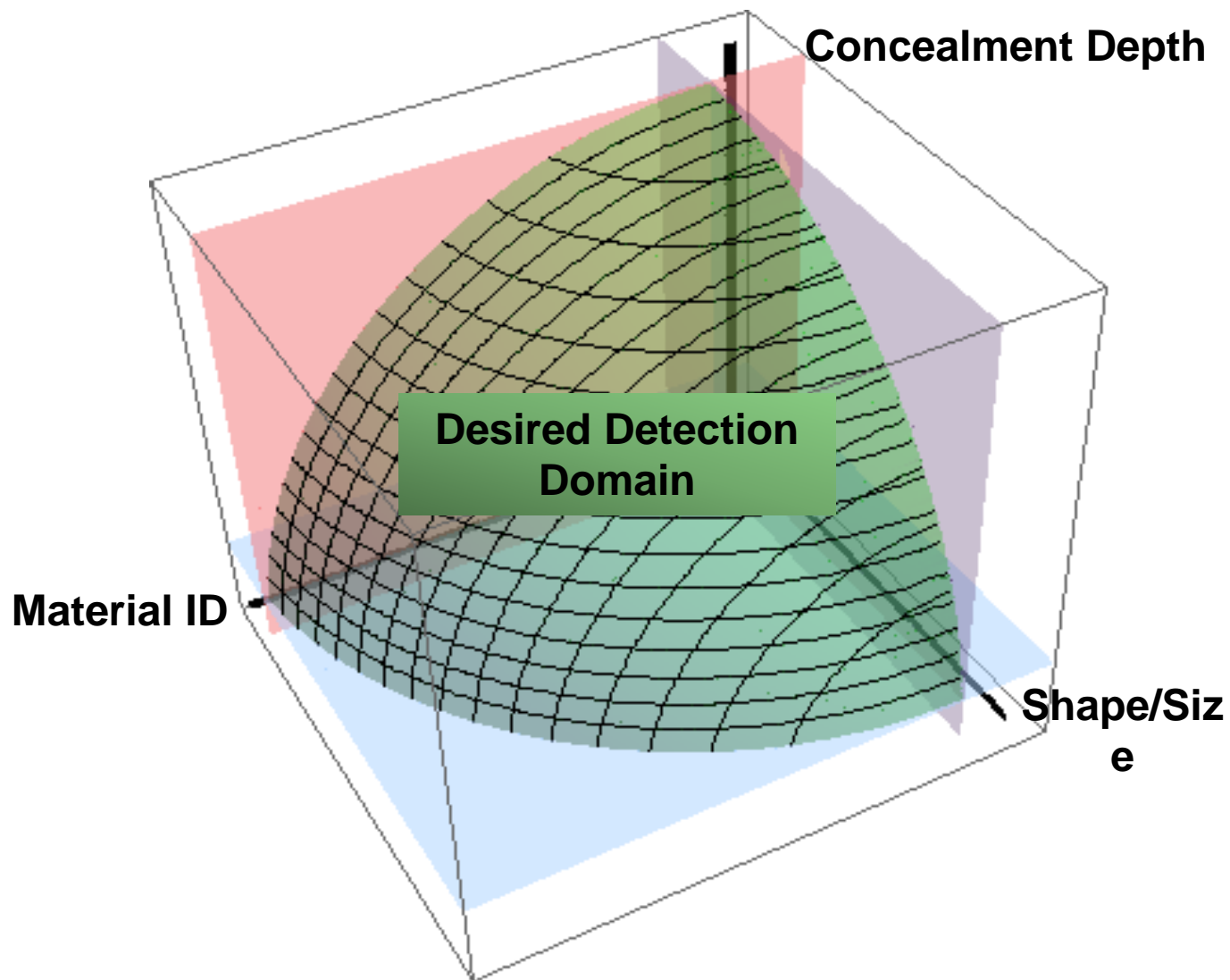


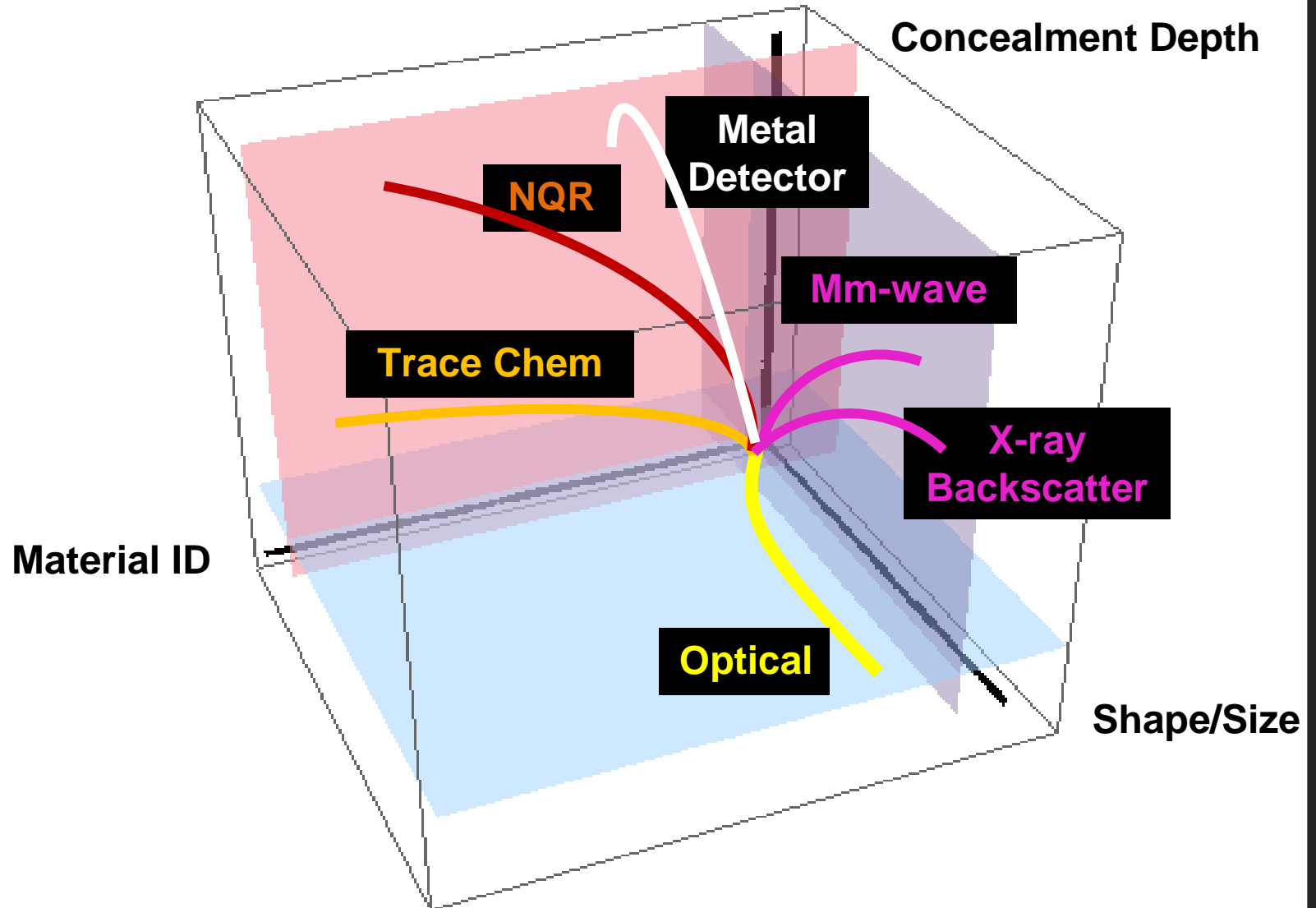
AIT Sensing Table (from White)

Sensor	Wavelength/energy	Signature	Detection Type
Metal Detectors	kHz	Eddy current induced in metals	Material ID
Active mm-wave	20-40GHz (15-7.5mm)	Dielectric scattering contrast	Shape/size
Passive mm-wave	30-300GHz (10-1mm)	Natural blackbody radiation	Shape/size
X-ray backscatter	50-125kVp	Differential scattering (Z_{eff} , ρ)	Shape/size
X-ray transmission	80-160kVp	Differential attenuation (Z_{eff} , ρ)	Shape/size
IR thermography	8-10 μ m	Thermal emission from body	Shape/size
IR spectroscopy	8-13 μ m	RF molecular vibration absorption	Material ID
Trace portal/puffer		IMS (or MS) spectral match	Material ID
THz imaging	0.1-3THz (3-0.01mm)	Attenuation /scattering from dielectrics	Shape/size
THz spectroscopy	0.1-3THz (3-0.01mm)	RF molecular vibration absorption	Material ID
NQR	0.5-5MHz	RF resonance (molecular/N environ.)	Material ID
NMR	kHz	Characteristic RF decay from ^1H	Material ID











Considerations for Fusing Technologies with Mm-Wave Sensing

- Compensate for deficiencies of mm-wave sensing
 - Low resolution
 - No skin penetration
 - No material identification
 - Heavy computation
- Establish minimum desired sensing requirement
- Consider completely orthogonal sensor
 - No joint inversion – simple union of sensor info
- Consider front-end fusion – joint inversion
 - Initial guess
 - Regions of particular interest

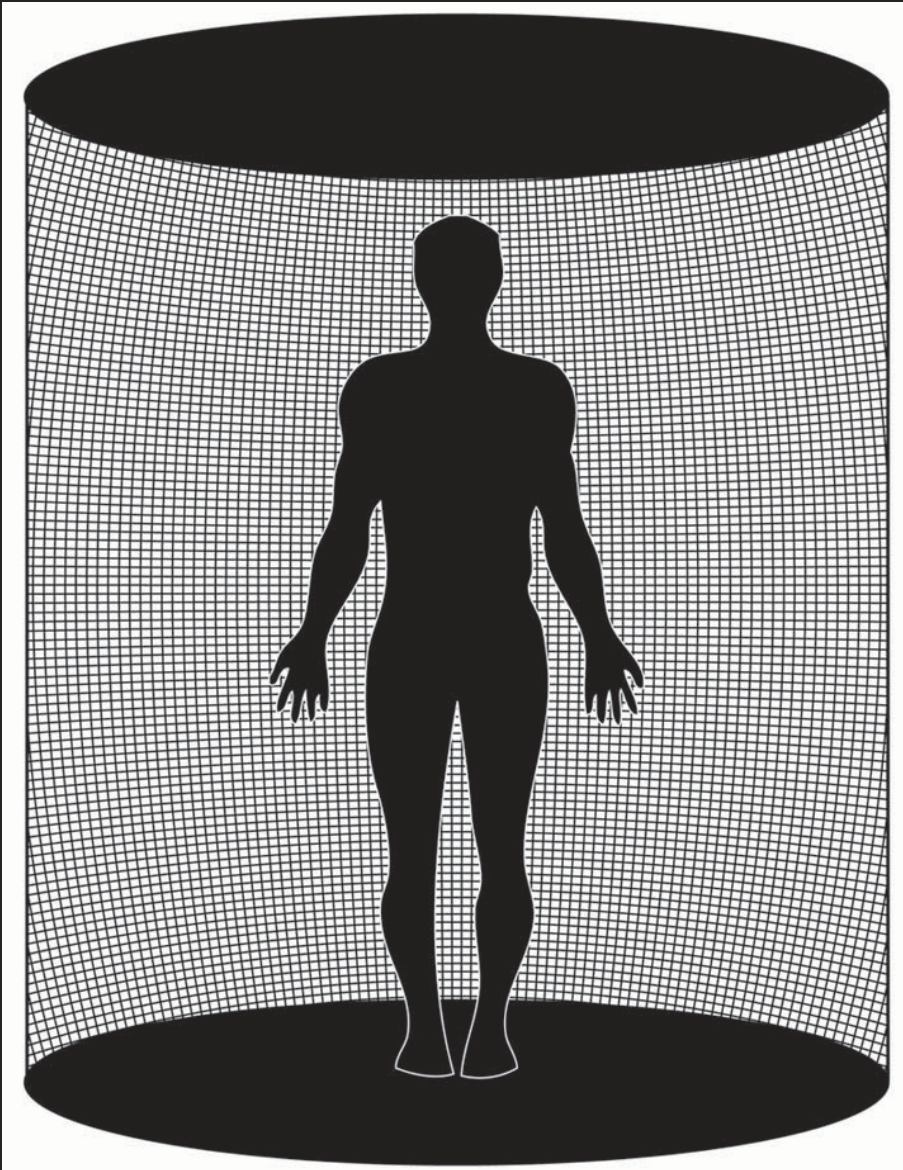


Whole Body Imaging Testbed at NEU

- Precision portal multi-axis sensor array positioning system
 - Designed to accommodate various types of sensors
 - Separately, for analysis
 - Together, to test fused sensor information
 - Built to be flexible for reconfiguration
- Provide access to raw measurement data
 - Allows specific, modality-based inversion
 - Allows joint modality reconstruction
- Ultimate Goals
 - Establish performance metrics for sensor modalities
 - Develop and evaluate novel inversion and multi-modal threat detection algorithms



Portal Provides the Possibility for Full Aperture Sensing



Huge 360 deg. Aperture

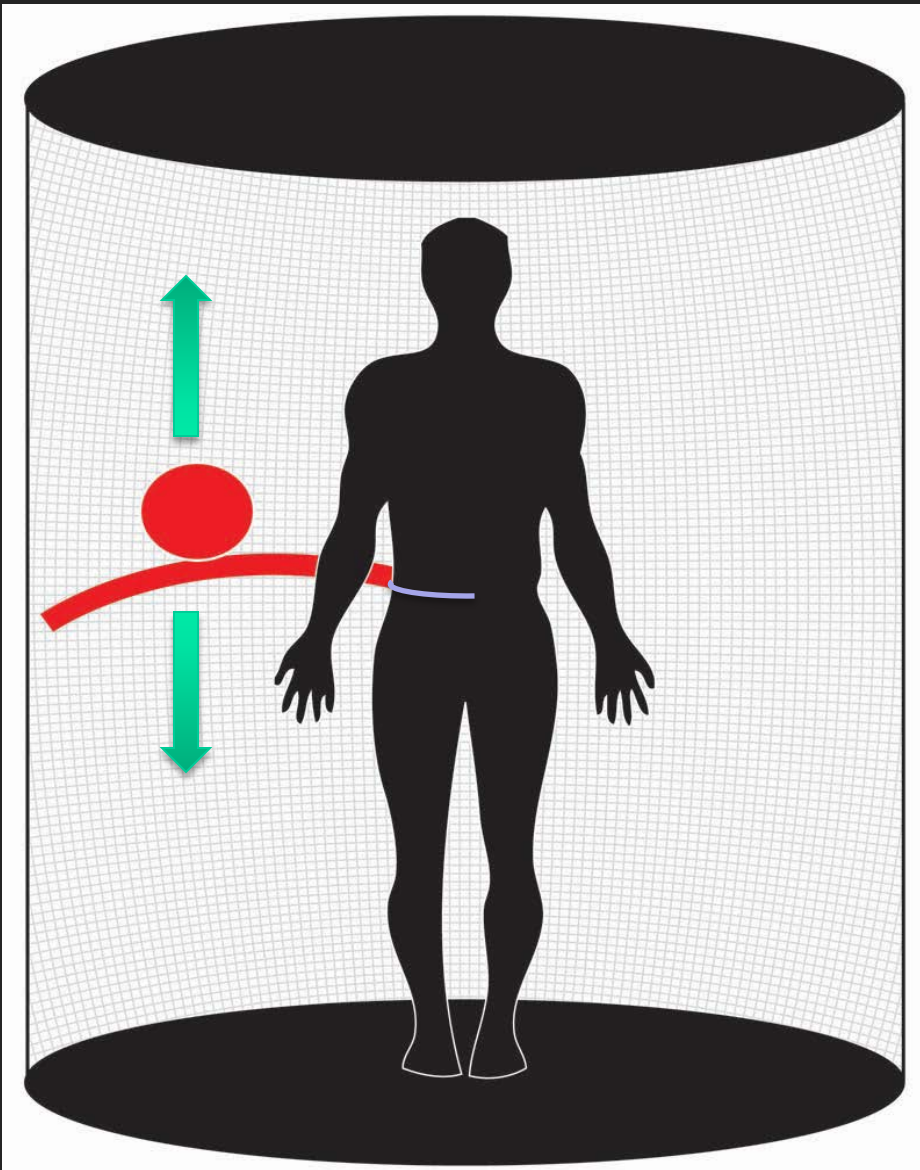
- Almost perfect body surface reconstruction
- No motion artifacts

However:

- Very expensive
- Long acquisition time
- Long computation time and massive storage
 $(500 \times 1000)^2$ Tx/Rx
10,000 (cm²) body pts.
= 2.5×10^{15} focusing calculations



Expedient Alternative: Vertically Moving Focusing Reflector Antenna Trans./Arc Array Rec.



One transmitter

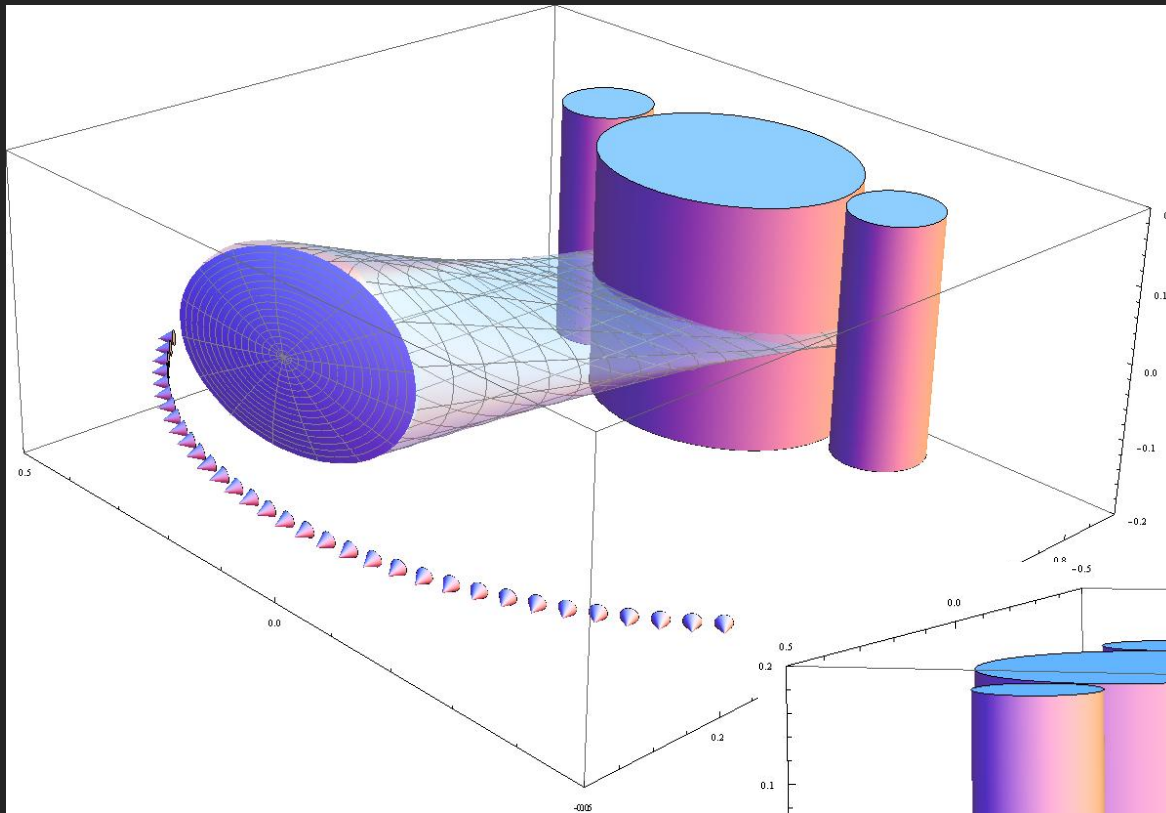
- Moves up/down
- Focuses on thin slice
- Allows multiple 2D processing
- Minimal motion artifacts

Arc Receiver

- Quarter circle
- Sparse element positions
- Moves up/down with transmitter
- Multistatic: no dihedral artifacts



Specially Designed Elliptical Parabolic Reflector Focuses to a Thin Slice on Body

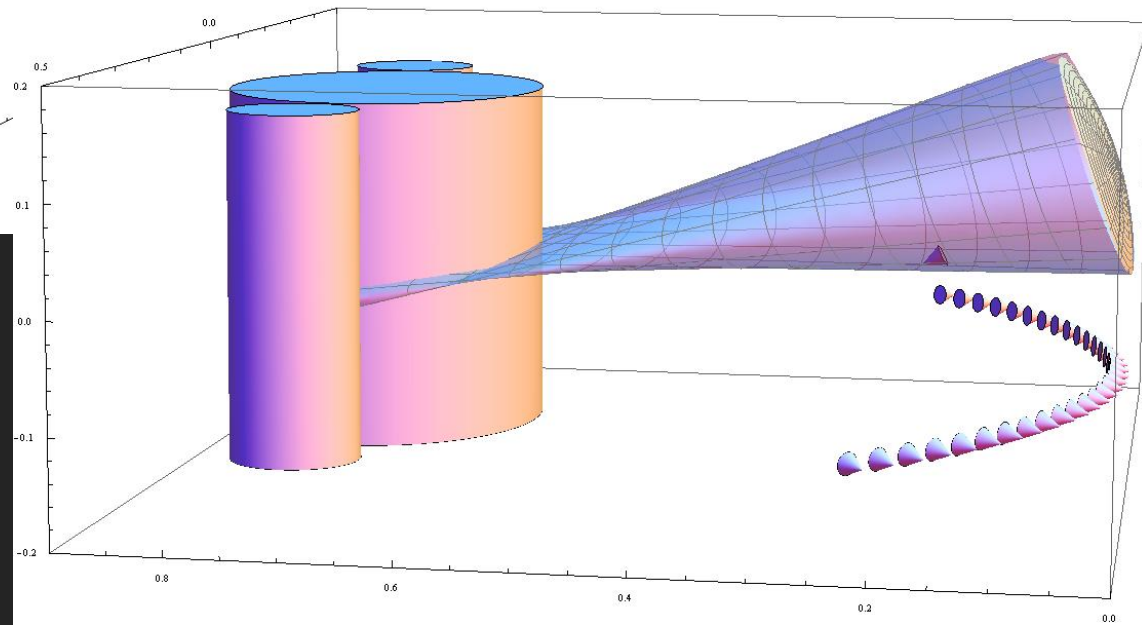


Parabolic in azimuth

- Gives wide beam
- Parallel incident rays

Elliptical in elevation

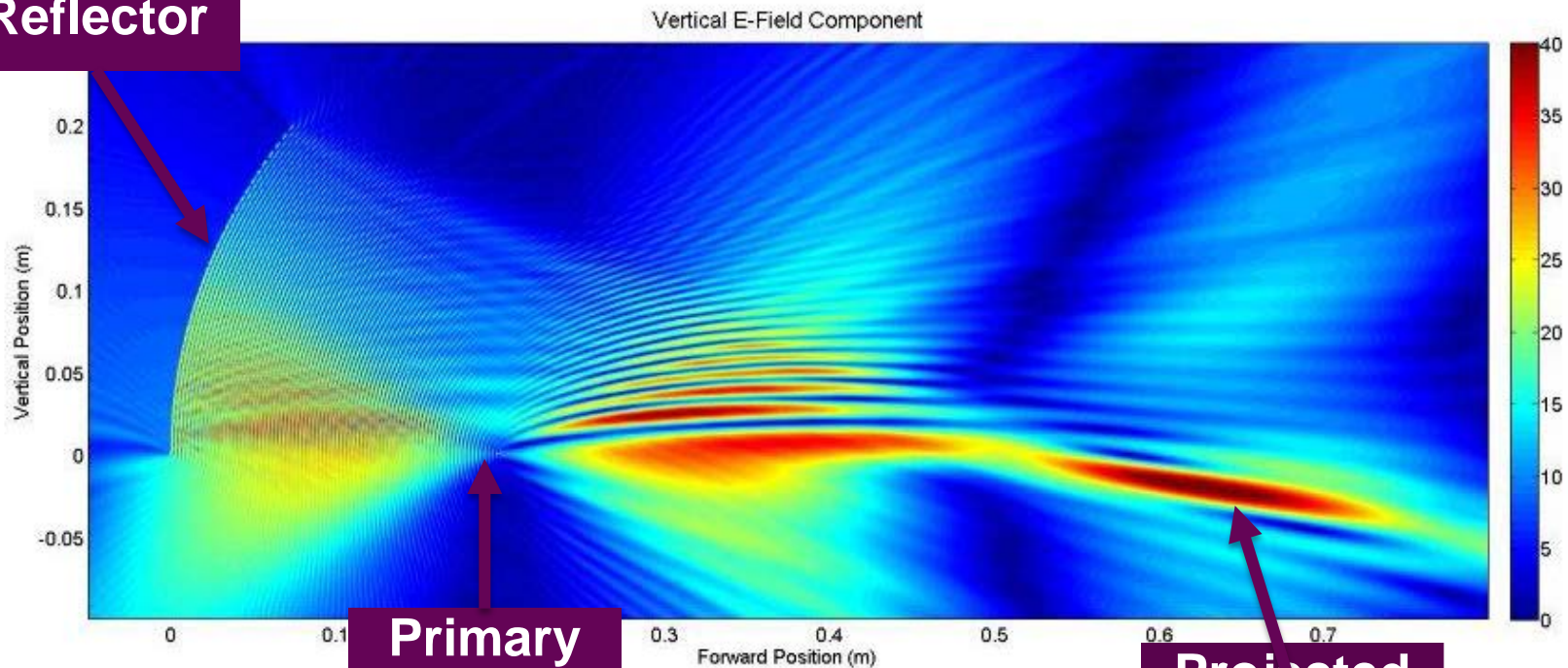
- Gives tight “Blade Focus”
- Illuminates narrow slice





Full Wave FDFD modeling of Elliptical Reflector Focusing to a Thin “Blade Beam”

Elliptical Reflector

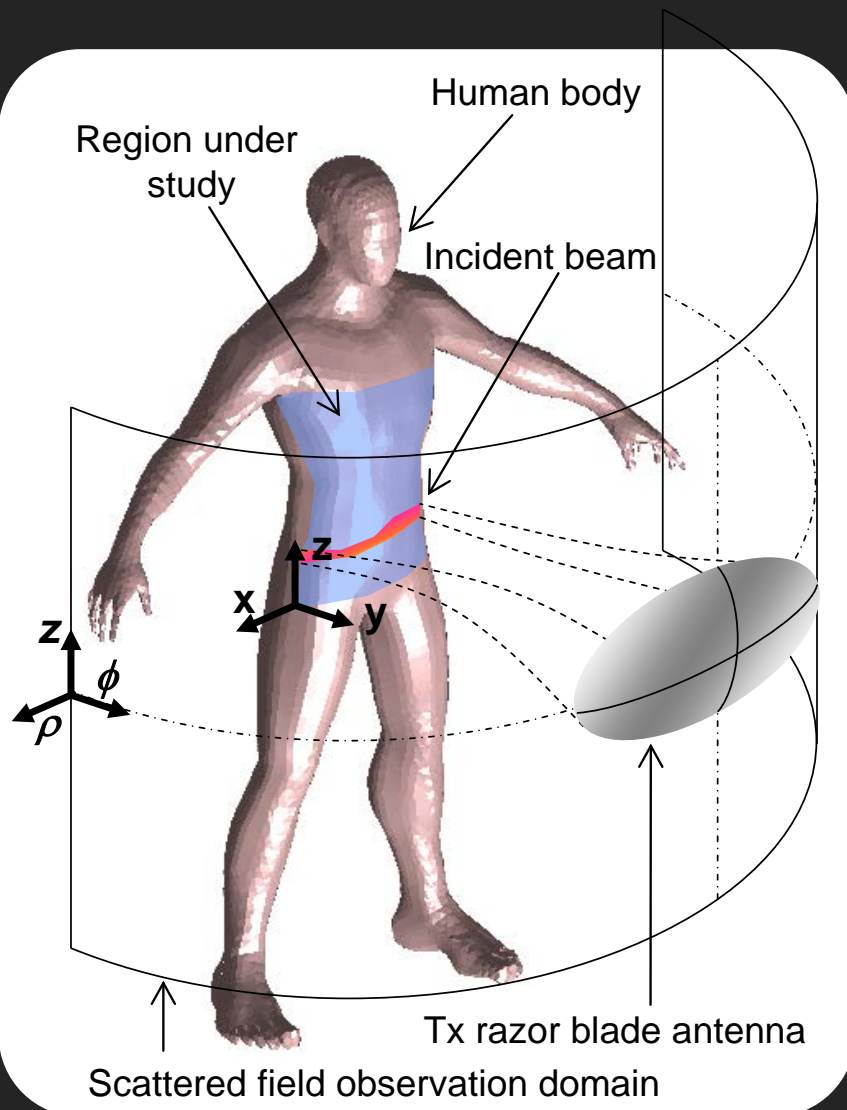


Primary Focus

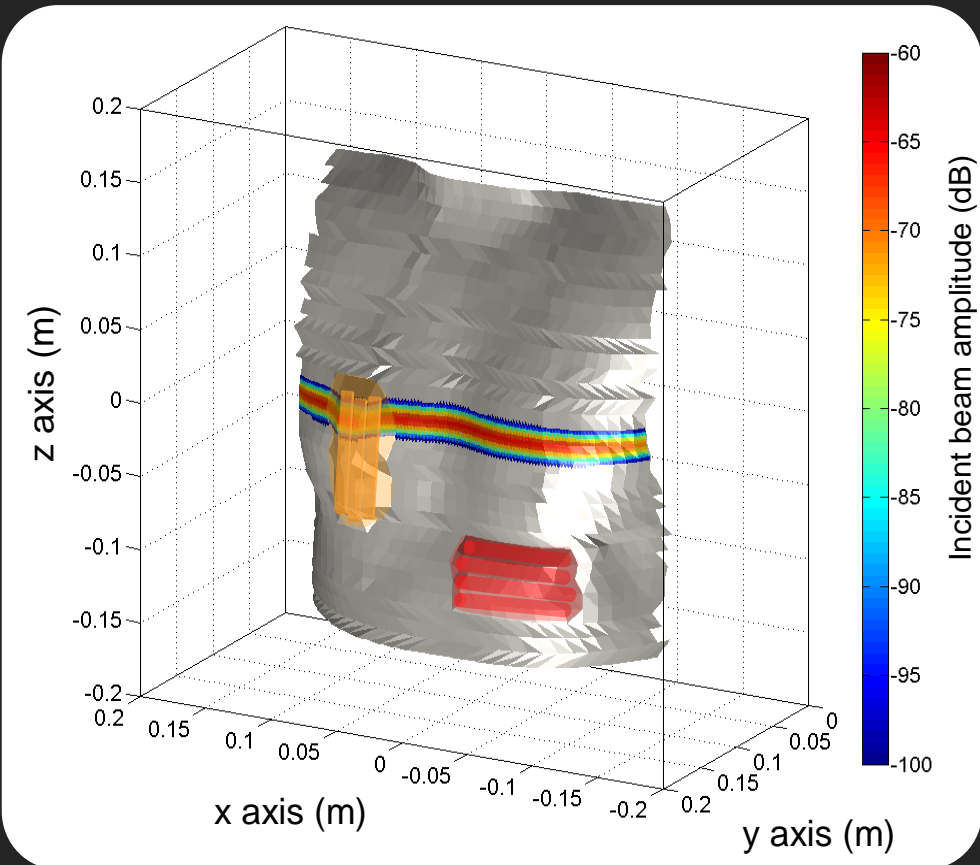
Projected Focus



Specific 3D Human Modeling Geometry



Resulting computed illumination on torso with foreign objects

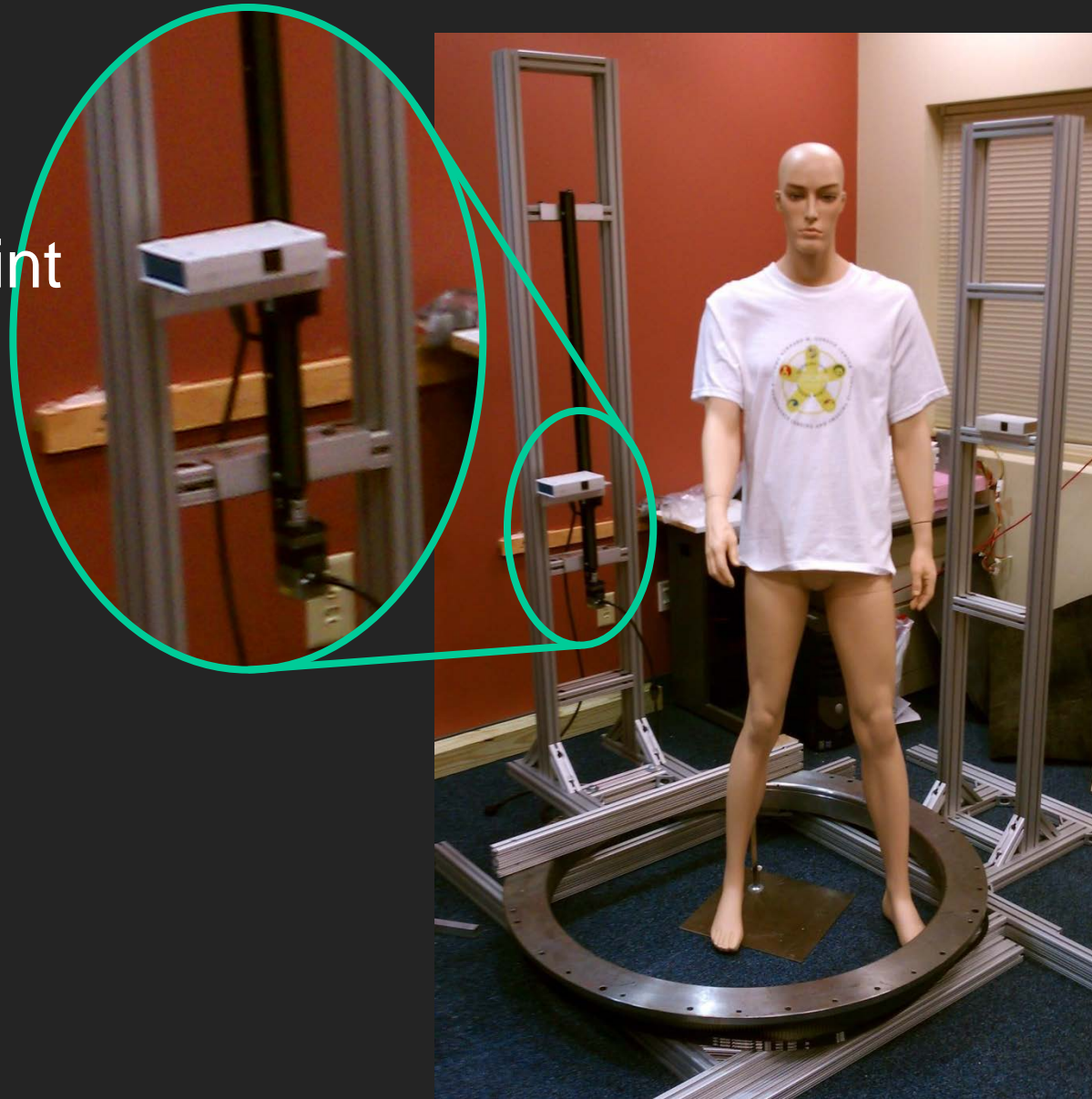




Rotating / Variable Height Cylindrical Scanning Stage and Mounted 60 GHz Radar

- Independent multistatic experimentation
- Open support: joint x-ray sensor placement

* Circular bearing donated by Neurologica, Inc.





60 GHz Skin and Explosive Simulants

Skin simulant for combined mm-wave / x-ray phantom

- 0.75 cm thick hydrogel layer has very similar water content as skin
- Much better dielectric match than metalized mannequin
- Fully absorbs mm-waves to conceals internal metal parts
- Same transparency to x-ray backscatter as skin
- Workable, smooth, safe, cheap



60 GHz Skin and Explosive Simulants

Explosive simulant for mm-waves

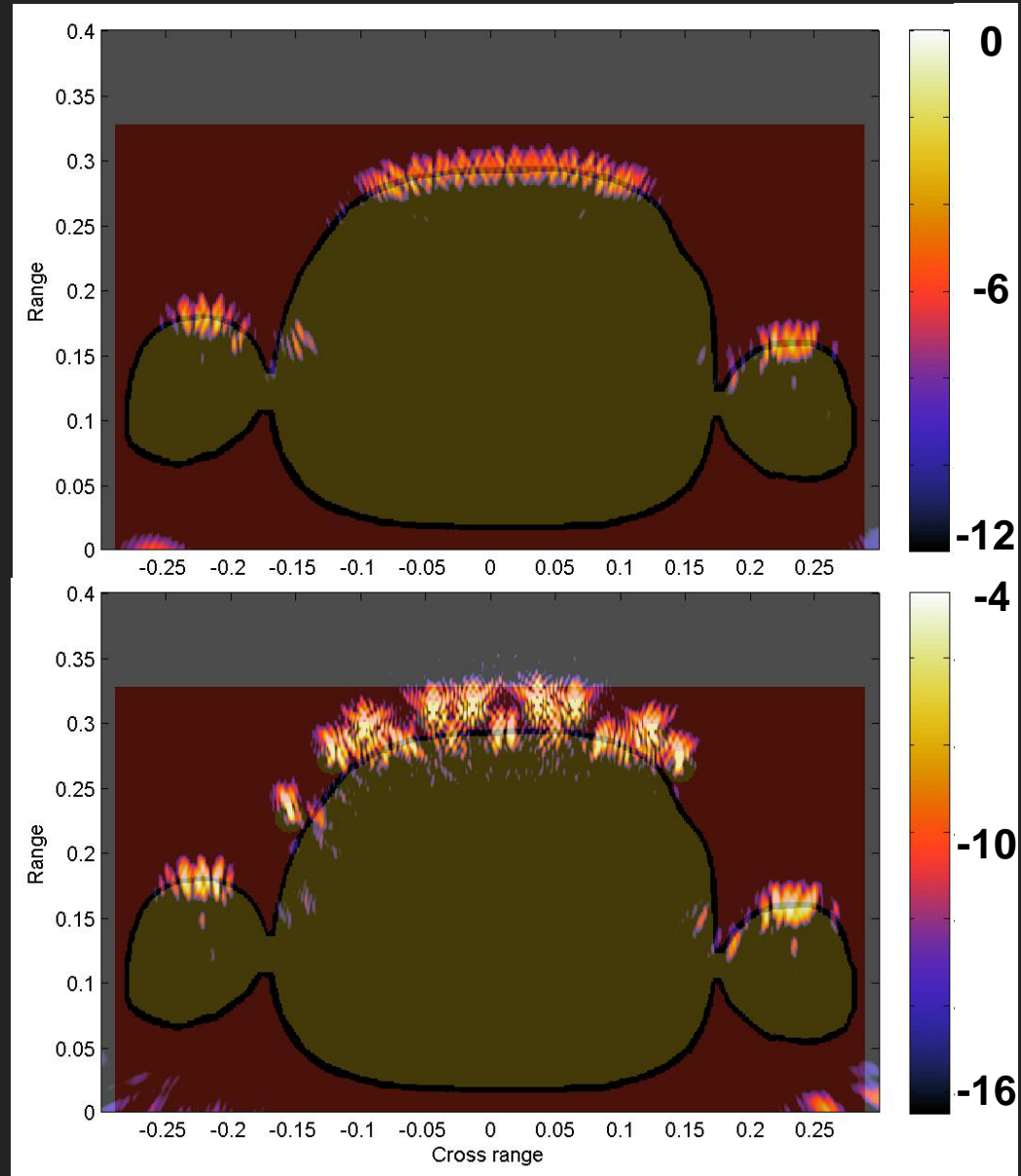
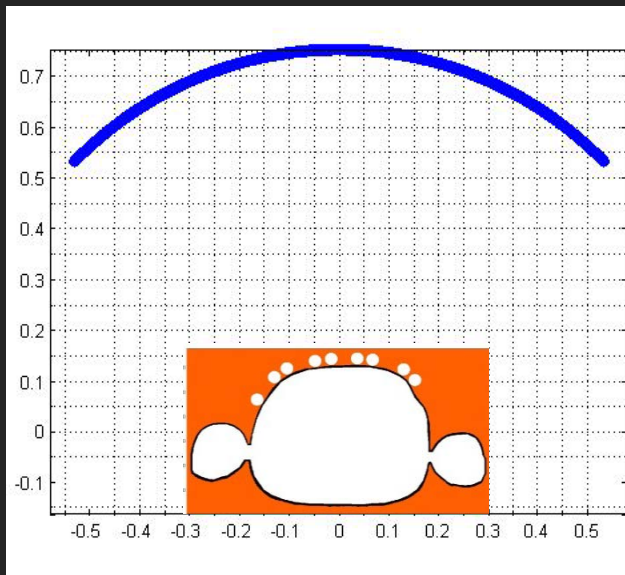
- Same electrical characteristics as TNT/RDX/PETN
- Paraffin and TiO_2
- Workable, stable, safe, cheap





Slice Reconstruction of Torso with and without metal pipe bomb simulants

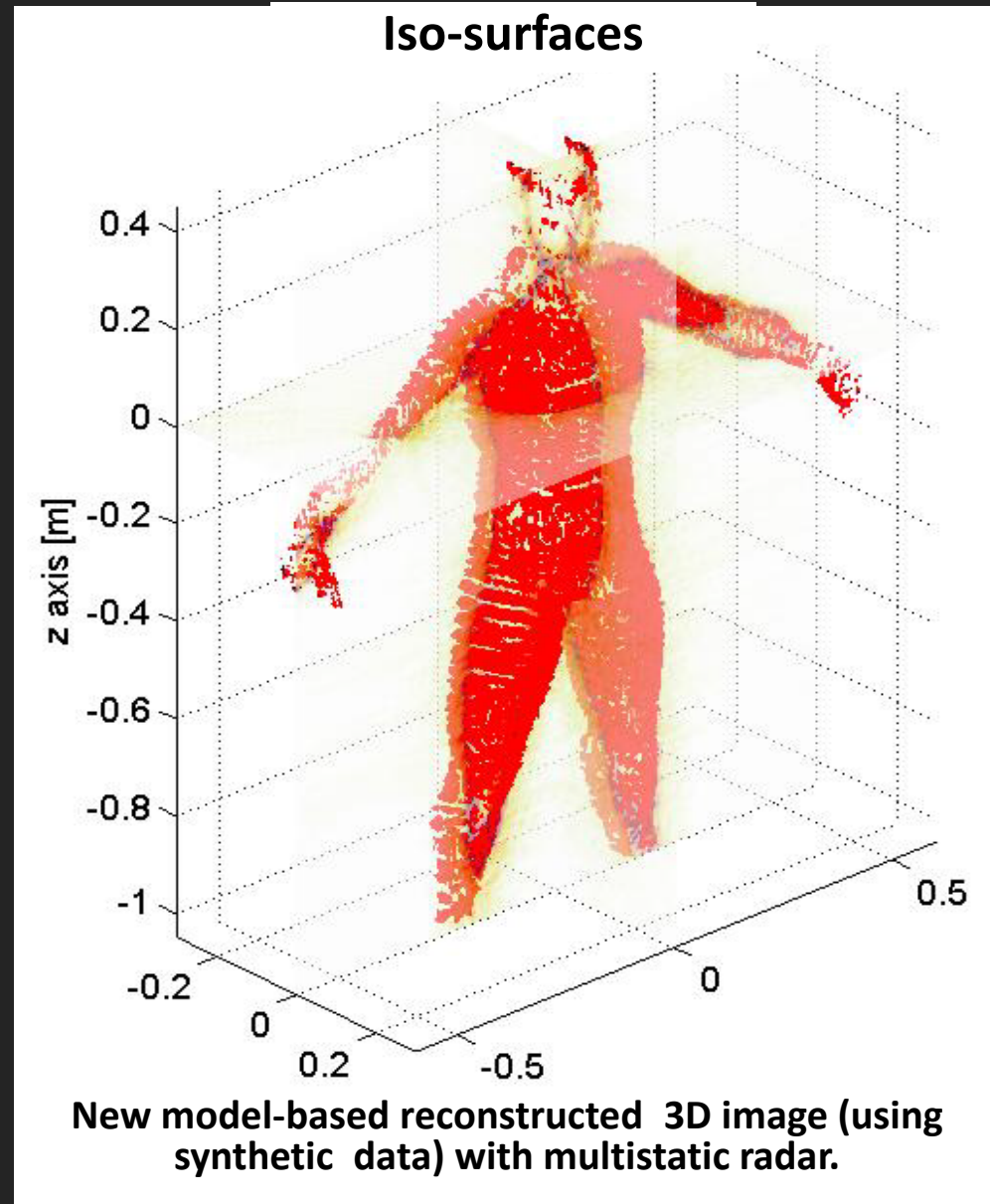
- 2D Multistatic imaging
- Shows smooth innocent body contour
- No dihedral artifacts.





Stacked Slice 3D Reconstruction

- Fast multistatic model-based imaging
- Shows smooth innocent body surface curvature
- High resolution
- No artifacts / dropouts

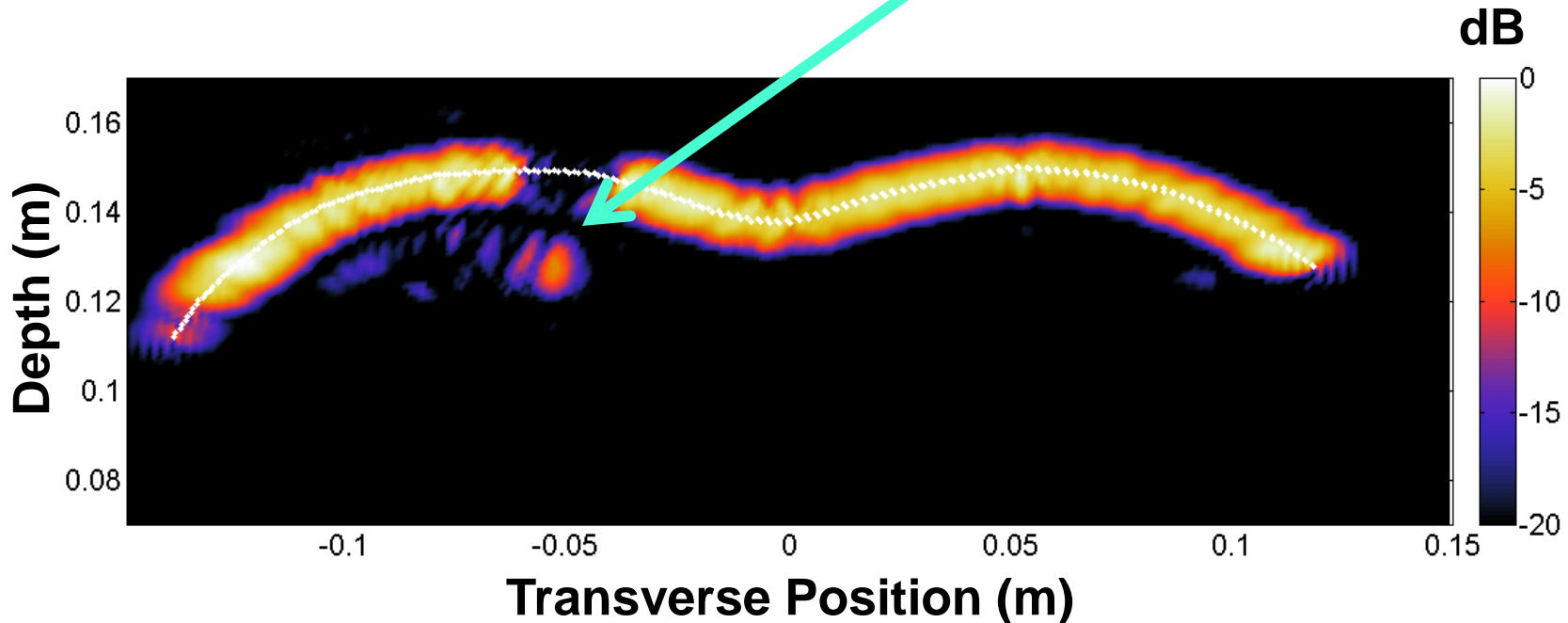




3D Reconstruction of Synthetic Data – Inverse Fast Multipole Method / SAR

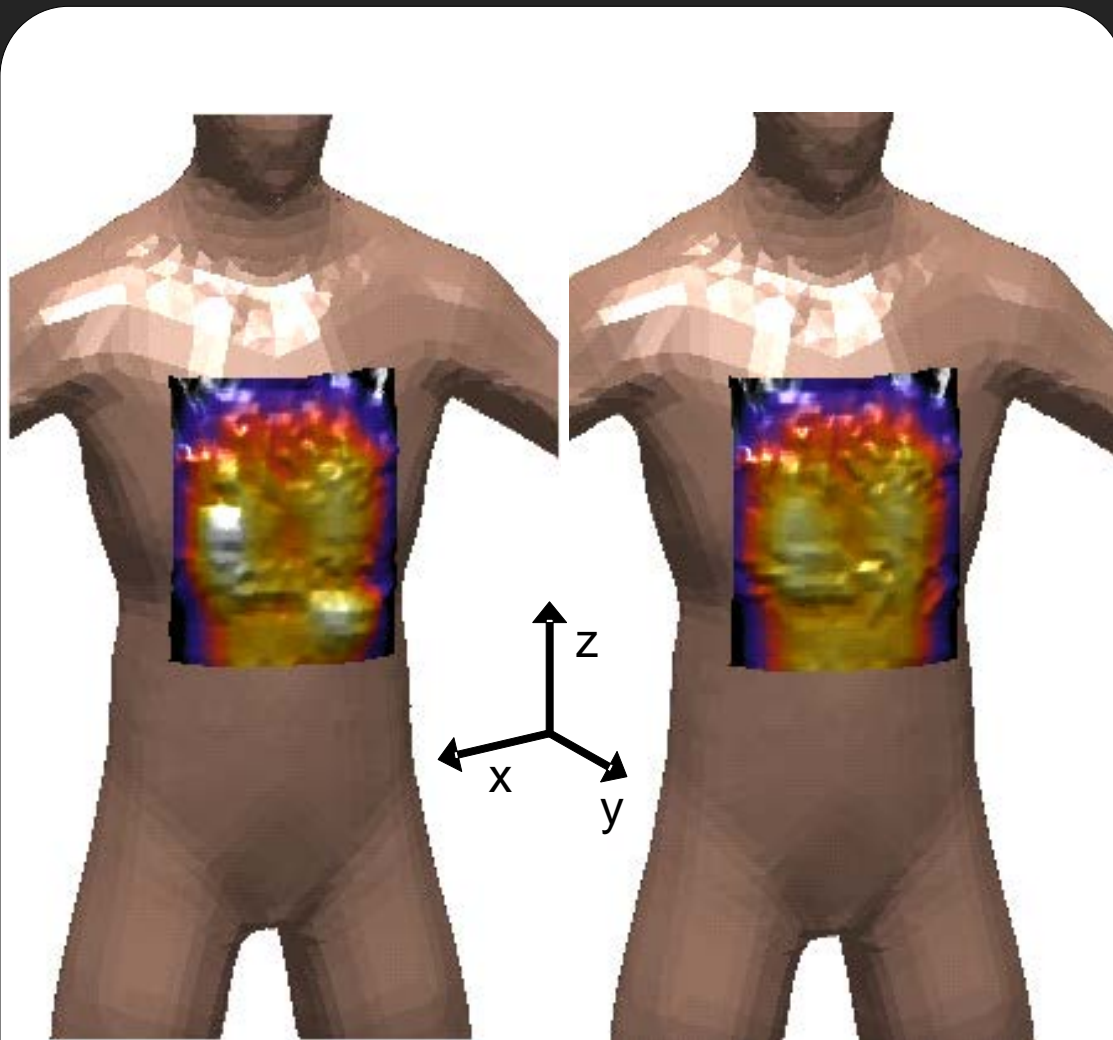
- Adjust phase from radar antenna to each point in image space.
- Combine sources into a much smaller number of multipole sources
- High correlation indicates scattering center
- Display scattering centers as bright points – reflective surfaces

3 cm TNT rod ($\epsilon' = 3$)
on skin gives
anomalous response
within torso

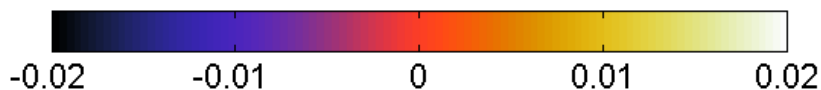




Iterative Field Method (IFM) used for High Resolution Surface Imaging



Surface difference (m) with respect to $y = 15$ cm plane

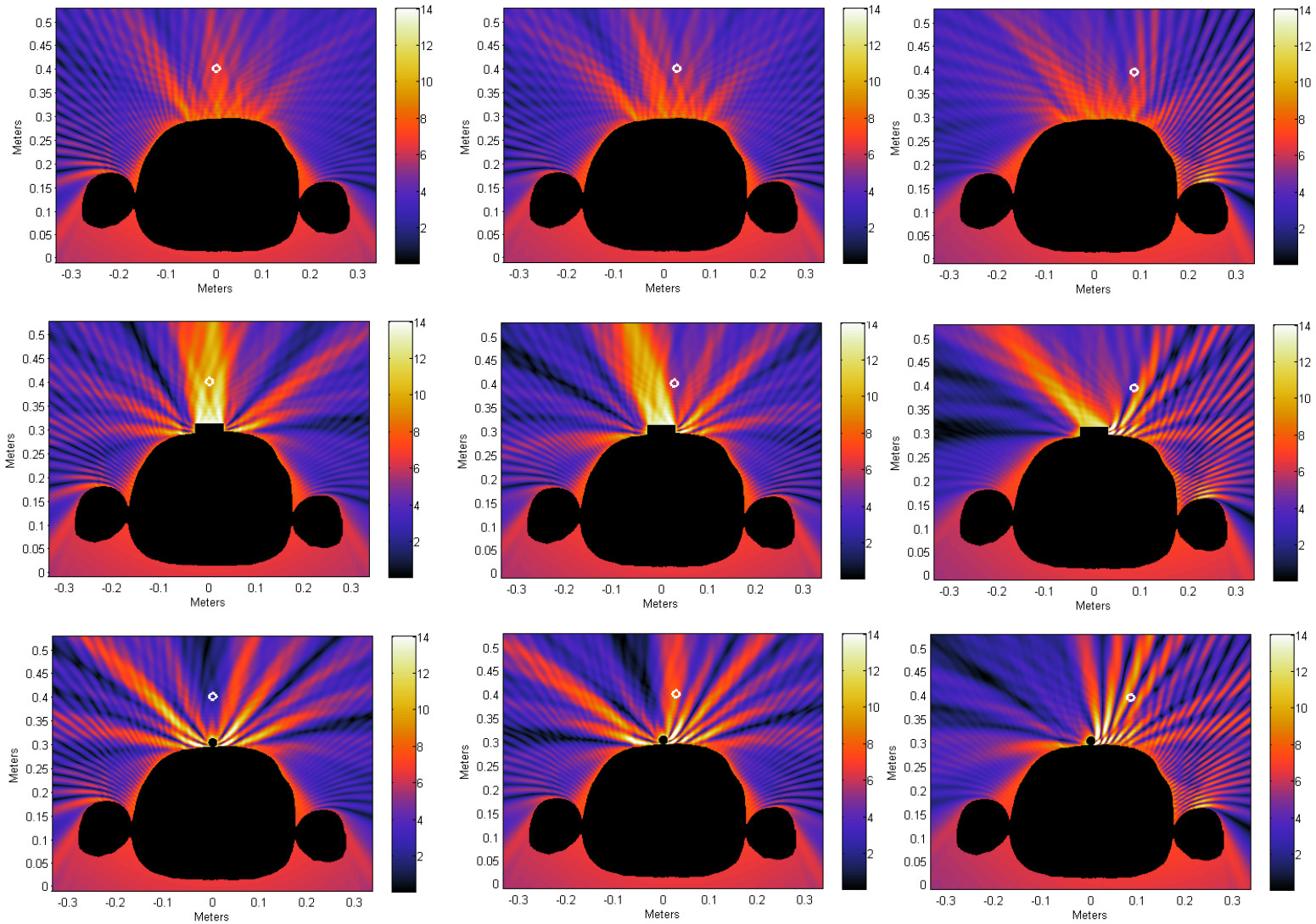


- Given estimate of range, estimate faceted surface
- Perturb surface facet positions based on linearized phase
- Iterate until convergence
- Surface reconstruction accuracy $\lambda/4 \sim 1$ mm





Finite Difference Frequency Domain Computational Model – Wand Scattered Field





Summary of Computational EM Models

Forward Models

- Finite difference Frequency Domain (FDFD) – 2D and 3D full wave with polarization: metal / dielectric
- Physical Optics (PO) – 2D and 3D surface scattering: metal
- Modified Equivalent Current Approximation (MECA): PO for dielectric
- Method of Moments (MoM) – 3D surface scattering: metal / dielectric

Inverse Models

- Synthetic Aperture Radar processing (SAR) – Generalized, non-FFT based volume inversion
- Inverse fast multi-pole method (IFMM) – SAR accelerator
- Iterative Field Method (IFM) – Precise surface determination using center frequency

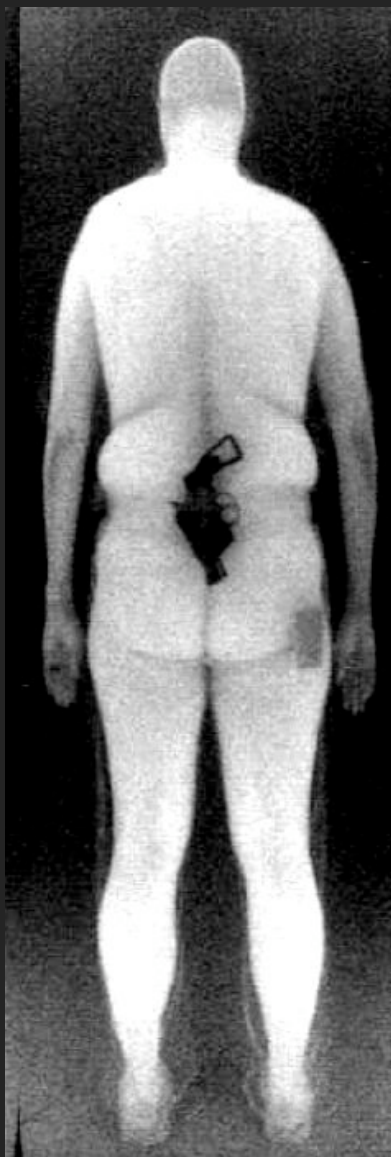


Fusion Example – X-Ray Backscatter with mm-wave

- **XBS and mm-wave are NOT orthogonal**
 - Both detect shape/size
 - Both sense material contrast relative to skin
 - Neither (appreciably) penetrates skin
- **Both require sensor head movement**
- **XBS advantages**
 - High resolution (wires, beads)
 - Fast
- **Mm-wave advantages**
 - Depth information (3D shape, thin layers)
 - Non-ionizing



X-Ray Backscatter Person Scan Images



- Skin is light
- Water is light
- Metal is dark
- Bone is dark
- Space is dark
- Minimal penetration into flesh



Controlled X-Ray Backscatter Experiment



- Plastic lined bucket filled with water
- 4 holes with varying diameters
- Protrusions and Depressions



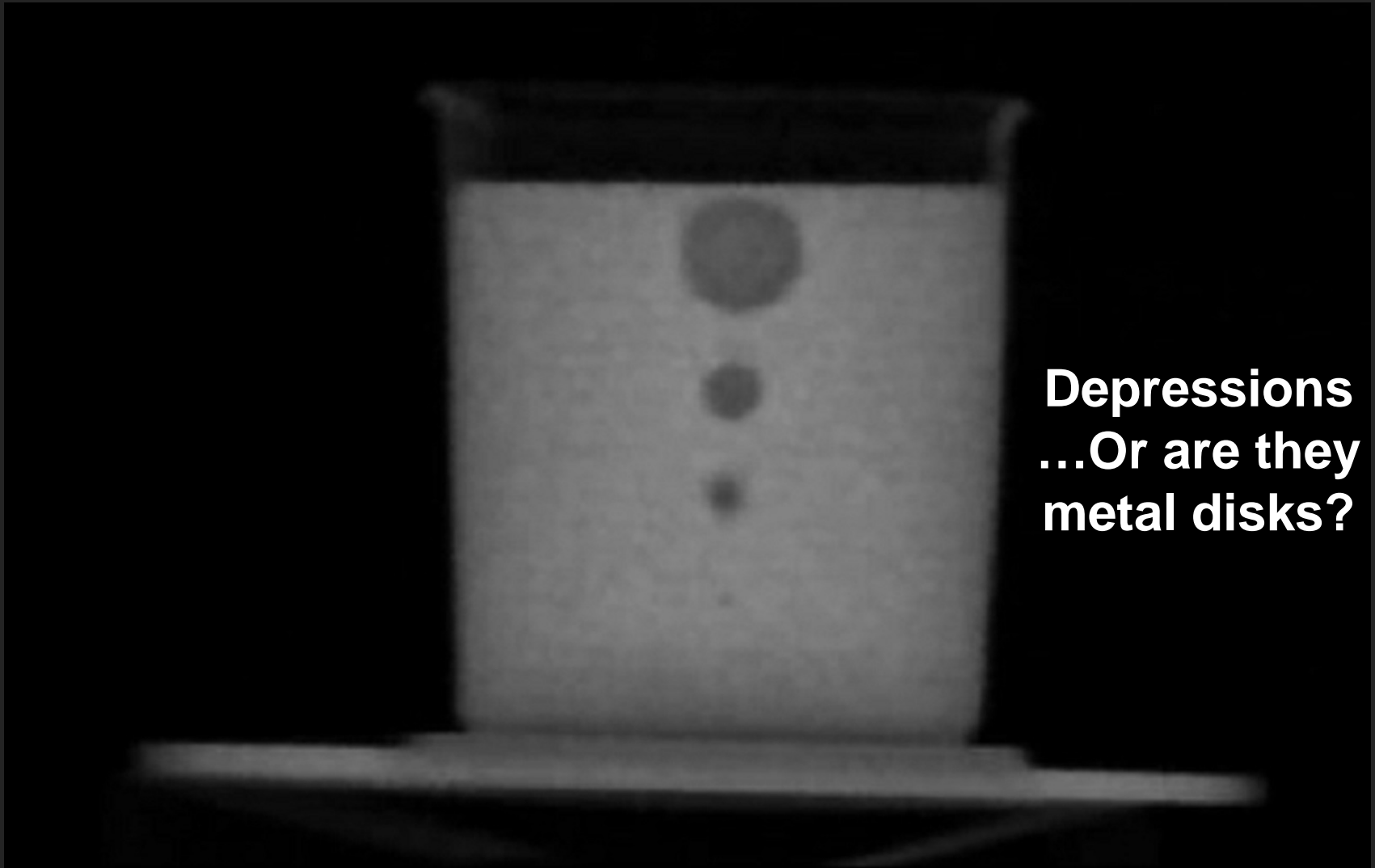
Controlled X-Ray Backscatter Experiment



- Interior view, plastic lined bucket
- 4 holes plugged with x-ray transparent styrofoam



Measured X-Ray Backscatter Image of Depressions in Water Volume



**Depressions
...Or are they
metal disks?**



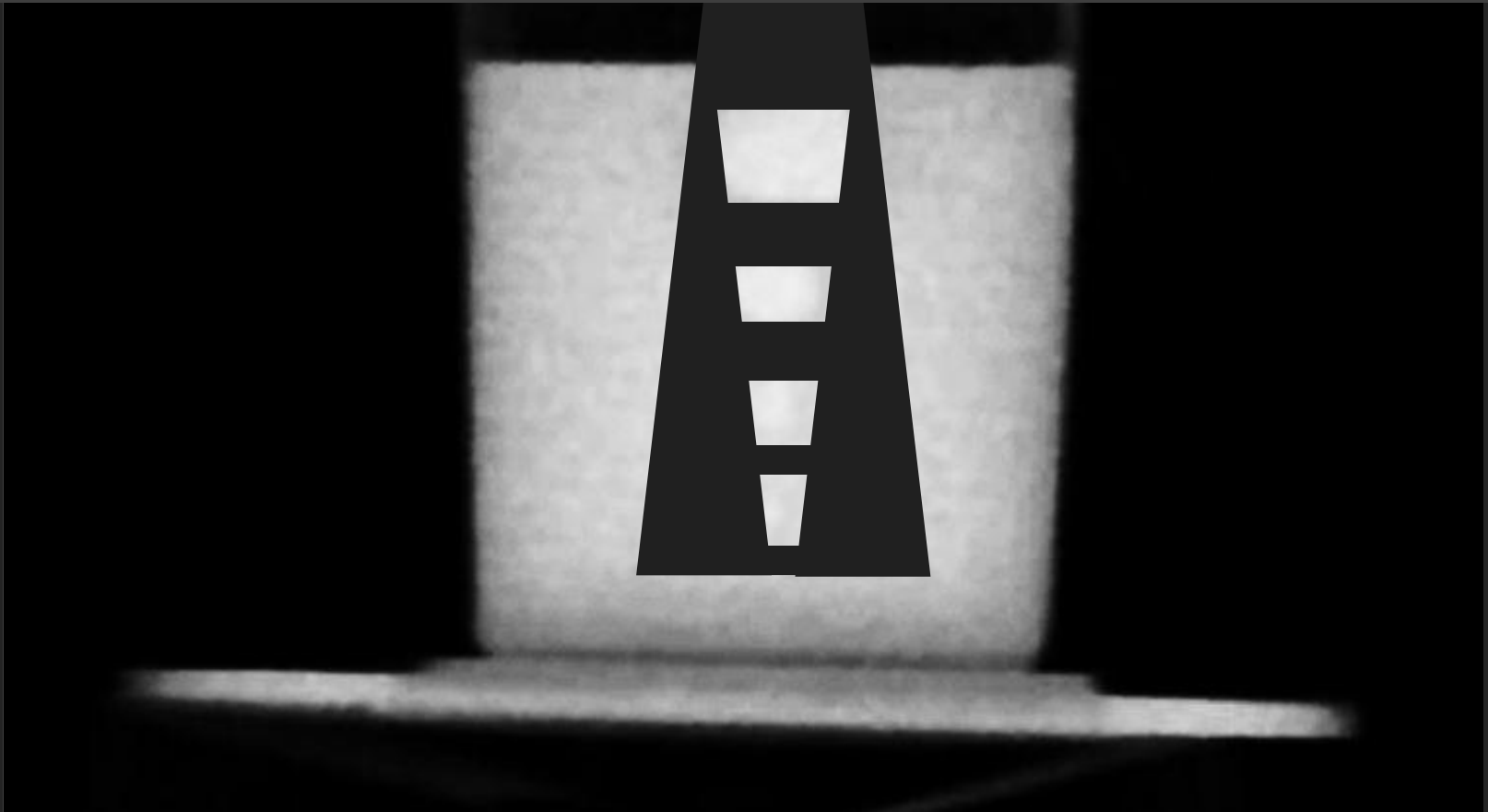
Rotating X-Ray Backscatter Video 1



Measured X-Ray Backscatter Image of Protrusions in Water Volume

- No real depth information
- Edges give appearance of height

Masking edges eliminates appearance of height



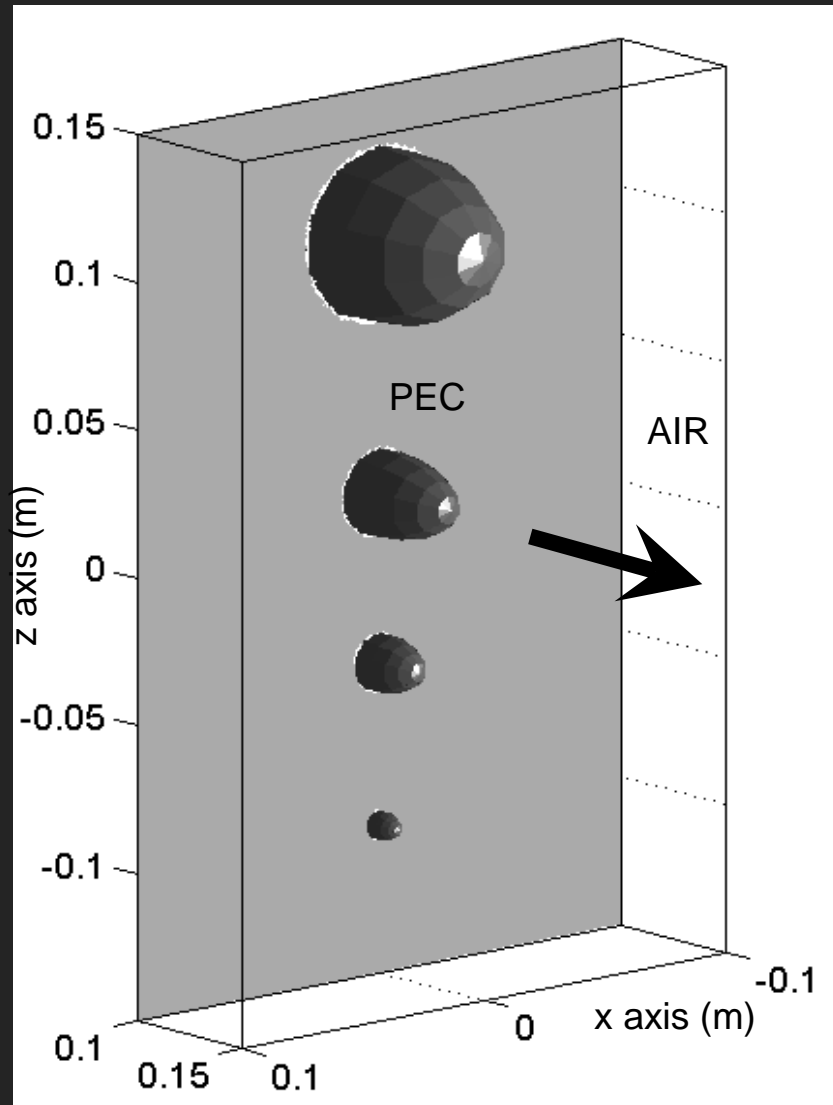


Rotating X-Ray Backscatter Video 2

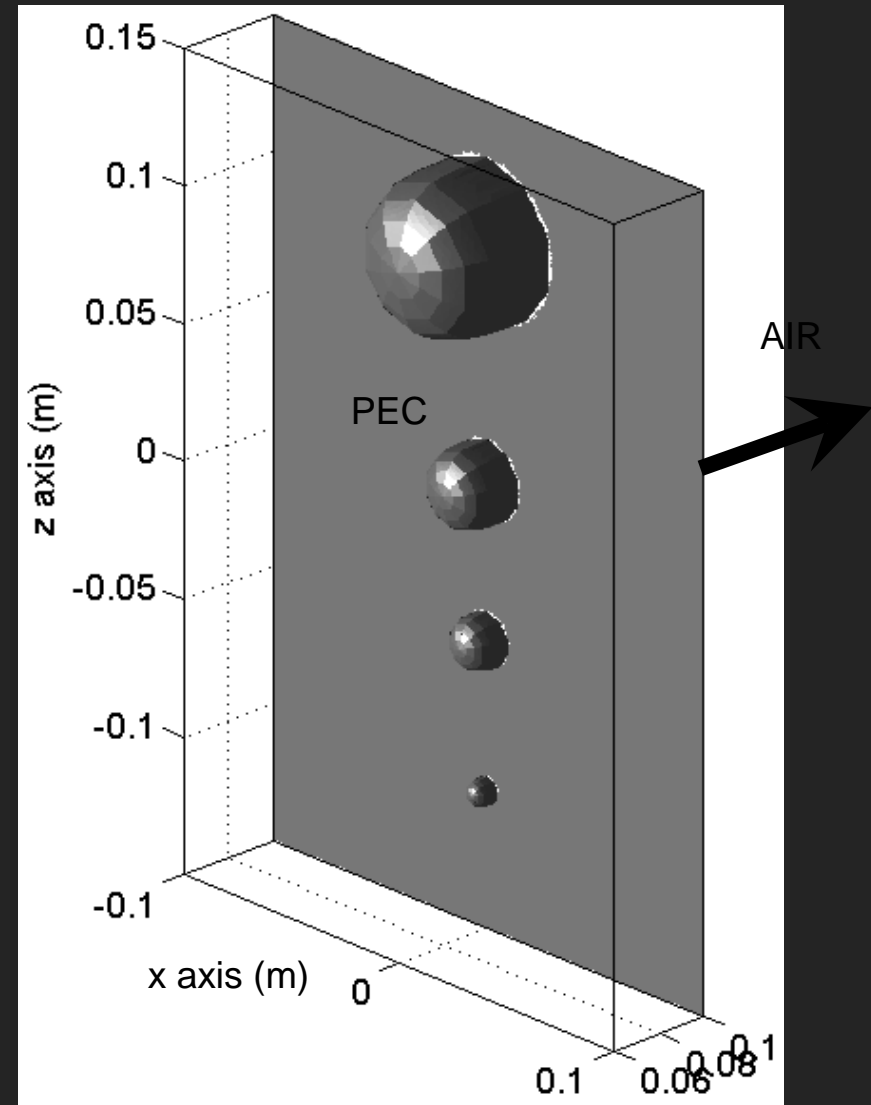


MM-Wave Forward and Inversion Modeling of Hole Series

Protrusions— Modeled geometry

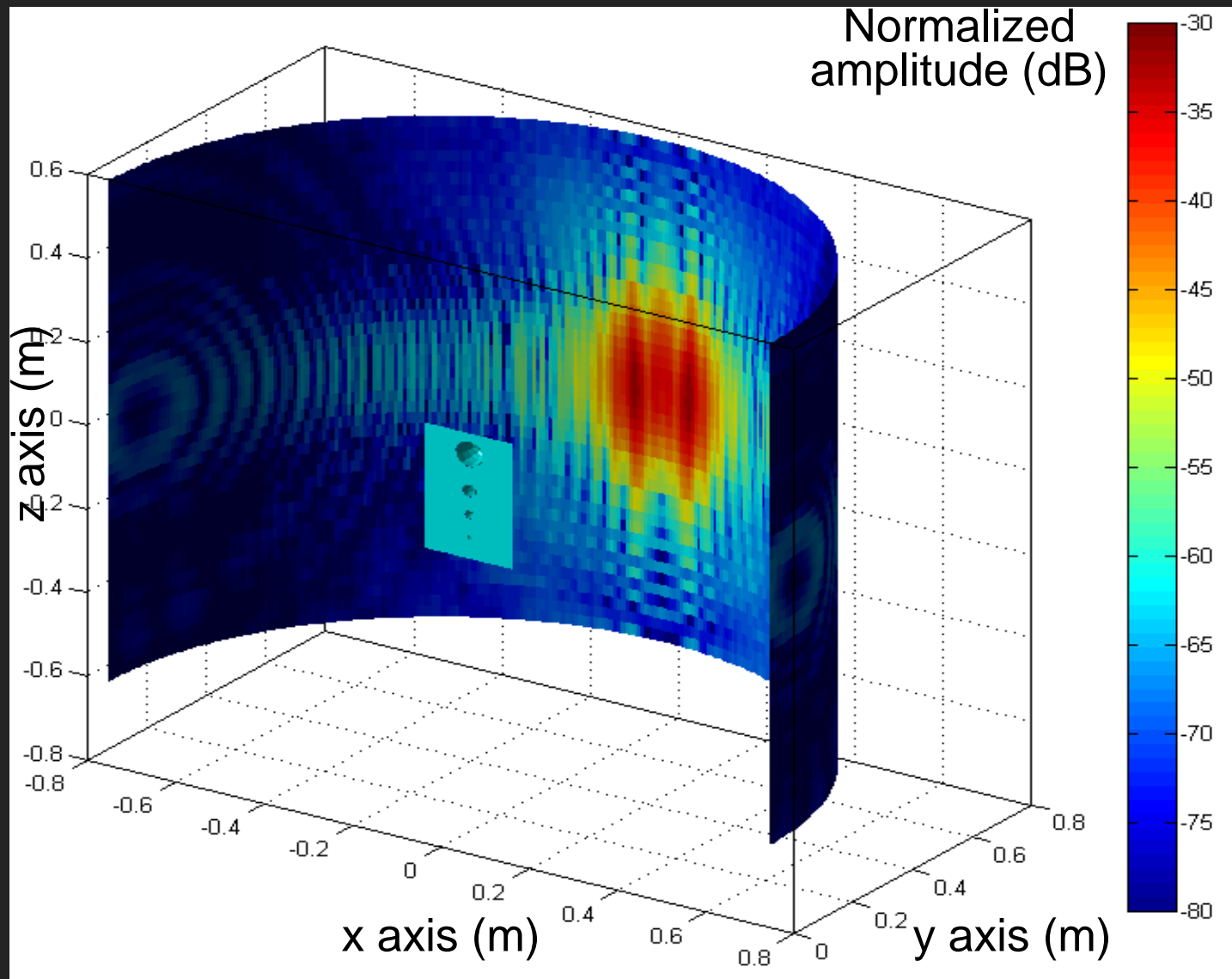


Depressions— Modeled geometry (inside view)





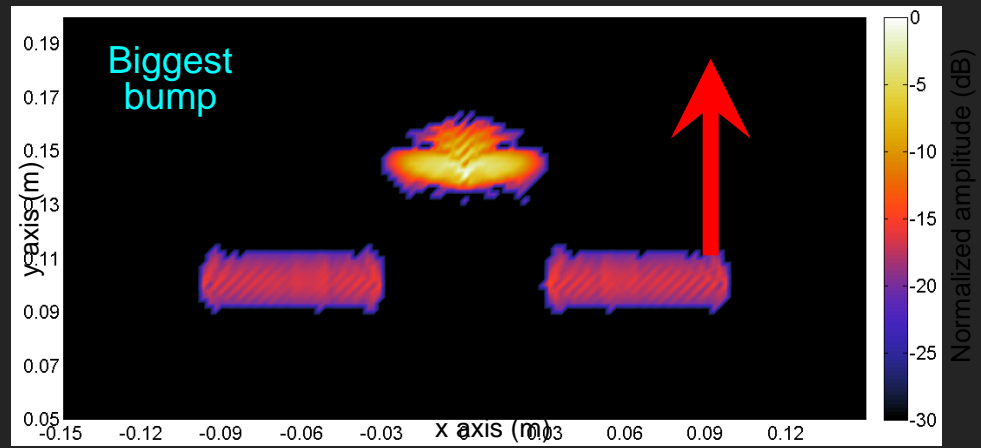
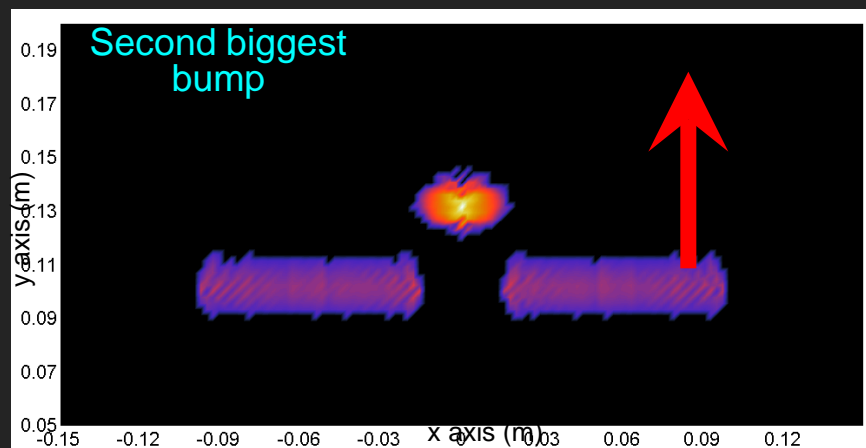
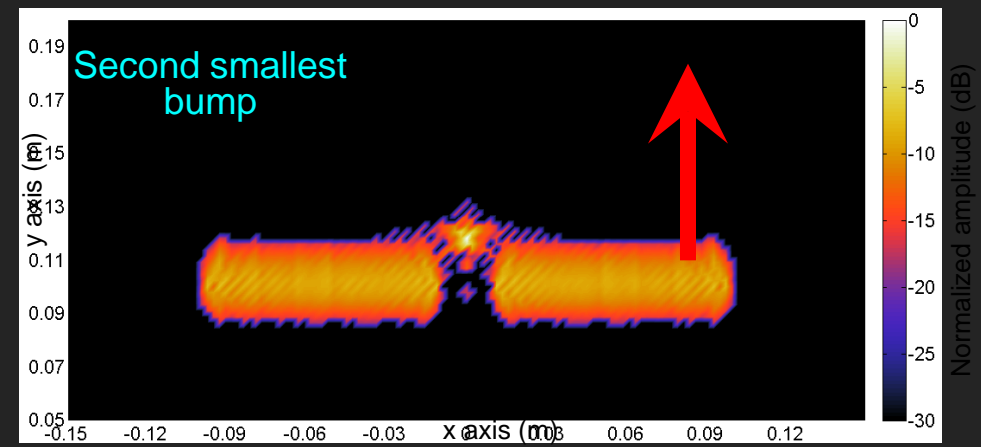
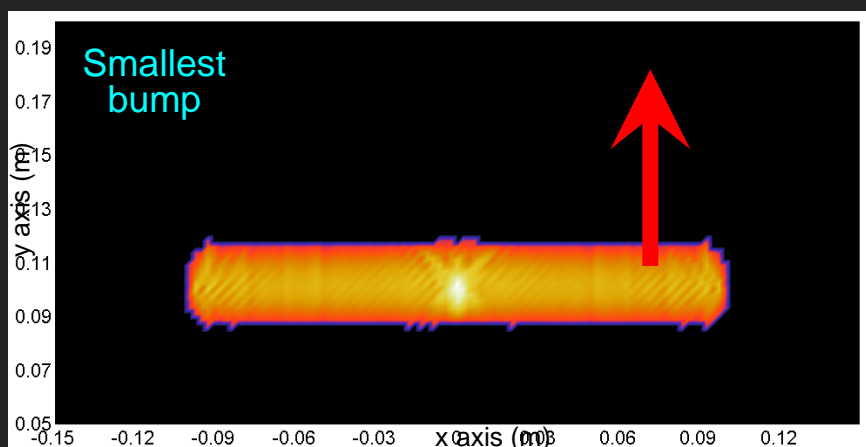
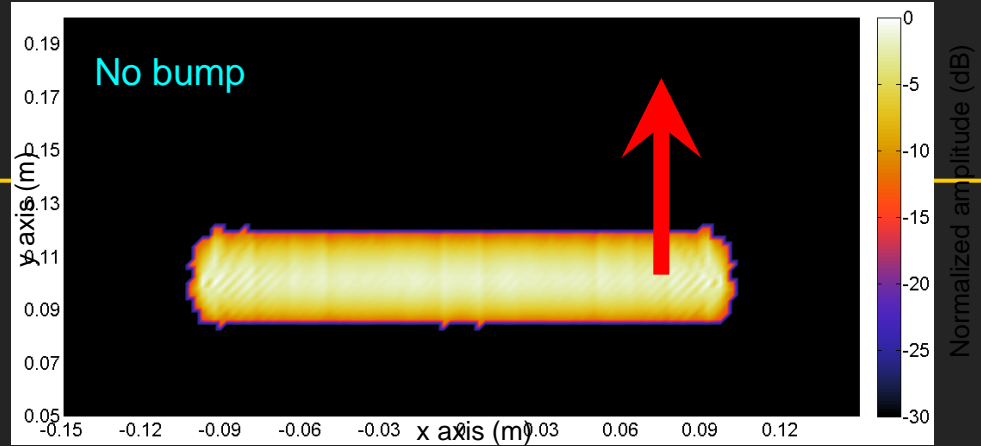
Scattered Field on the Cylindrical Acquisition Surface – Test Item with 4 Protrusions





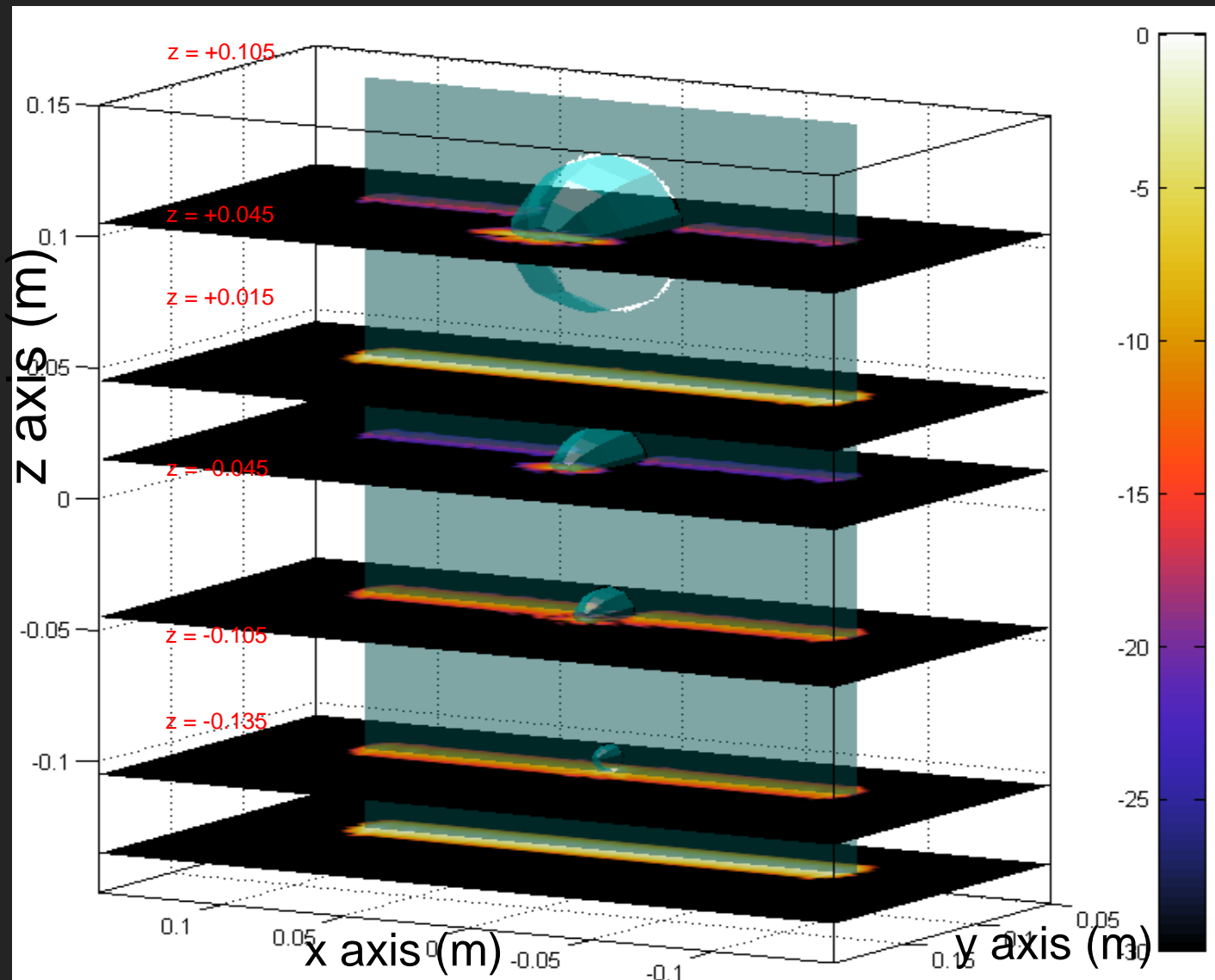
SAR Reconstruction of Protrusions

Range view, showing material closer to detector



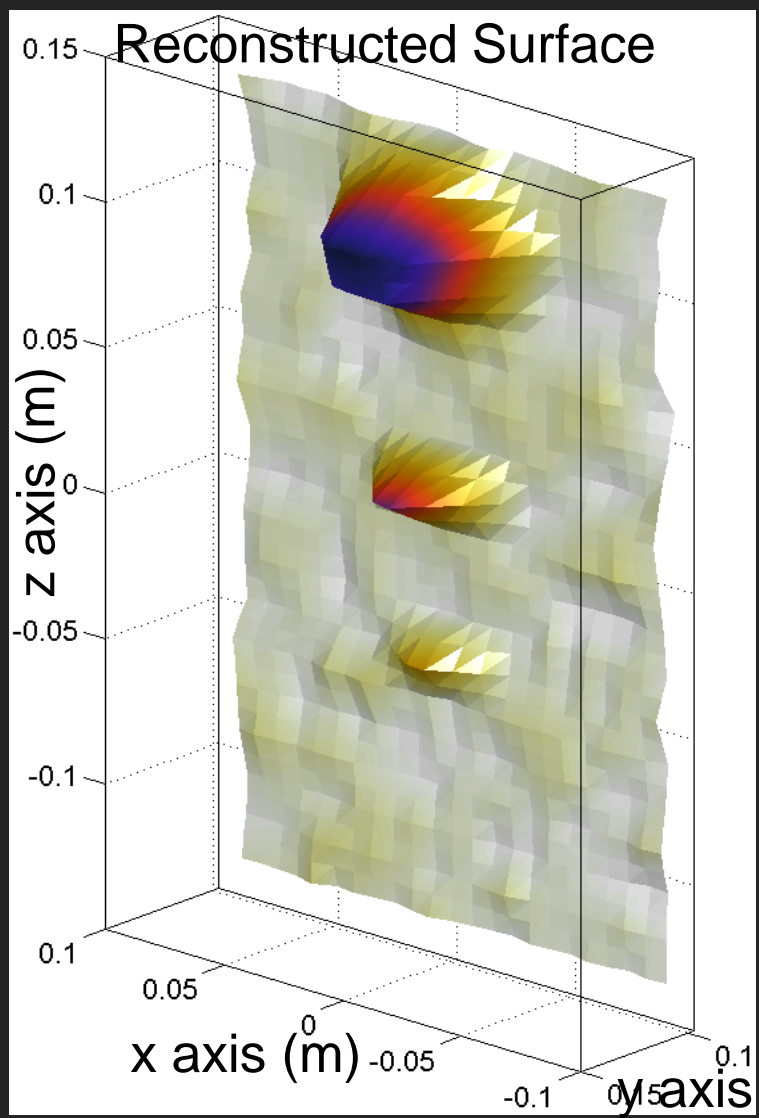
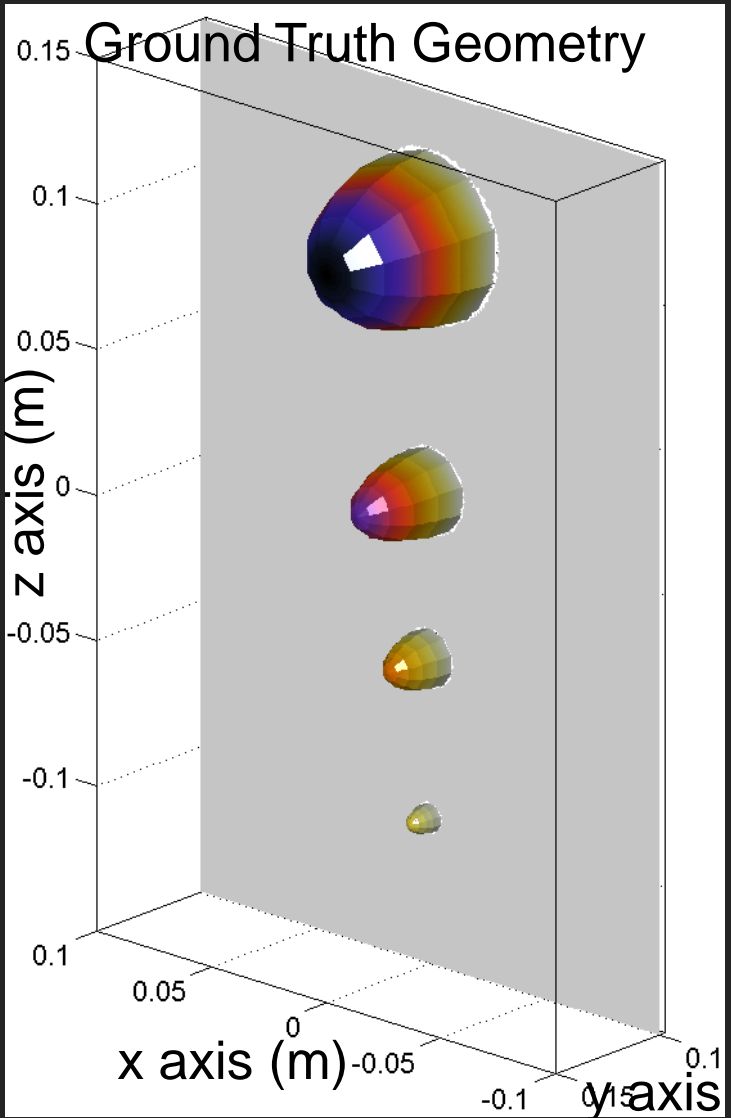


Stacked slices – 4 Protrusions





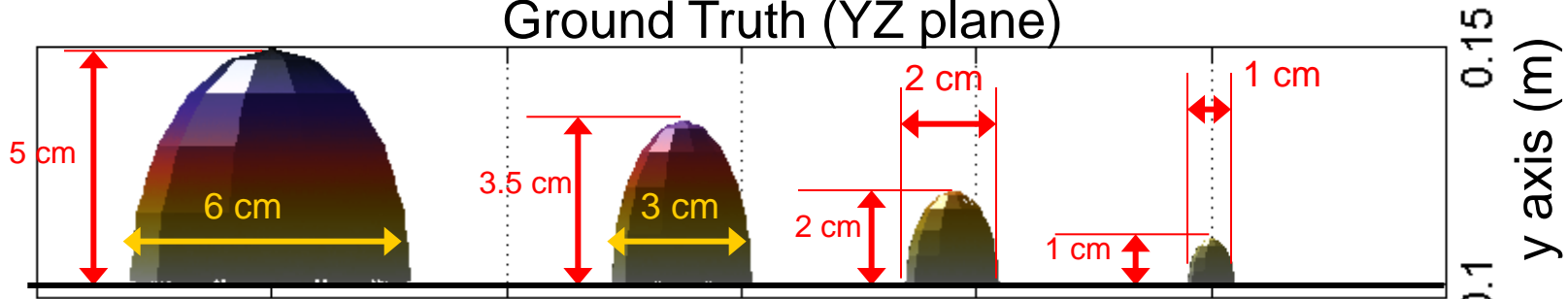
3D Surface Reconstruction: 4 Protrusions of Water from Water Plane



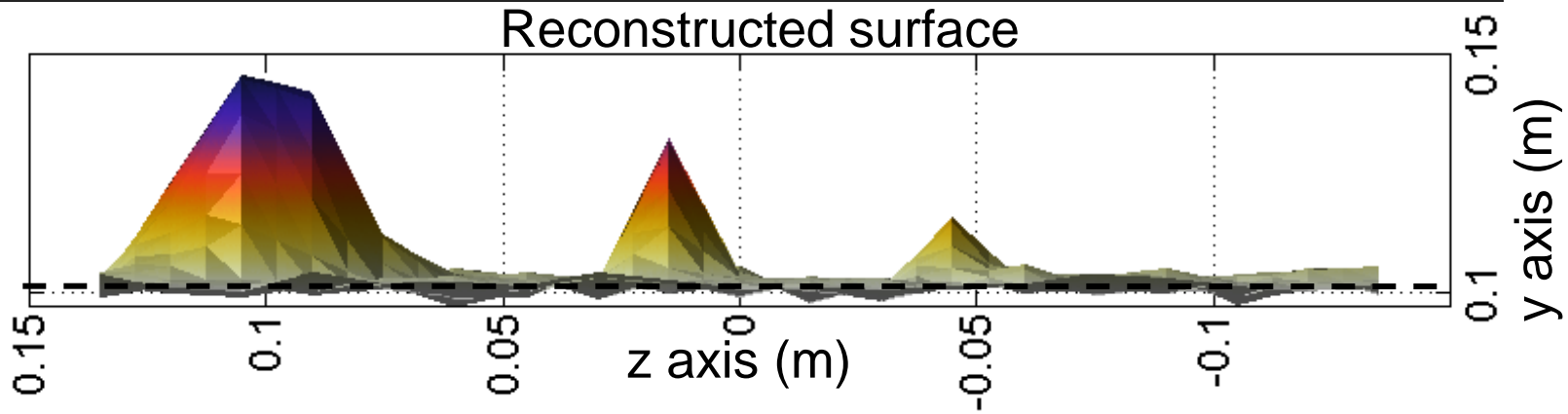


3D Height Reconstruction: 4 Protrusions

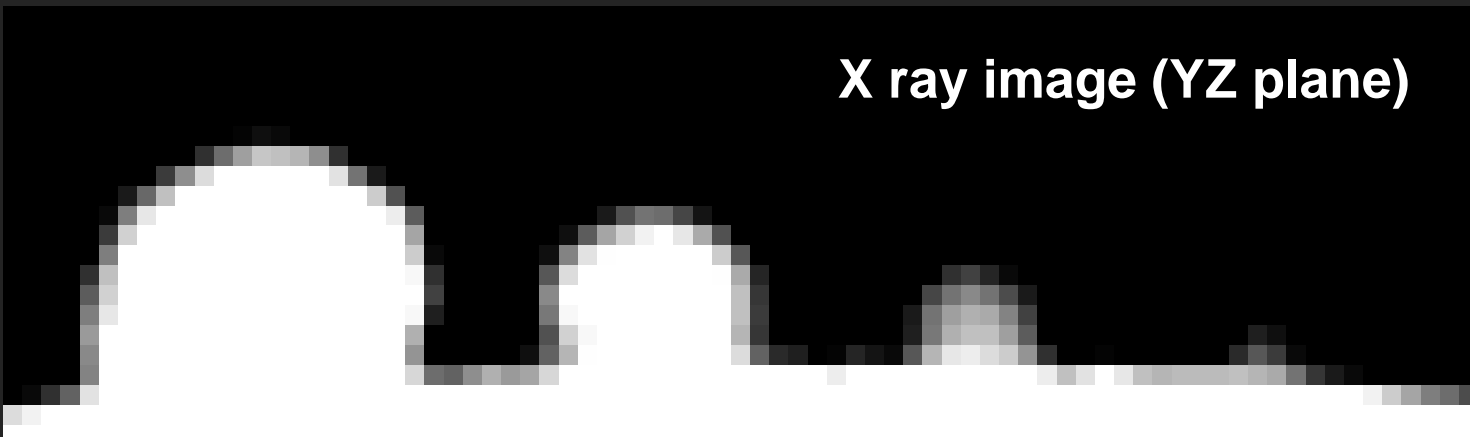
Ground Truth (YZ plane)



Reconstructed surface

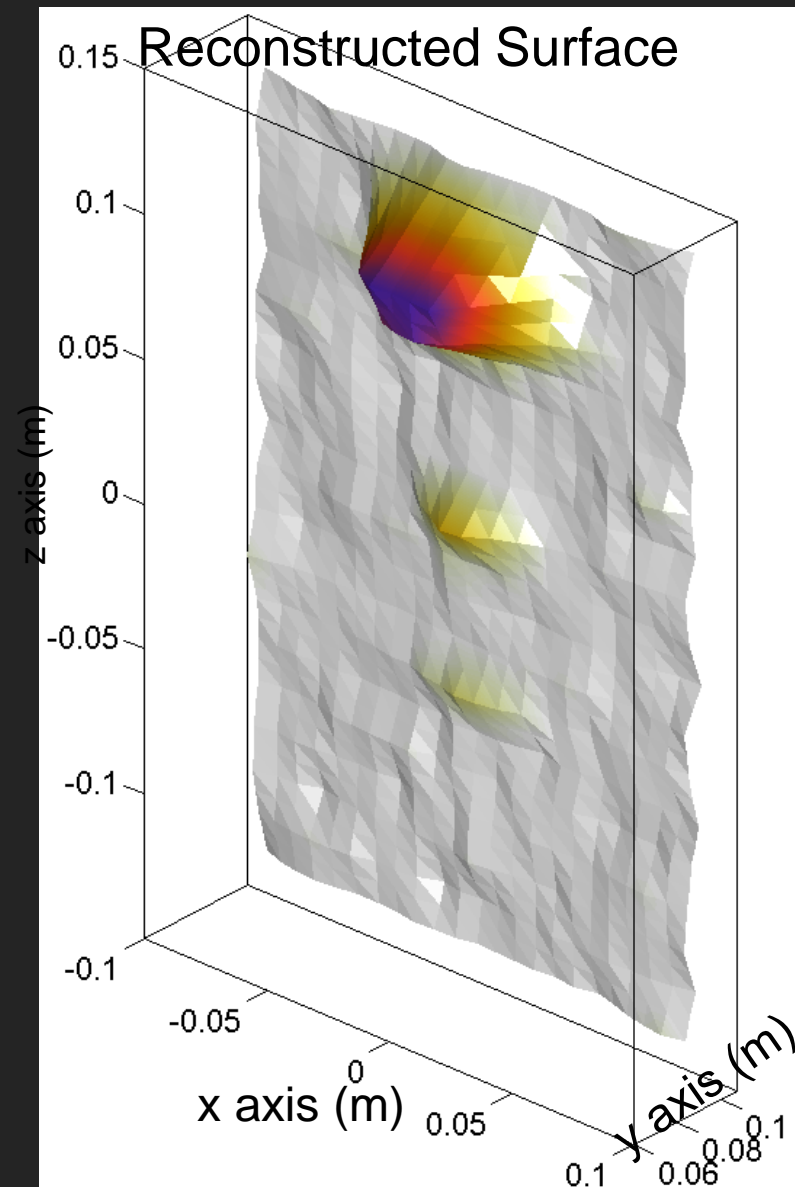
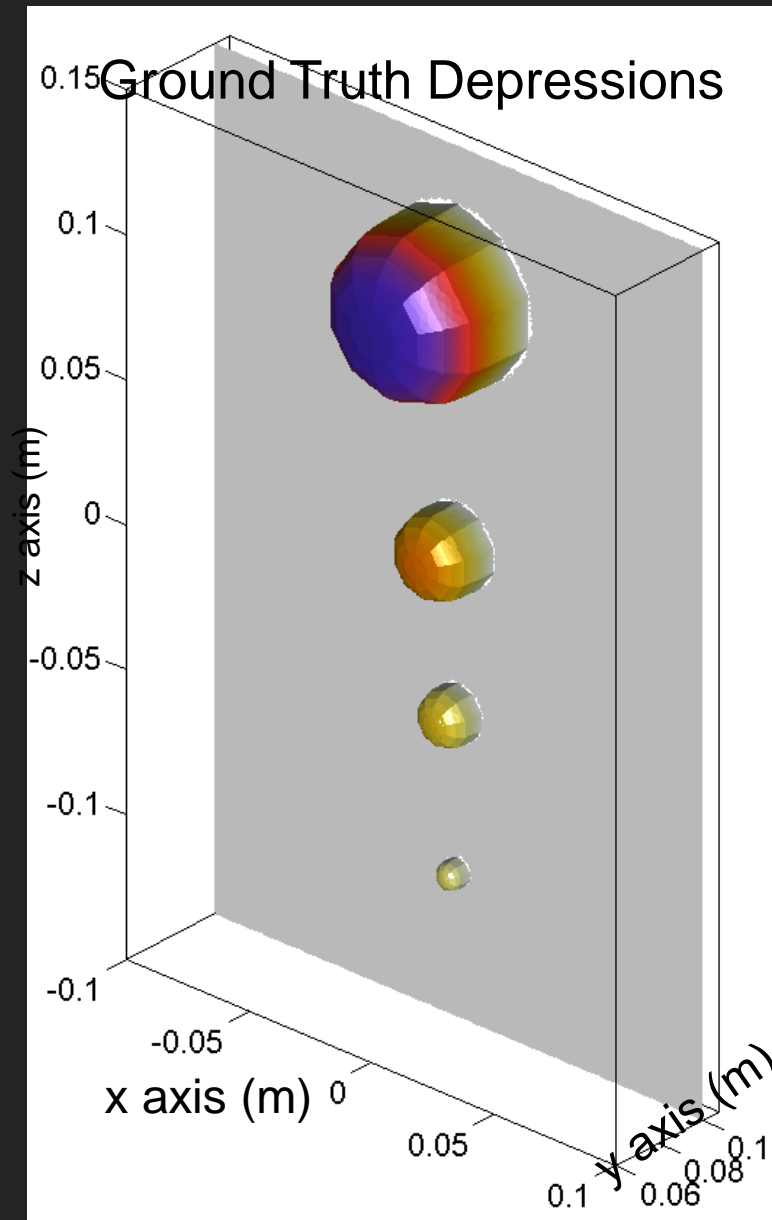


X ray image (YZ plane)





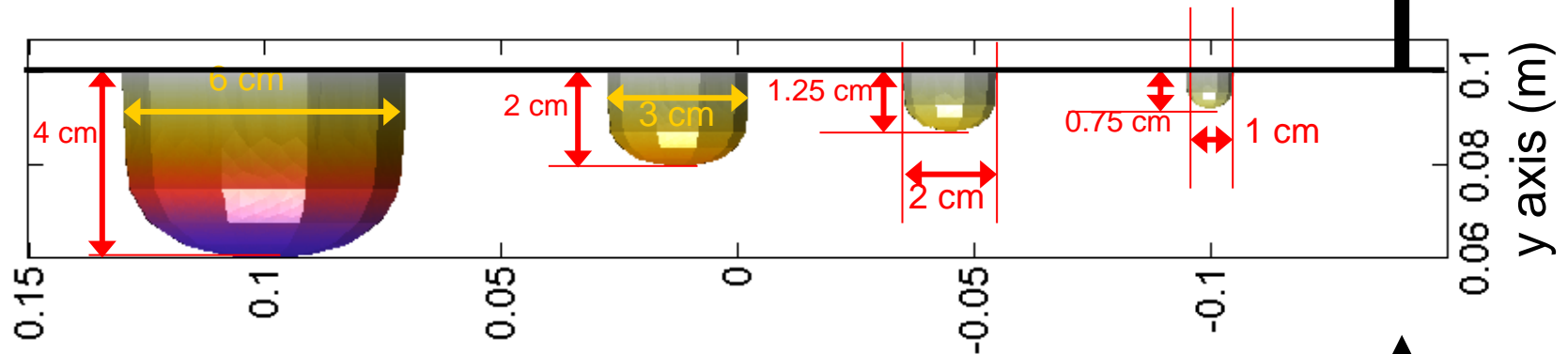
3D Height Reconstruction: 4 Depressions in Water Wall (Inside View)



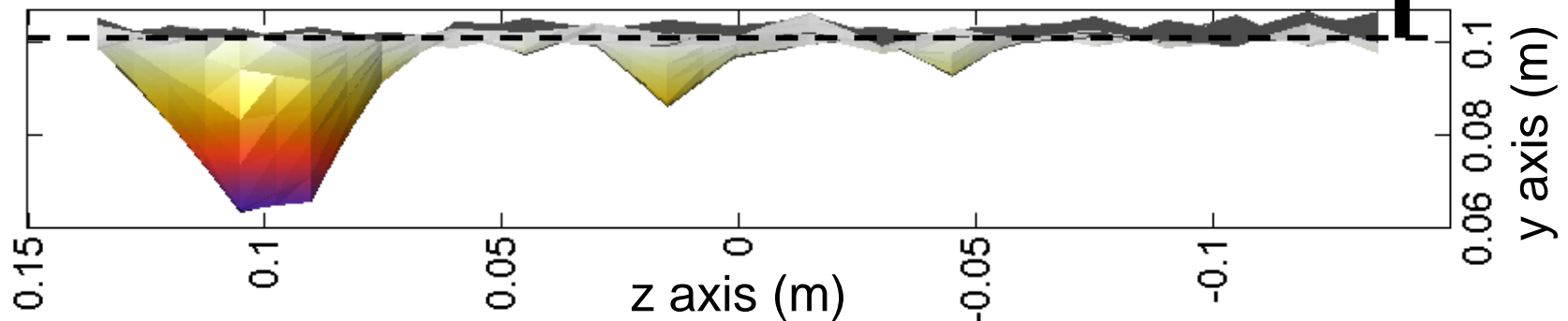


Quantitative comparison of Reconstruction – 4 Depressions

Inner bumps – original geometry (YZ plane)



Retrieved mesh



Note: No X-ray image available for depressions



Intimately Near Detection: Advanced Imaging Technologies (AIT) for Whole Body Imaging

- NEU Testbed: Unbiased academic-oriented testbed for development and evaluation of multi-modal sensors and algorithms for whole body imaging
 - Enable experimentation with new sensing modalities
 - Optimize sensor configurations
 - Optimize scanning modes
 - Explore new algorithm concepts
 - Model based vs. Fourier inversion
 - High resolution fused imaging
 - Automated anomaly detection
 - Develop approaches to information fusion and adaptive multisensor processing



Whole Body Imaging Sensors to Fuse with Mm-Wave

- **X-ray Backscatter**
 - Penetrates all concealing layers
 - Dual energy distinguishes foreign materials
 - Ionizing radiation but very low dosage
- **IR Thermography**
- **NQR**
- **THz**



Nuclear Quadrupole Resonance (NQR)



- Detect local nuclear fields of nuclei with spin > 1 (^{14}N)
- Detect presence of ^{14}N
- Very specific to material ID
- Penetrates throughout body
- Close sensor proximity
- Must be solid phase
- Temperature dependent

<http://www.morphodetection.com/technologies/quadrupole-resonance/>



Passive Thermography

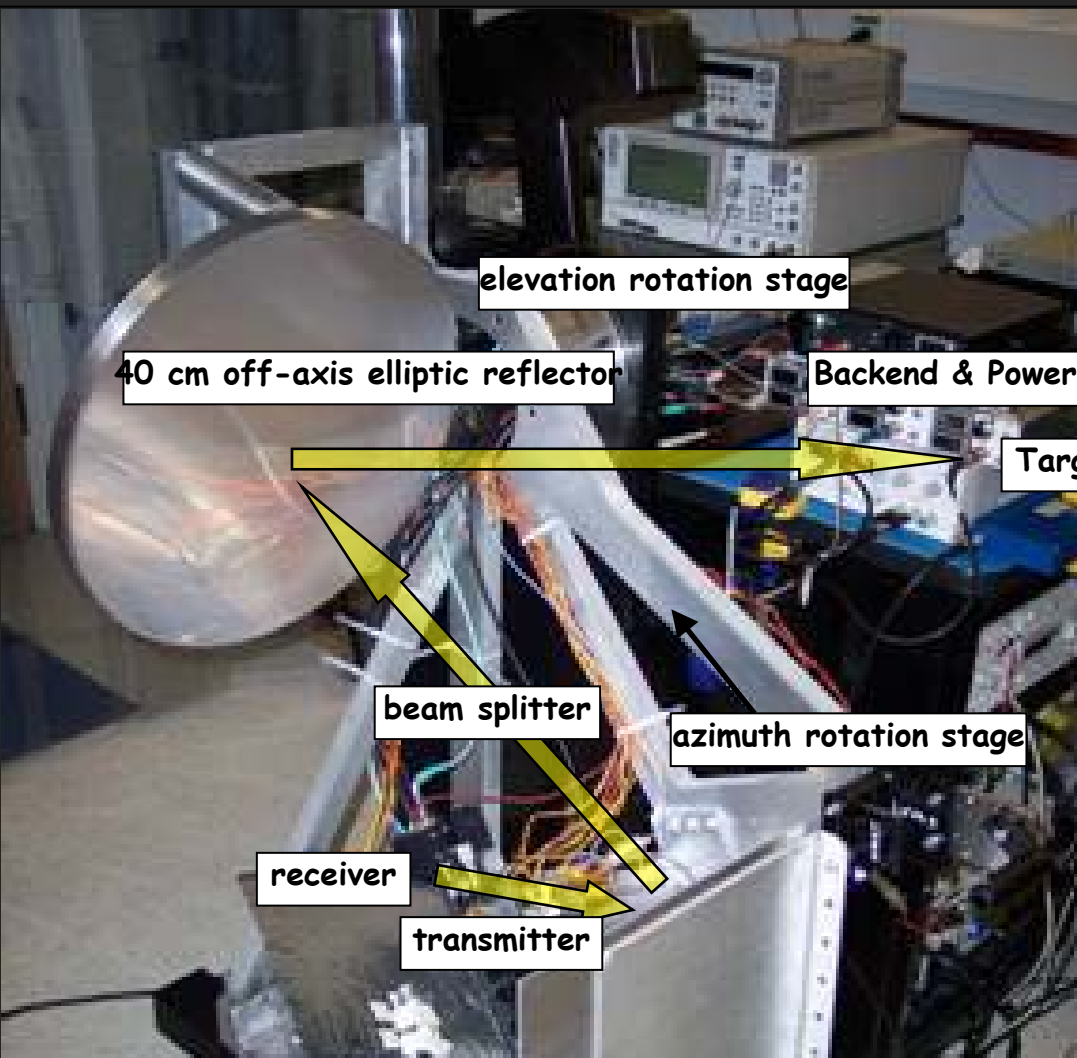


- IR absorption is a function of molecular vibrations and rotations
 - Variable absorption / emittance of IR by materials between body and detector
 - Signal can be enhanced with environmental pre-cooling
-
- Non-ionizing
 - Fast
 - Low-resolution
 - Low penetration through clothing

http://www.nec-avio.co.jp/en/products/ir-thermo/lineup/tvs200is_tvs500is/index.html



THz Imaging



- Passive/active – similar to mm-wave
- Must be scanned mechanically
- Non-ionizing
- High spatial & depth resolution
- Clutter from clothing scatter
- No skin penetration
- Surface texture affects scatter
- Time domain systems can be slow

Siegel, JPL: 654-686 GHz Heterodyne T/R System with 32 GHz Chirp (1cm range bin)



Conclusions

- Established detection regime and parameters
- Described why fusion necessary
- Showed potential challenges and considerations with fusion with mm-waves
- Described the ALERT AIT Testbed (ScanBED)
- Explained how advanced simulation and modeling saves lots of time and money
- Presented a specific example of the potential of fusing x-ray backscatter with mm-wave sensing
- Described the plans for ScanBED multi-modal fusion



People Who Actually Did the Work...

Prof. Jose Martinez
Prof. Yuri Alvarez
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Luis Tirado
Dan Busioc
Melissa Buttimer
Tommy Hayes
Richard Moore