

# Millimeter Wave Imaging using Metamaterial Transceivers

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**CENTER FOR METAMATERIALS  
AND INTEGRATED PLASMONICS**





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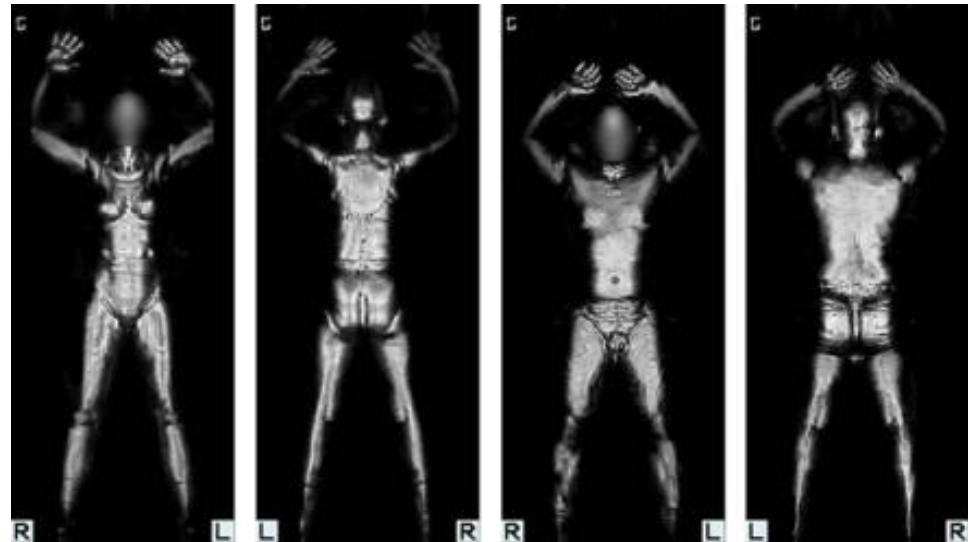
## Teledyne

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This work was supported by the Department of Homeland Security, Science & Technology Directorate (Contract No. HSHQDC-12-C-00049). The published material represents the position of the author(s) and not necessarily that of the DHS.

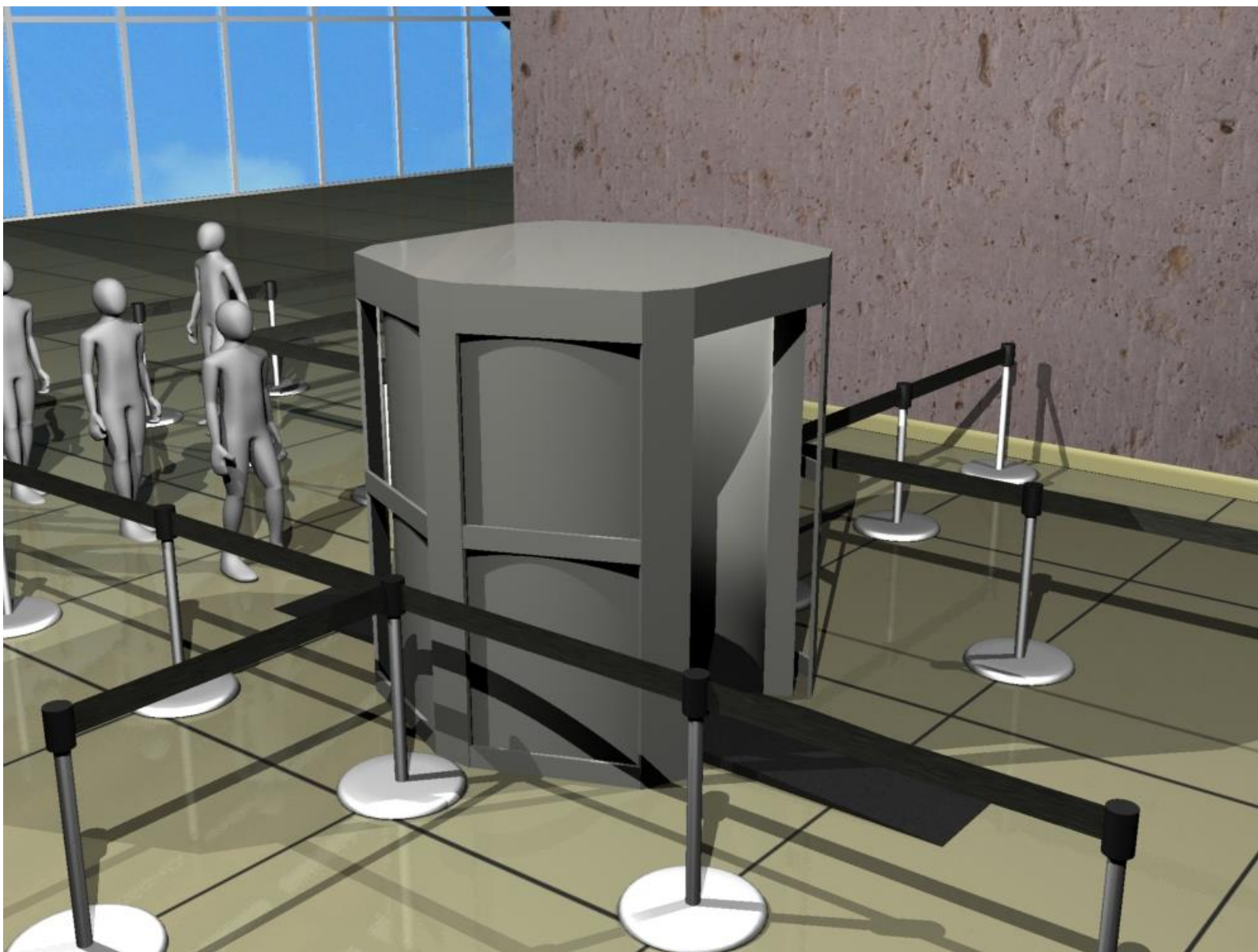


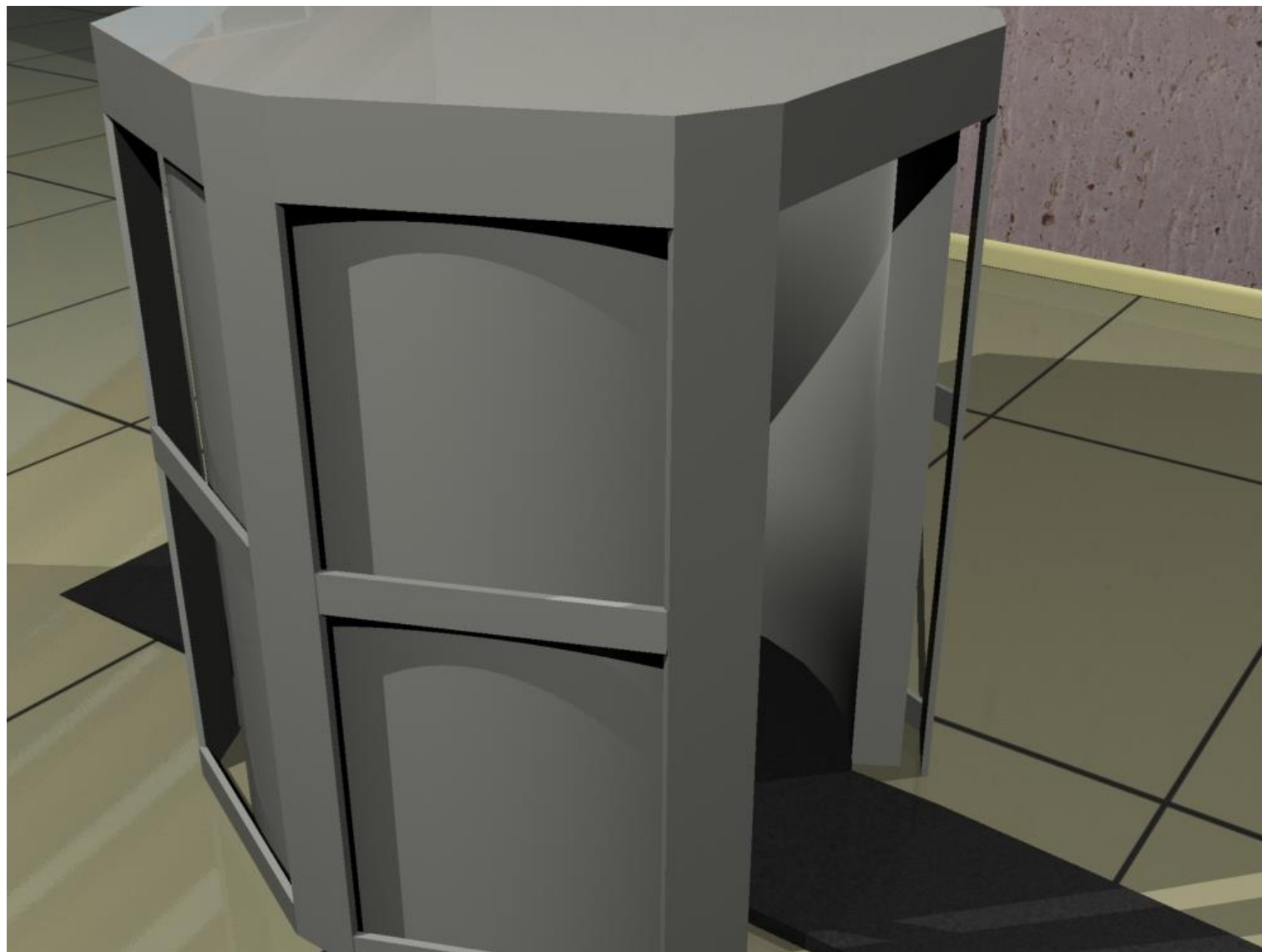
# Current Standard in Airport Screening (L3 Pro-Vision)



Millimeter wave screening via mechanical scanning of an array of antennas. A 3D image is obtained.





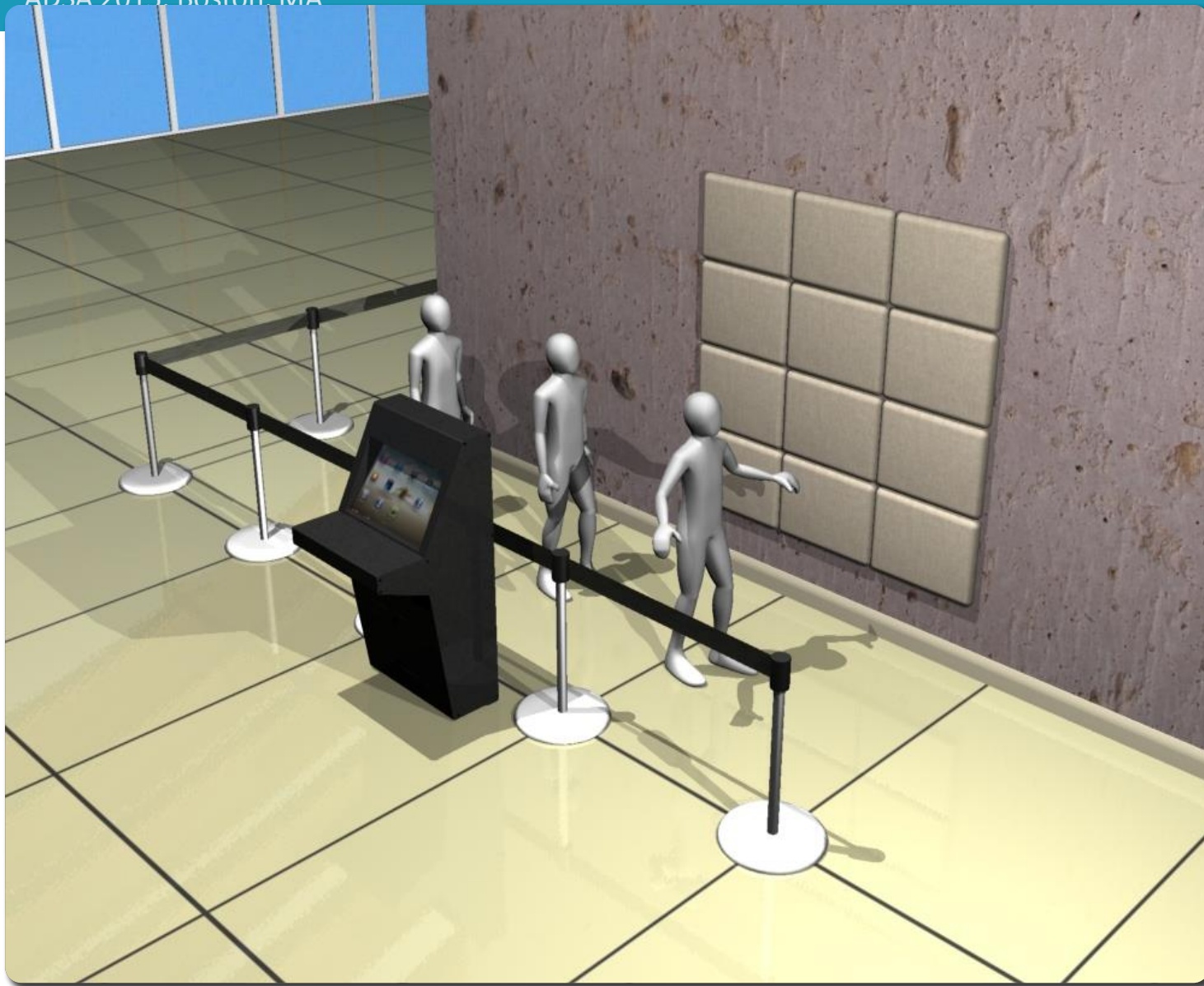




# Limitations of The Current Technology:

- **Detection:** The current technical approaches are beleaguered by blind spots and false positives.
- **Deployment:** The Bulky form factors and infrastructure needs (power, structural) set limits on equipment placement.
- **Cost:** The Economics determine the number of devices that can be deployed and the resulting passenger throughput (and annoyance). *But further,* it constrain the overall “architecture” of security screening.

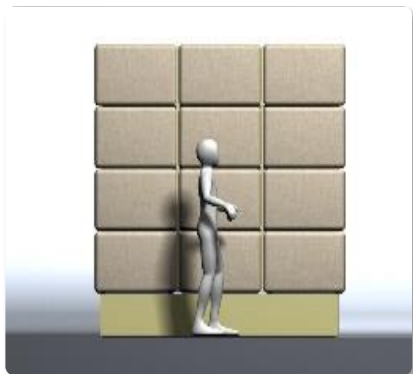




## Metamaterial Millimeter Wave Imager

# The Focus of The AIT Flat Panel Development effort is to:

- Develop Real-time imaging that enables dynamic threat monitoring and “no-stop” screening.
- Utilize Sensors with a low-profile and form factor which can be deployed and adopted to a variety of environments.
- Enable a new security paradigm of “graduated” security zones. Inconspicuous sensors that can be deployed in a manner allowing increasing scrutiny as one approaches a secure zone (more appropriate for today's security needs).





# Agenda

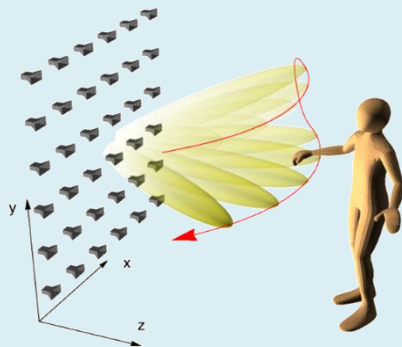
- Introduce computational imaging and metasurfaces as a useful platform for security Imaging.
- Provide an overview of the Meta-Imager architecture and our prototyping effort.
- Discuss our experimental imaging results and current metrics.
- Sketch our future development efforts



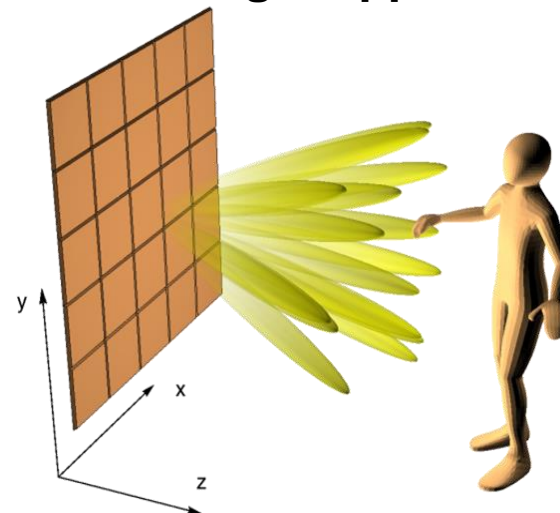
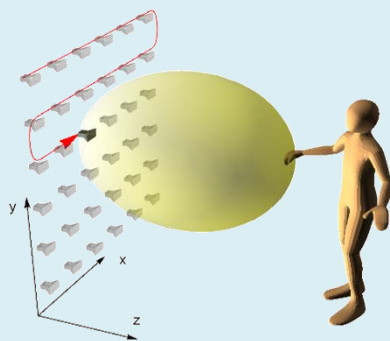
# Computational Imaging + Aperture Design Flexibility

## Meta-imager approach

### Phased Array

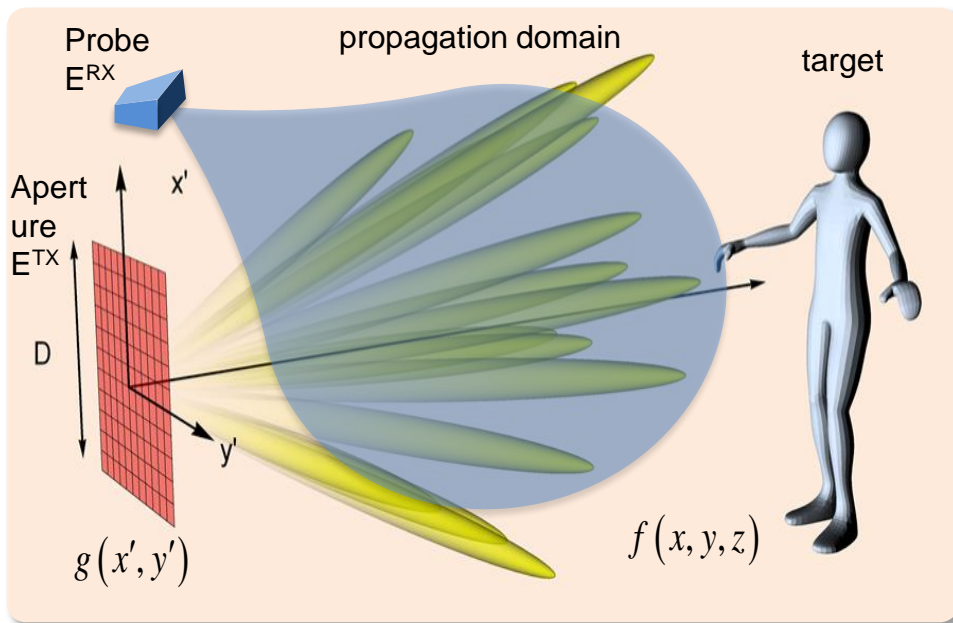


### Synthetic Aperture



- Complex beam patterns (not necessarily orthogonal) can be used to sample a scene.
- This approach allows flexibility in the aperture design and allows the aperture to be tailored to a particular scene scenario (and their requirements for speed and economics).

# Computational Imaging



Generally, the imaging problem can be presented in the discrete form:

$$g = Hf + n$$

$$\text{Measurement} \begin{pmatrix} g_1 \\ g_2 \\ \vdots \\ g_M \end{pmatrix} = \begin{matrix} \text{Measurement Modes} \\ \begin{pmatrix} h_{11} & h_{12} & h_{13} & h_{14} & \dots & h_{1N} \\ h_{21} & h_{22} & h_{23} & h_{24} & \dots & h_{2N} \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ h_{M1} & h_{M2} & h_{M3} & h_{M4} & \dots & h_{MN} \end{pmatrix} \end{matrix} \begin{pmatrix} f_1 \\ f_2 \\ \vdots \\ f_M \end{pmatrix} \text{Scene Vector}$$

$$h_{ij} \gg E^{TX}(\mathbf{r}_s - \mathbf{r}_i) E^{RX}(\mathbf{r}_s - \mathbf{r}_j)$$

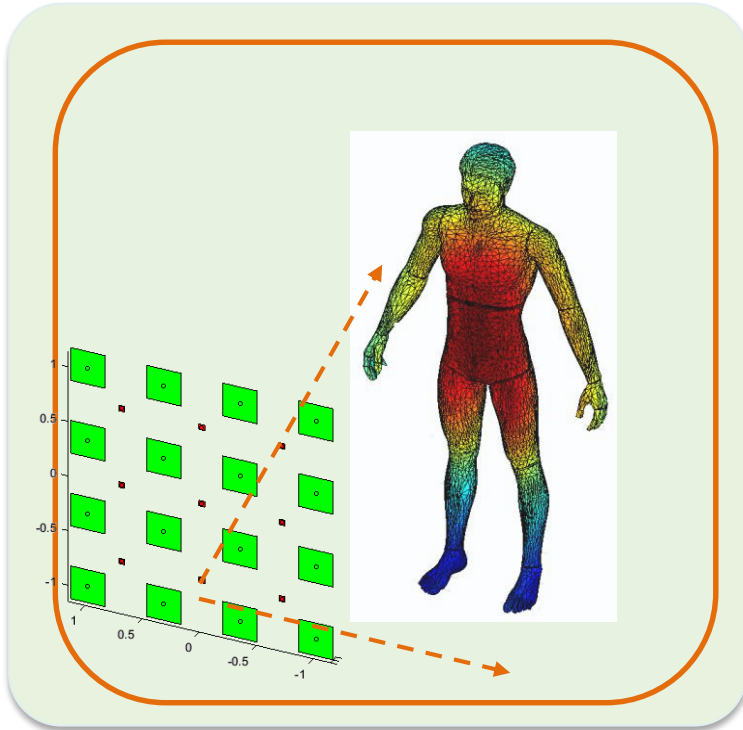
- > Meas. Modes = (freq. steps)(transmit panels)(receive panels)
- > Inverse is ill-posed, but matched filter or iterative minimization process can be used (TwIST, etc.):

$$f_{est} = H^\dagger g$$

$$f_{est} = \arg \min_f \| Hf_{est} - g \|_2^2 + |R(f_{est})|$$



# System Optimization (Virtualizer Simulator)



Optimization is best performed with a customized simulation software suite (Virtualizer):

- Simplified forward model based on the Born Approximation (no multi-path effects)
- Panels discretized into magnetic dipoles and fields calculated with greens function propagator

*The return  
signal*

*The receiver  
rad. pattern*

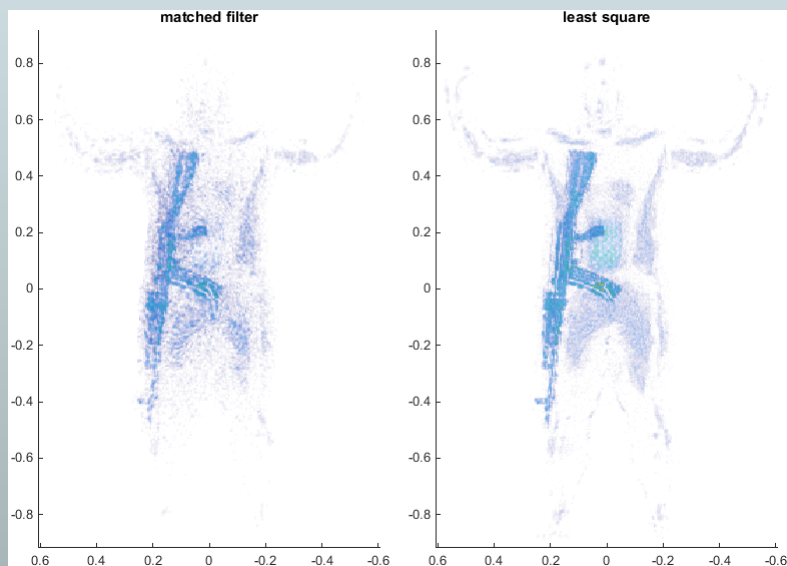
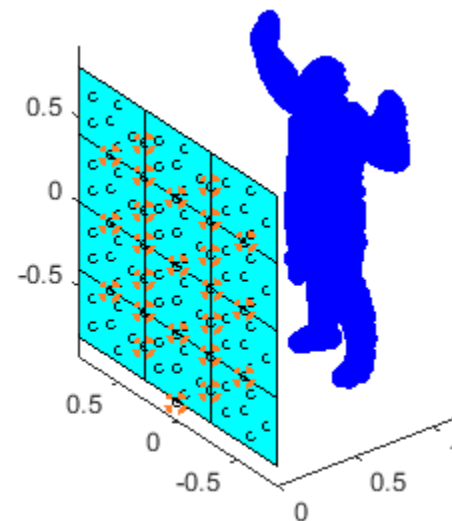
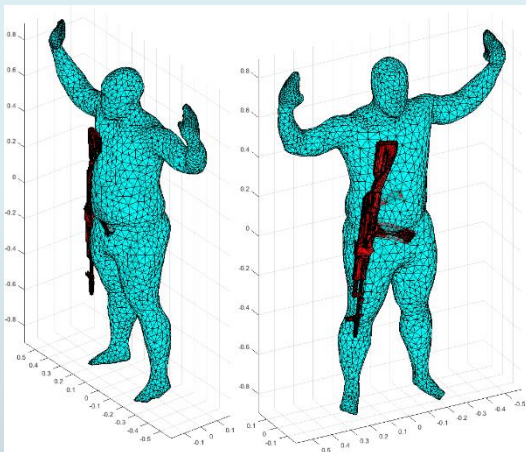
*The scene's scattering  
coefficient*

$$g(\omega) \propto \int \vec{E}_T(\omega, \vec{r}) \cdot \vec{E}_R(\omega, \vec{r}) \sigma(\vec{r}) d\vec{r}^3$$

*The transmitter  
rad. pattern*



# Virtualizer Capabilities

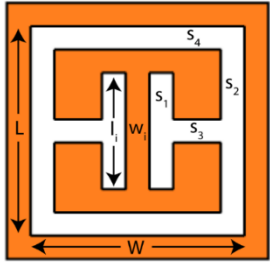


The Virtualizer allows “statistical” optimization of the system (but not direct analytic predictions):

- Analysis of panel/probe Layout
- Analysis of the panel design (element Q, size, feeding)

# MetaAntenna (Scene Encoder)

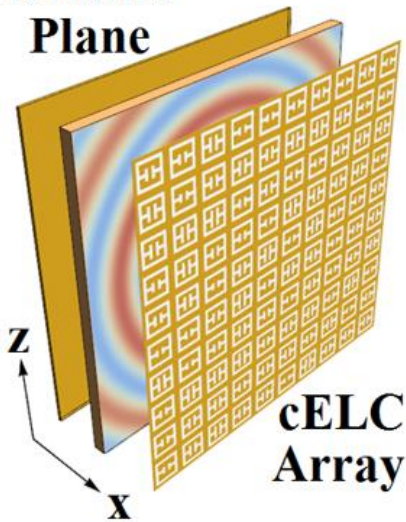
## cELCs Design



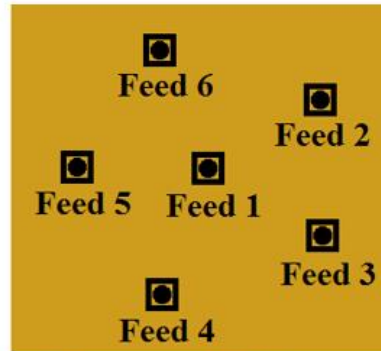
Each element radiates as a magnetic dipole, with polarizability of:

$$a_m(w) = 1 - \frac{FW^2}{W^2 - W_0^2 + iWg}$$

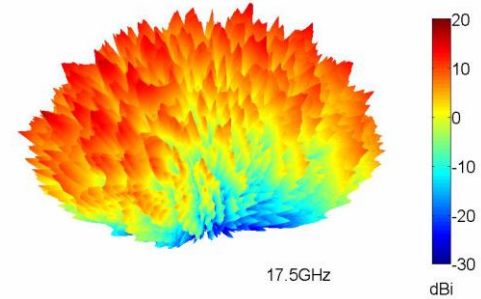
## Ground Plane



cELC Array

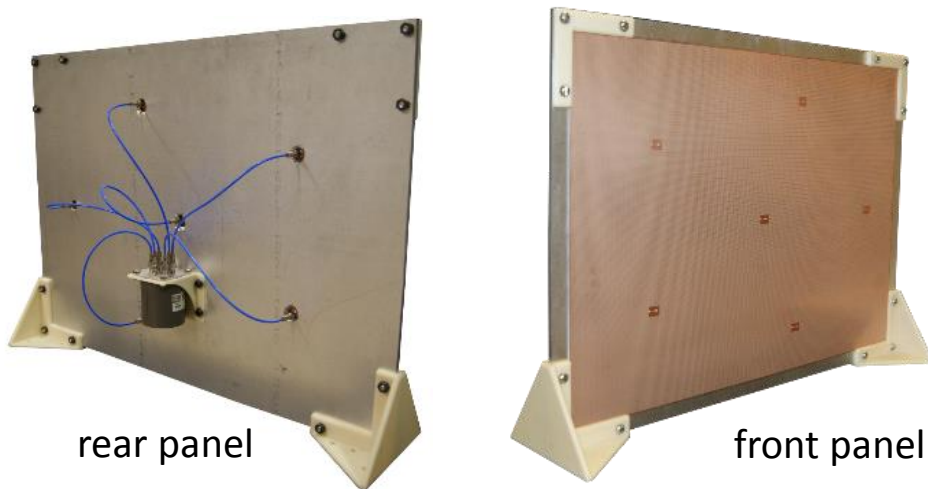


Ground Plane



- Aperture consists of metamaterial elements with random resonance frequencies.
- Aperture produces diverse modes as a function of frequency.
- Frequency scan encodes scene information on frequency measurements (18-26 GHz). Both range and cross-range measured.

# Panel Fabrication

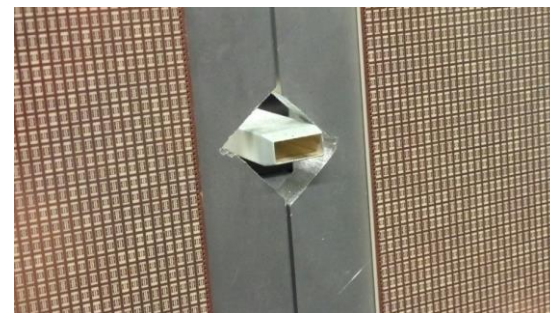
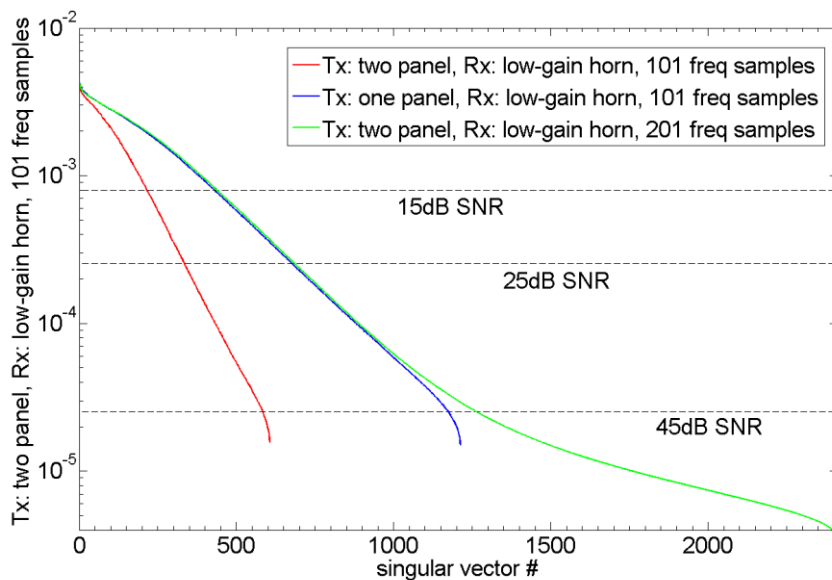


rear panel

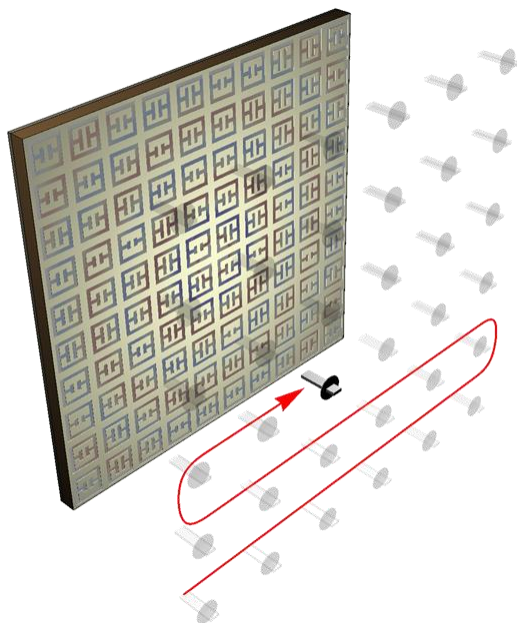
front panel

## SINGLE PANEL SPECS

- 56 cm x 44 cm.
- Frequency diversity: 101 independent modes.
- Spatial diversity: 6 feed points.
- ~600 measurement modes, *maximum*.
- Noise reduces number of measurement modes.
- Single low-gain probe for receive.

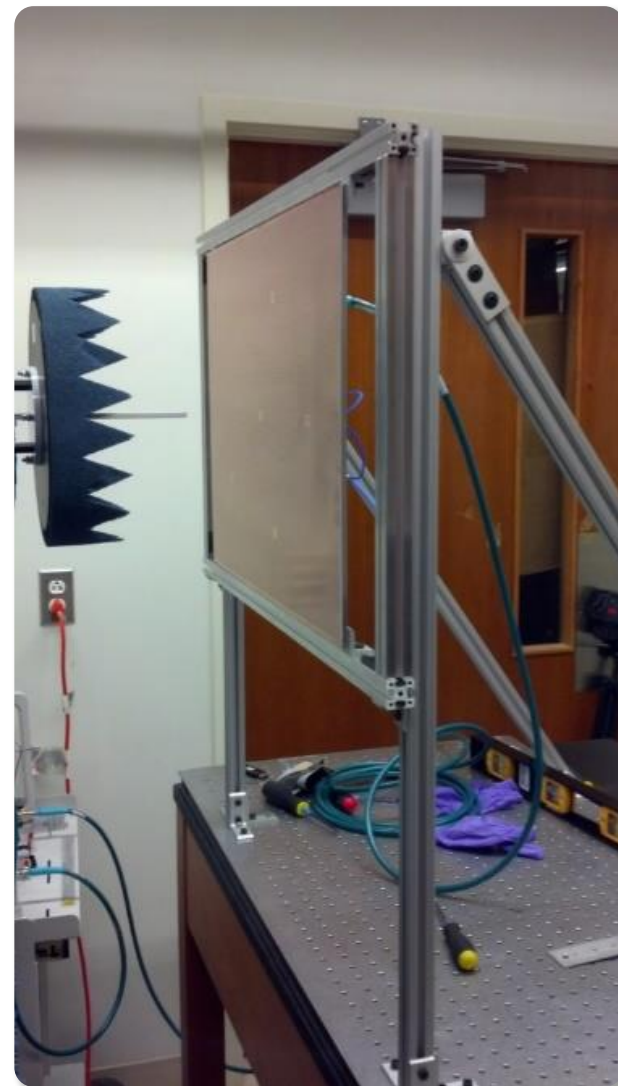


# Panel Characterization



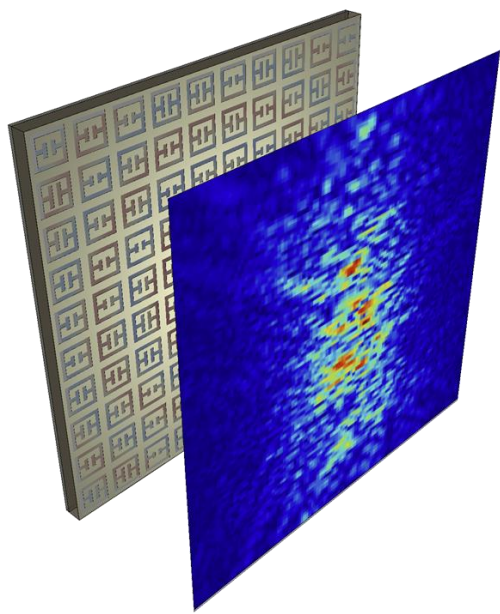
## NEAR-FIELD SCANNING

- Complex apertures require detailed characterization of radiated fields.
- Scan area:  $76.5 \times 68.5 \text{ cm}^2$ ; step size 5 mm.
- 21k samples.
- 12.1 hours per polarization (6 feeds, 101 frequency samples).





# Determining Measurement Matrix



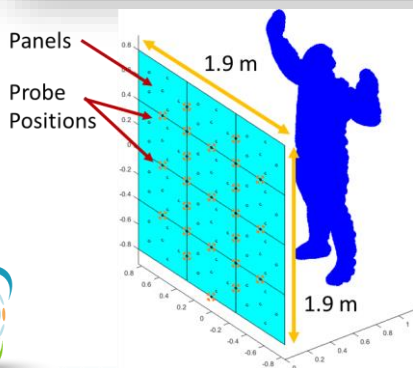
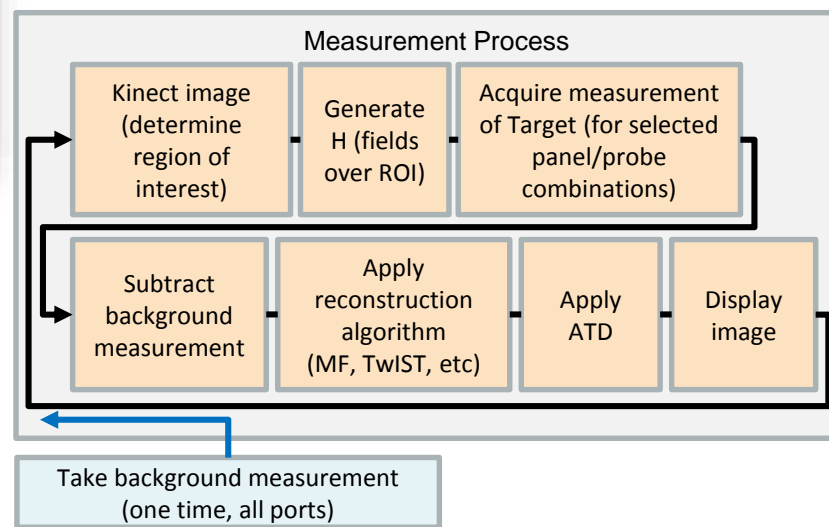
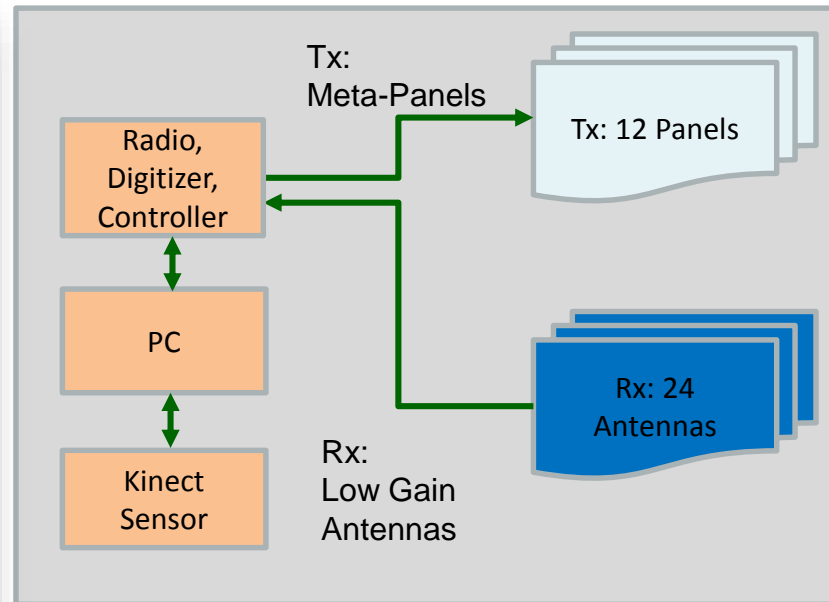
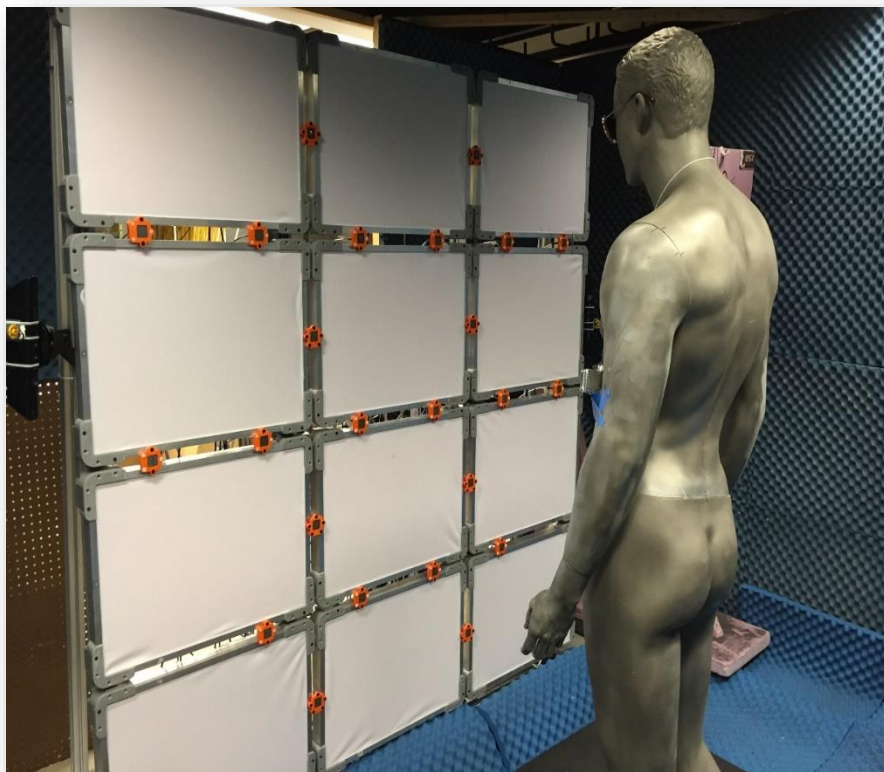
## H GENERATION

- For full scale imaging scene at diffraction limit, 30+ GB of data must be accessed (big data challenges).
- The H-matrix is built on the fly from a set of field lookup tables over the imaging regime.





# MetaImager: Architecture



# Imaging Results (under review for release)

- **Imaging Status:** Imaging full-size mannequin target and threat objects
  - Metallic phantoms are clearly observed and dielectric objects have secondary observable properties that can be used for detection
- **Reconstruction time:** ~1 minute per image (90% is data acquisition that is the result of mechanical switching).
  - Utilizing advanced factorization algorithm for reconstruction.
- **Resolution:** At the aperture diffraction limit for small objects (<1 cm).
- **System architecture:** composed of a few core components (single radio, passive panels/probes, and a switching network).



# Future System Improvements

- **Speed:** (Next phase is targeting 10 fps)
  - Moving to electronic switching
  - Upgrading the radio for parallel data acquisition and faster sweeping.
  - Improving panel radiation diversity, Q (reducing the number of necessary measurement modes)

## **Image Quality:** (Coverage)

- Redistribution of panel/probe layout to improve viewing angles
- Implementing multiple look techniques (further down the road)



# Summary

- The Metalmager approach, combined with computational imaging techniques, provides a path towards a real-time security imaging devices and economical deployment of them.
- The Meta-Imager concept can support new strategies for security screening (sensor fusion, redistribution, etc.).





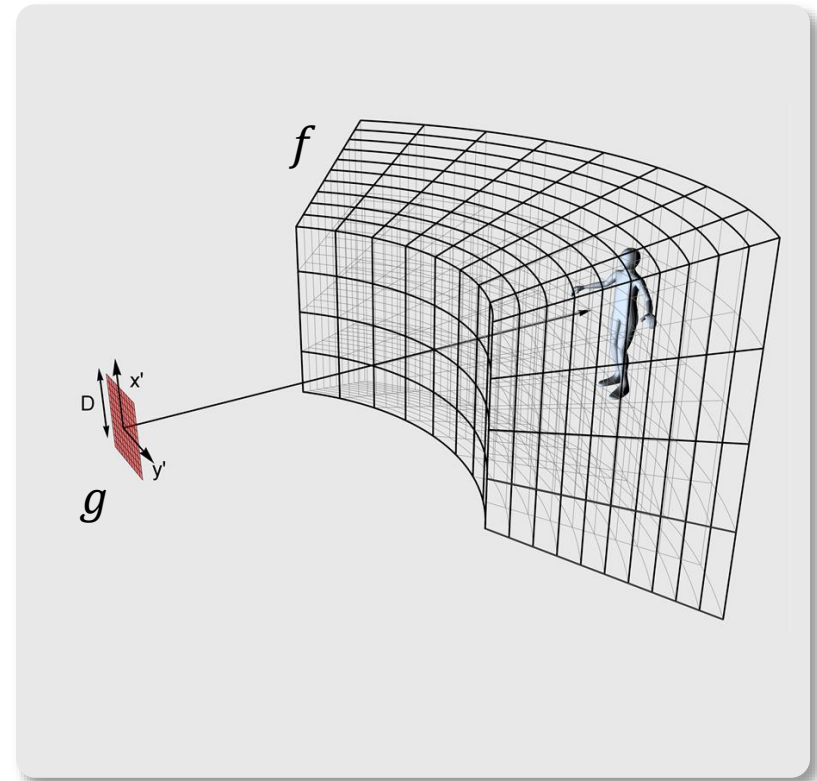
# Backup Slides



## COMPUTATIONAL IMAGING

- The scene is represented by a reflectivity function.
- Measurements of the scene can be taken, represented by, either parallel or sequential.
- A *forward model* relates scene reflectivity to the measurements.
- The basic imaging equation can be written:

$$g(\mathbf{x}) = \int H(\mathbf{x}, \mathbf{x}') f(\mathbf{x}') d\mathbf{x}'$$

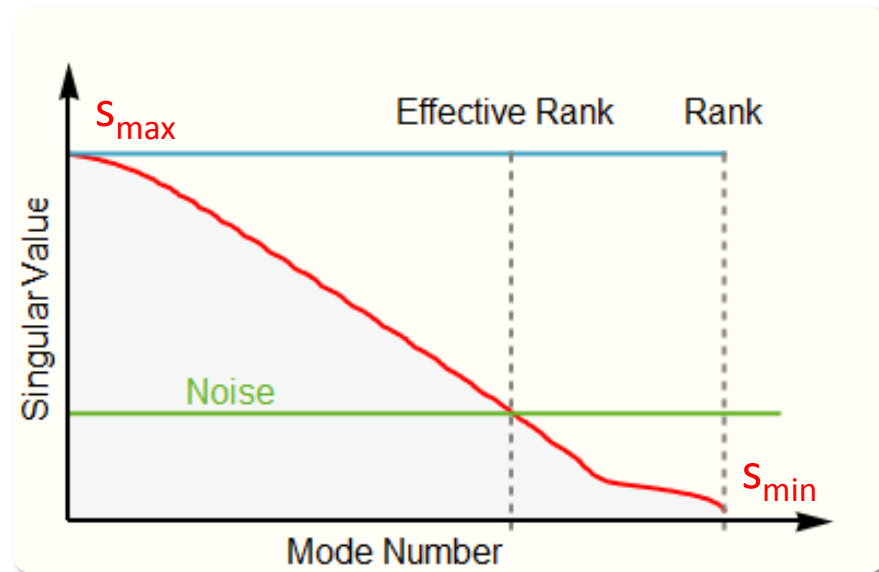


# Characterizing Imaging Quality

- > The set of measurement modes can be characterized by their singular value spectrum:

$$H = USV^+$$

- > If  $H$  is  $N \times M$ , then  $\Sigma$  is  $N \times M$  diagonal matrix of positive real values.
- > Uncorrelated modes have a flat spectrum, while correlated modes lead to non-flat SV.
- > Condition number relates the ease of matrix inversion
- > Presence of noise truncates SV spectrum (introduces effective rank)



Singular value decomposition relates the actual information contained in the measurement modes over a given imaging regime.

