

Model-Based Iterative Reconstruction for CT Luggage Screening

Pengchong Jin¹, Charles Bouman¹, Ken Sauer²

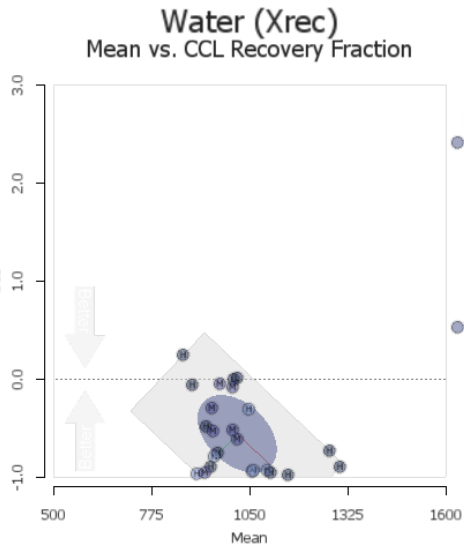
ALERT TO#3 Project Review

10/24/2013

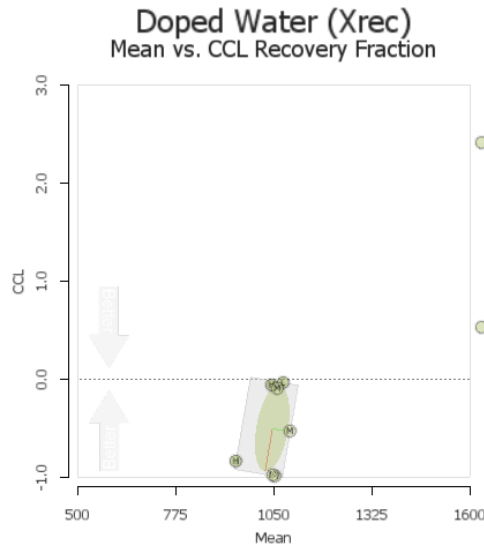
1. School of Electrical and Computer Engineering, Purdue University
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Cloud Plots

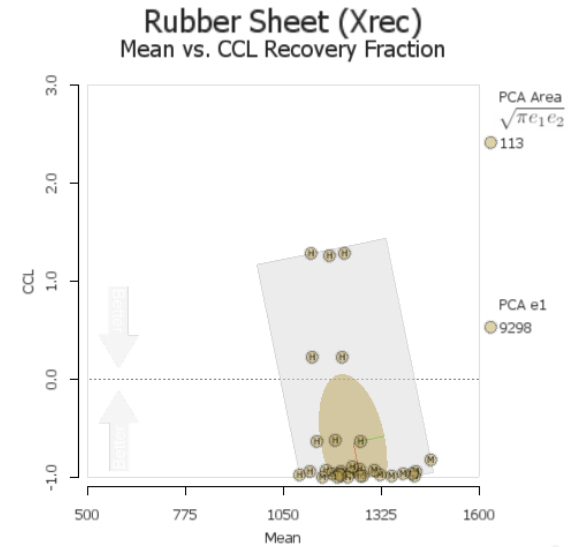
Xrec (FBP)



20131018 175854 "Bouman" scriptver 0x102 cloudver 0x103

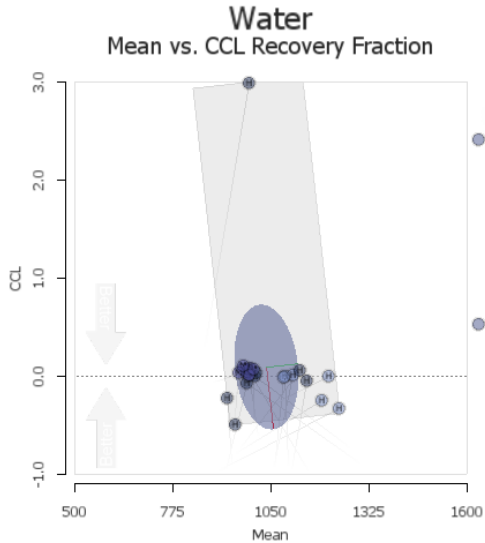


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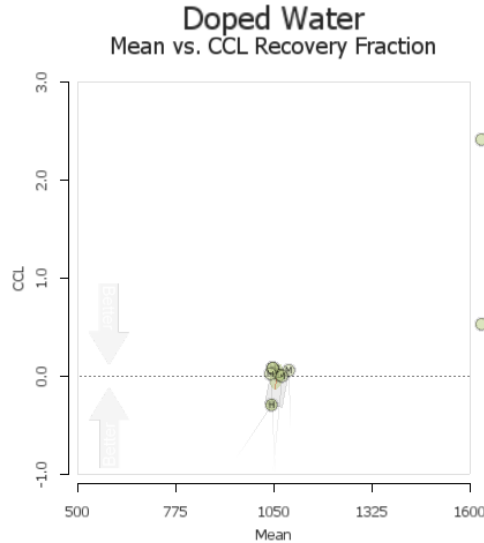


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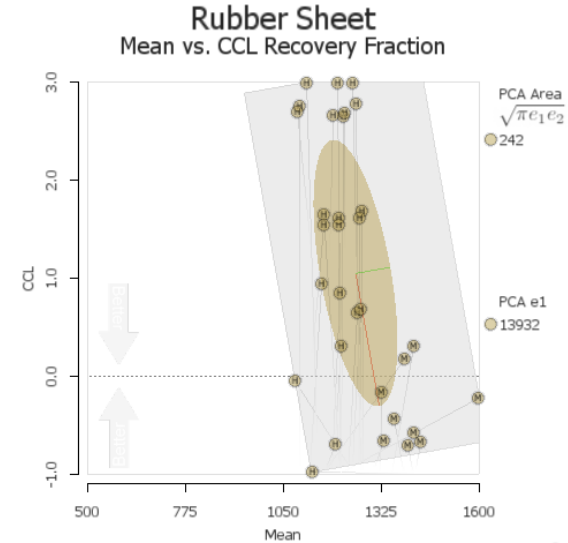
MBIR



20131019 143014 "Bouman" scriptver 0x102 cloudver 0x103



20131019 143014 "Bouman" scriptver 0x102 cloudver 0x103

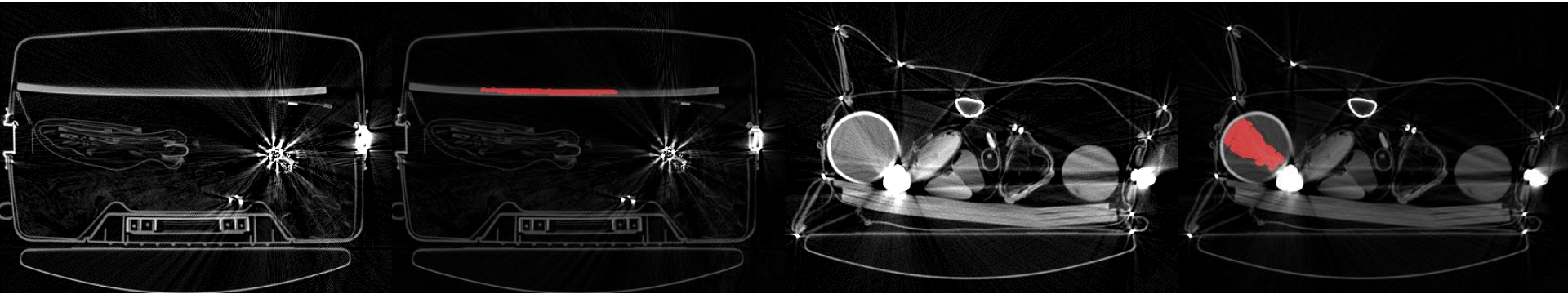


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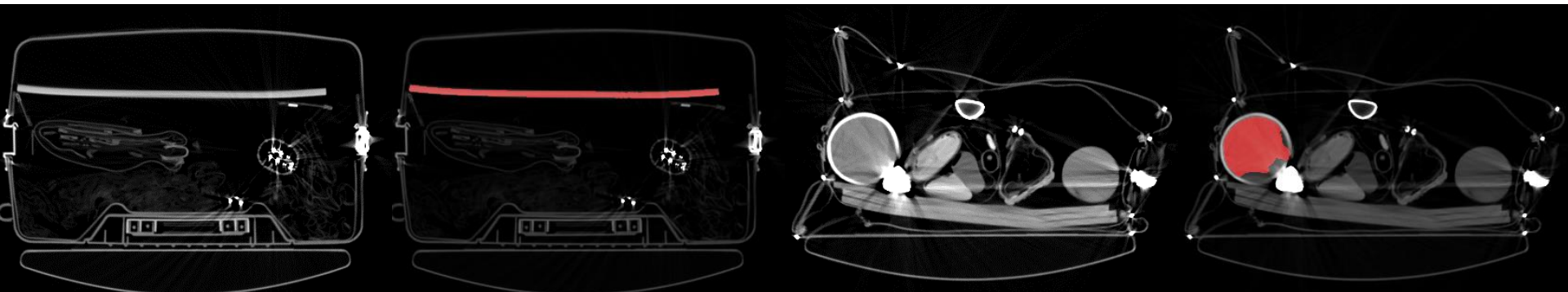
Sample Images

Medium Clutter (1-123)

High Clutter (1-239)



Xrec (FBP), and Tumbler segmentation



MBIR, and Tumbler segmentation

Introduction to the institution and researchers

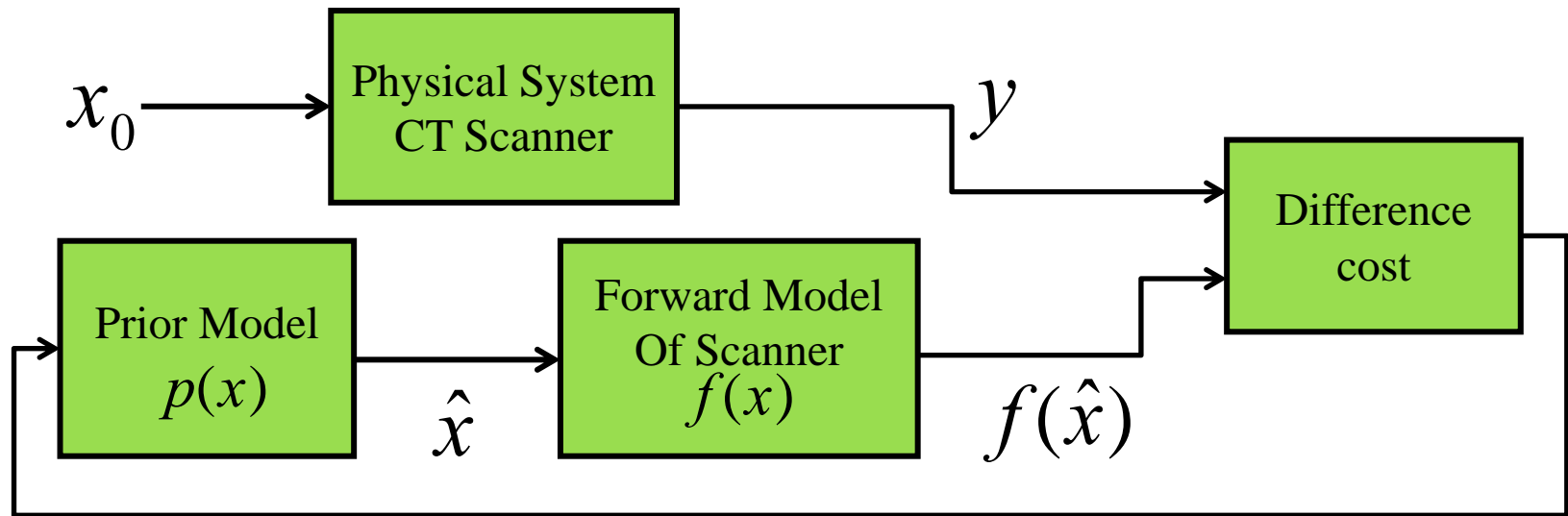


- Pengchong Jin – 5th year Ph.D. student, Purdue University. B.Eng, ECE from HKUST (2009). Statistical signal processing, inverse problems
- Charles Bouman – Showalter Professor of ECE, Purdue University. BSEE U. Penn, Ph.D. Princeton (1989). Stochastic image modeling, image rendering, tomography
- Ken Sauer – Assoc. Prof. of EE, University of Notre Dame. BSEE Purdue, Ph.D. Princeton (1989). Statistical methods in tomographic inverse problems, optimization



Methods

Model-based Iterative Reconstruction



- $x \hat{\in} R^N$: image to be estimated, $y \hat{\in} R^M$: sinogram
- Invert by computing the MAP estimate

$$\hat{x}_{MAP} = \arg \max \{ \underbrace{\log p(y | x)}_{\substack{\text{Likelihood function} \\ \text{Forward model derived from system physics} \\ \text{Measurement noise modeling}}} + \underbrace{\log p(x)}_{\substack{\text{Prior} \\ \text{Regularization} \\ \text{smoothing}}} \}$$

Likelihood function
Forward model derived from system physics
Measurement noise modeling

Model-Based Iterative Reconstruction

- Cost function for image reconstruction

$$\hat{x}_{MAP} = \arg \min_{x \geq 0} \left[\frac{1}{2} \|y - E[y | x]\|_W^2 + \sum_{\{s,r\} \in C} a_{s,r} r(x_s - x_r) \right]$$

- $x \in \mathbb{R}^N$: image to be estimated
- $y \in \mathbb{R}^M$: sinogram, measurements
- Data fit term of cost
 - Accurate model of X-ray forward projection $E[y | x]$
 - Accurate noise model, weighting matrix W

Main idea: Adapt data penalty term to take “pressure” off metal-corrupted measurements

Approach 1: Better Forward Projection Model

- Classic forward model assumes $E[y | x] = Ax$
- Energy-dependent attenuation \rightarrow beam “hardening”
- Our approach
 - Separate materials into low and high densities

$$E[y | x] = h(p_{L,i}, p_{H,i}) = \prod_k \prod_l g_{k,l}(p_{L,i})^k (p_{H,i})^l$$

- Two separate “material” projections

$$p_{L,i} = \prod_{j=1}^N A_{i,j} x_j (1 - b_j), \quad p_{H,i} = \prod_{j=1}^N A_{i,j} x_j b_j$$

- $b_j \in \{0, 1\}$: indicator of the j-th pixel for high density

Approach 1: Joint Estimation and Correction

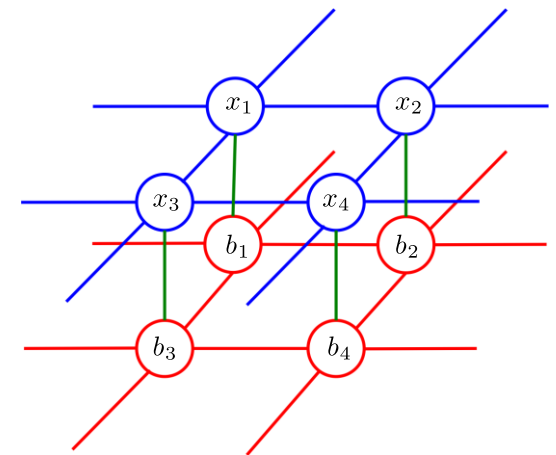
- Joint optimization problem

$$\{\hat{x}, \hat{b}, g\} = \arg \min_{x \geq 0, b, g} \left\{ \frac{1}{2} \sum_{i=1}^M \left(y_i - \sum_k \sum_l g_{k,l} (p_{L,i})^k (p_{H,i})^l \right)^2 + U(x, b) \right\}$$

- Simultaneous image reconstruction and beam hardening correction as a joint optimization problem
- Use alternating optimization for x , b and $g_{k,l}$ s.

- Joint regularization scheme $U(x, b)$

$$U(x, b) = \sum_{\{s,r\} \in C} \dot{a}_{s,r} r(x_s - x_r) + \sum_{\{s,r\} \in C} \dot{a}_{s,r} h_{s,r} d(b_s - b_r) + b \sum_{j=1}^N \dot{a}_j (x_j - T)_+ (1 - b_j) + (T - x_j)_+ b_j$$



Approach 2: Better Noise Model (Weighting)

- A typical weighting from Poisson-Gaussian model*

$$w_i = \frac{I_i^2}{I_i + S_e^2} \mu \frac{e^{-2y_i}}{e^{-y_i} + C_e}$$

- Large dynamic range when metals are present

- Novel weighting scheme

$$w_i = I_i e^{-y_i} + (1 - I_i) e^{-y_i/2}$$

- $0 \leq I_j \leq 1$: fraction of contribution from high density material
- Calculated using the initial image

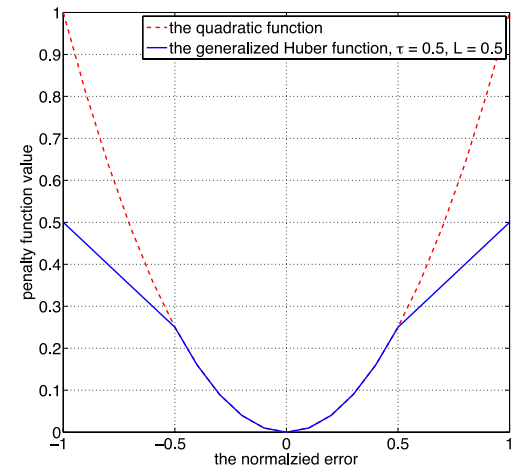
*Sauer, Bouman, TIP, Feb. 1993, Thibault, Sauer, Bouman, Hsieh, Medical Physics, Nov. 2007

Approach 3: Robust treatment of outliers

- The actual measurement can differ from the physical model significantly
 - Due to various effects coupled together, beam hardening, scattering, metal partial volume, etc.
 - Hard to integrate them individually
- Consider a modified model to reduce the influence of the defective measurement to the MBIR cost*

$$-\log p(y|x) = \frac{1}{2} \sum_{i=1}^M H_{L,t} \left(\sqrt{w_i} (y_i - A_{i,*}x) \right)$$

– $H_{L,t}(\times)$ is the generalized Huber function



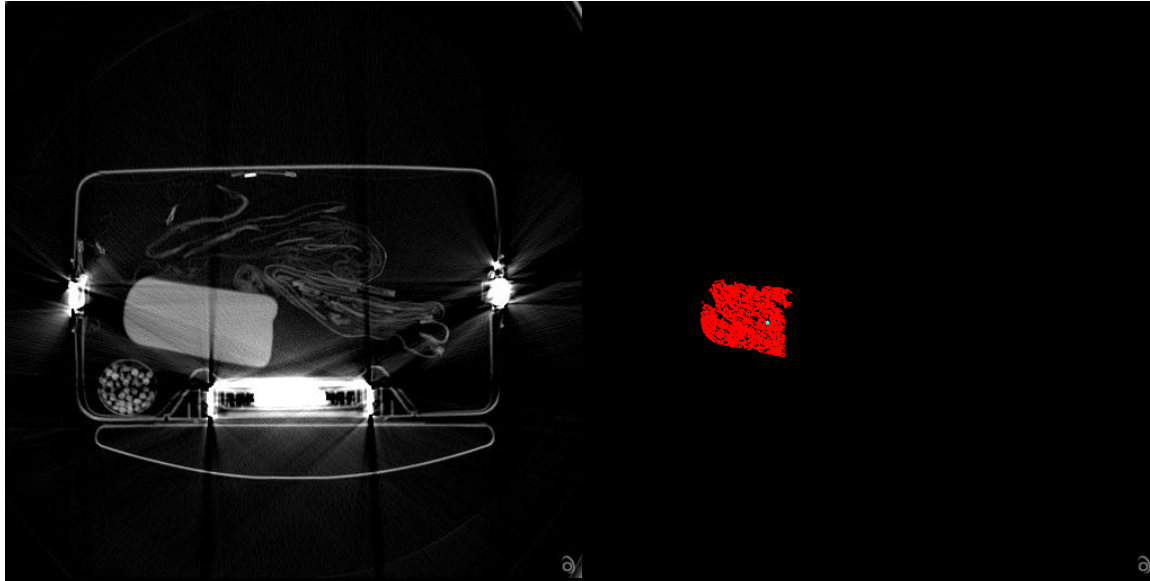
Results

Doped Water Recon/Segmentation

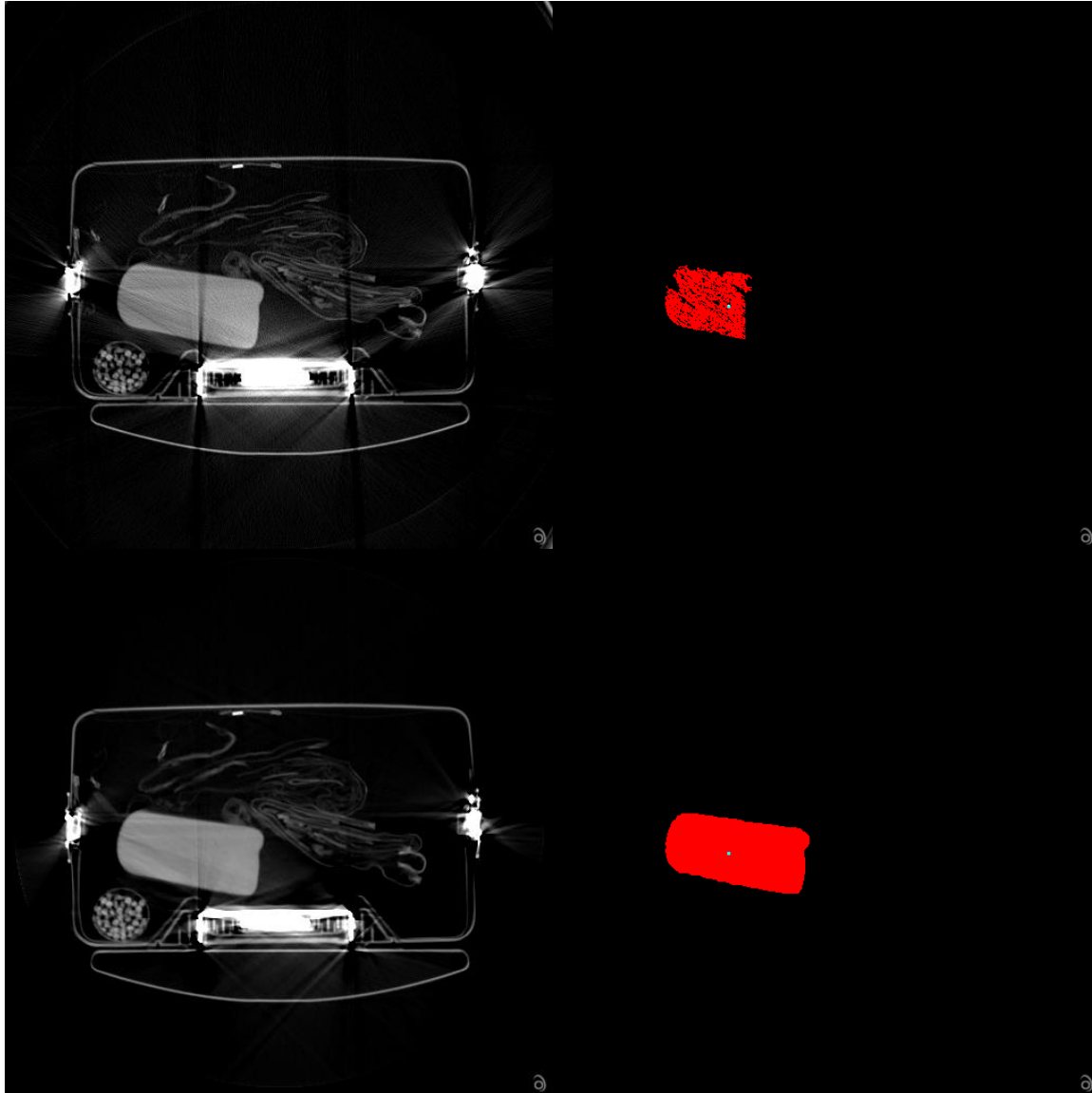
Medium Clutter (2-326)

CCL results

Xrec (FBP)



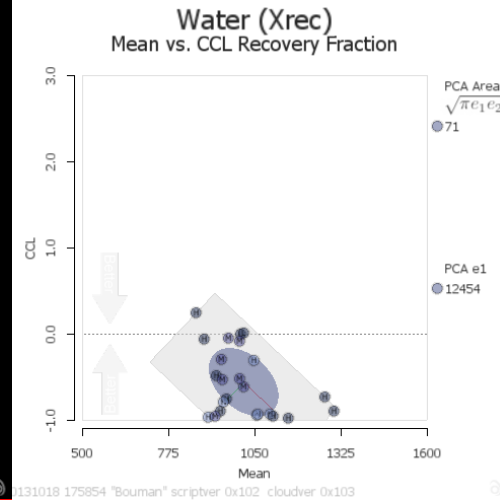
MBIR



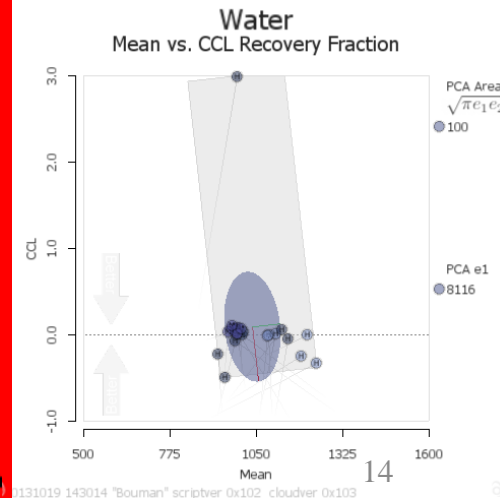
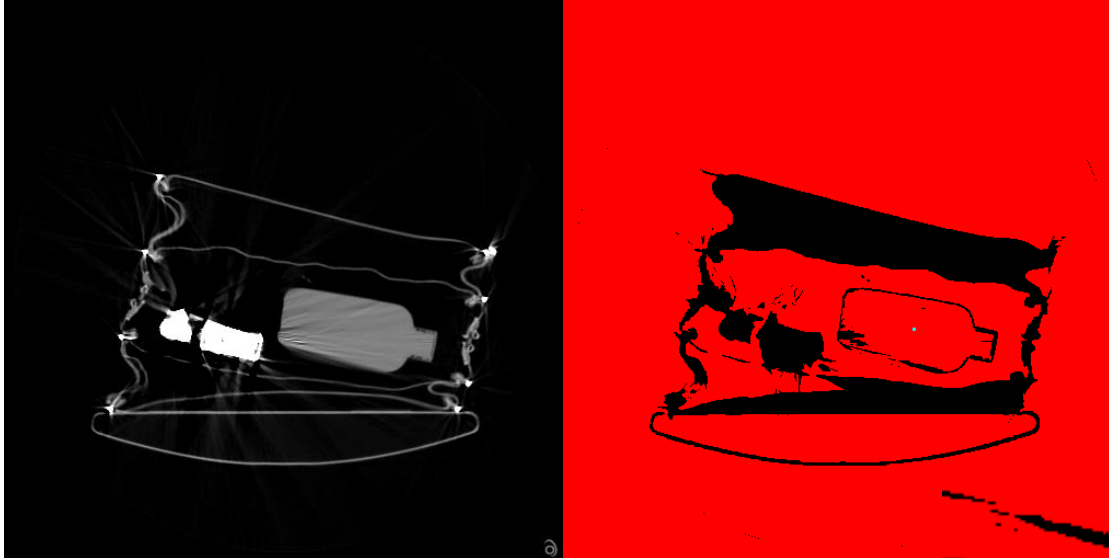
MBIR/CCL Epic Fail

High Clutter Water (1-350) CCL results

Xrec (FBP)



MBIR

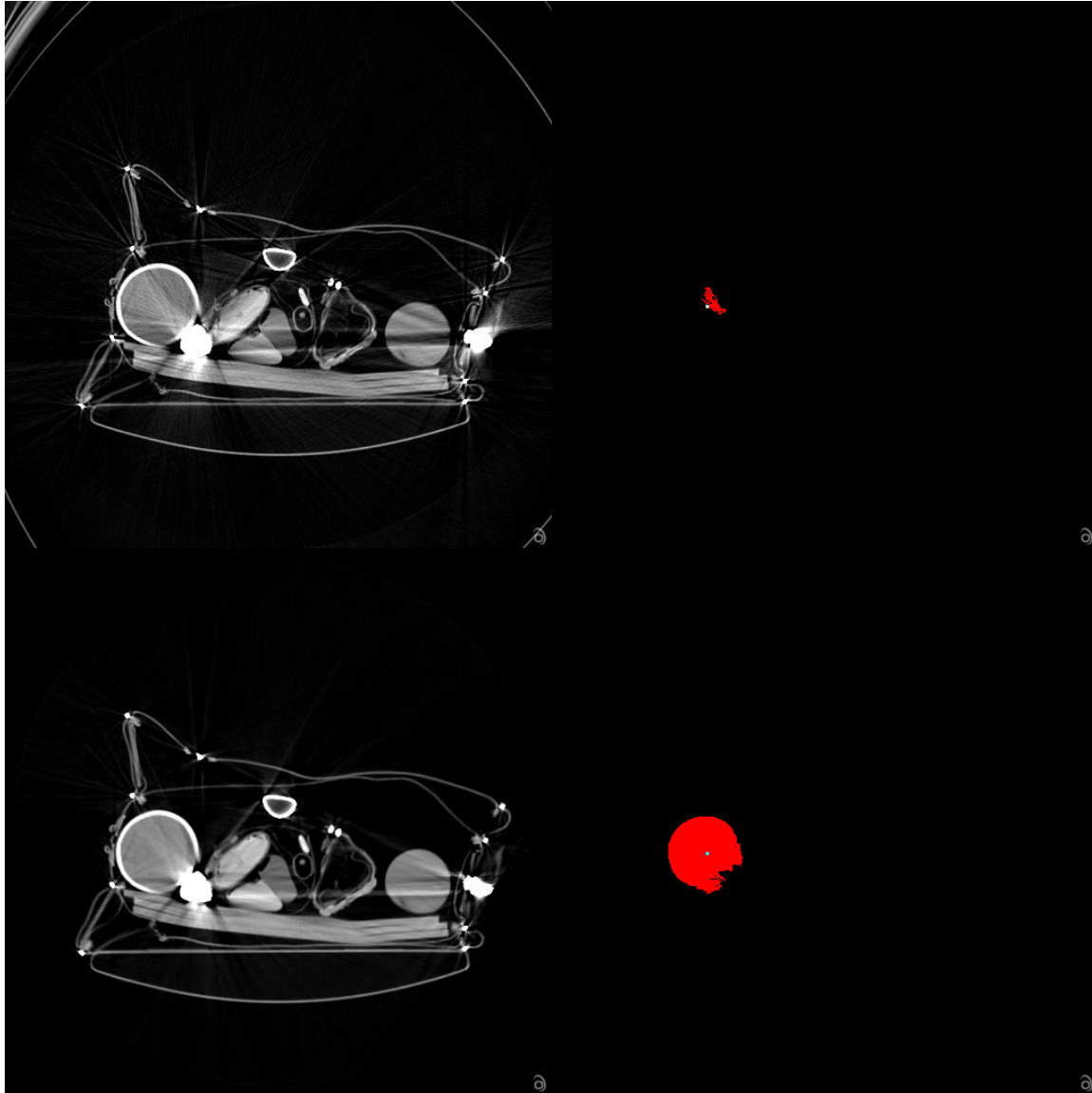


Sample Water Recon/Segmentation

High Clutter (1-239)

CCL results

Xrec (FBP)

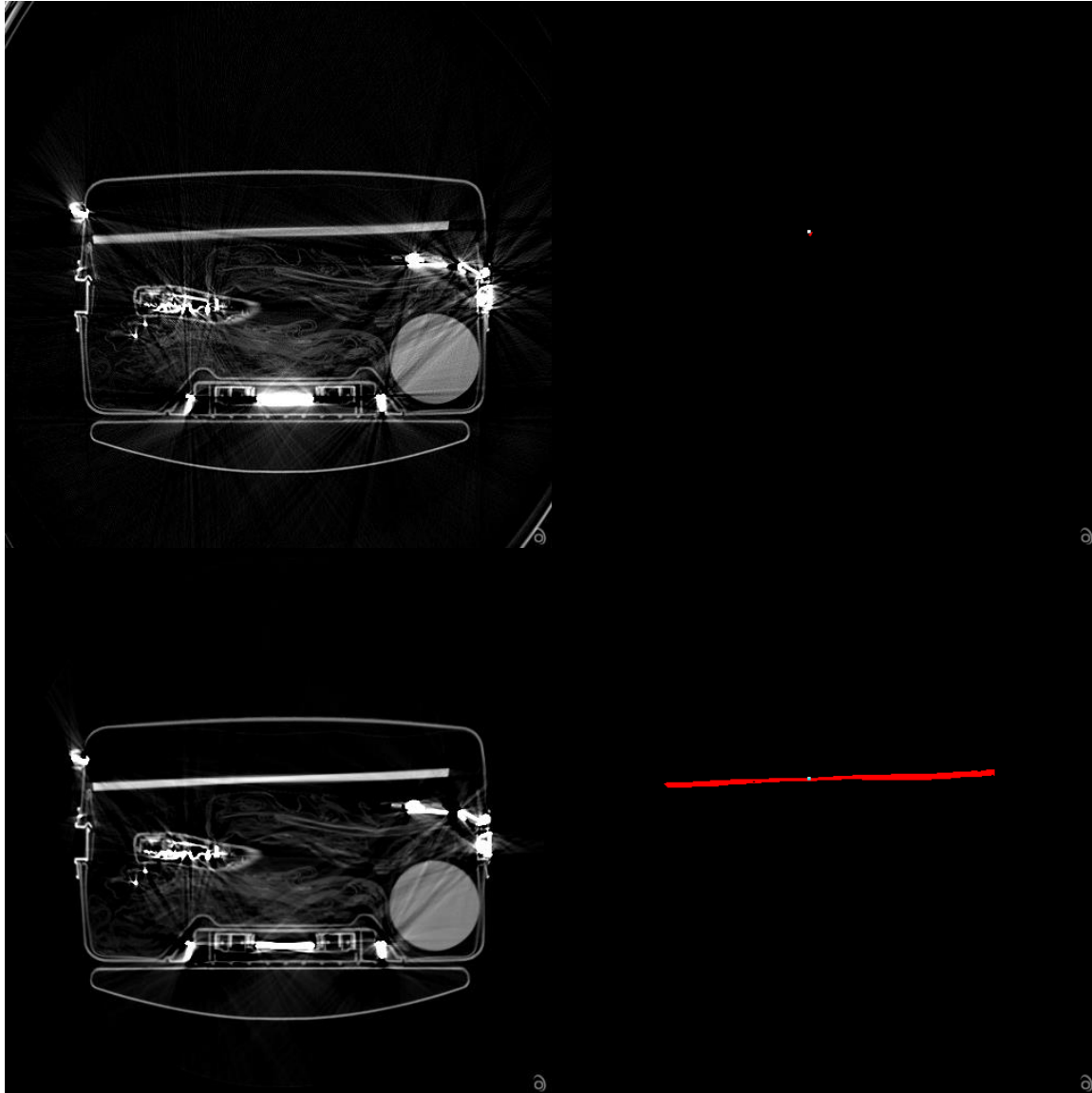


MBIR

Sample Sheet Recon/Segmentation

Medium Clutter (1-281) CCL results

Xrec (FBP)



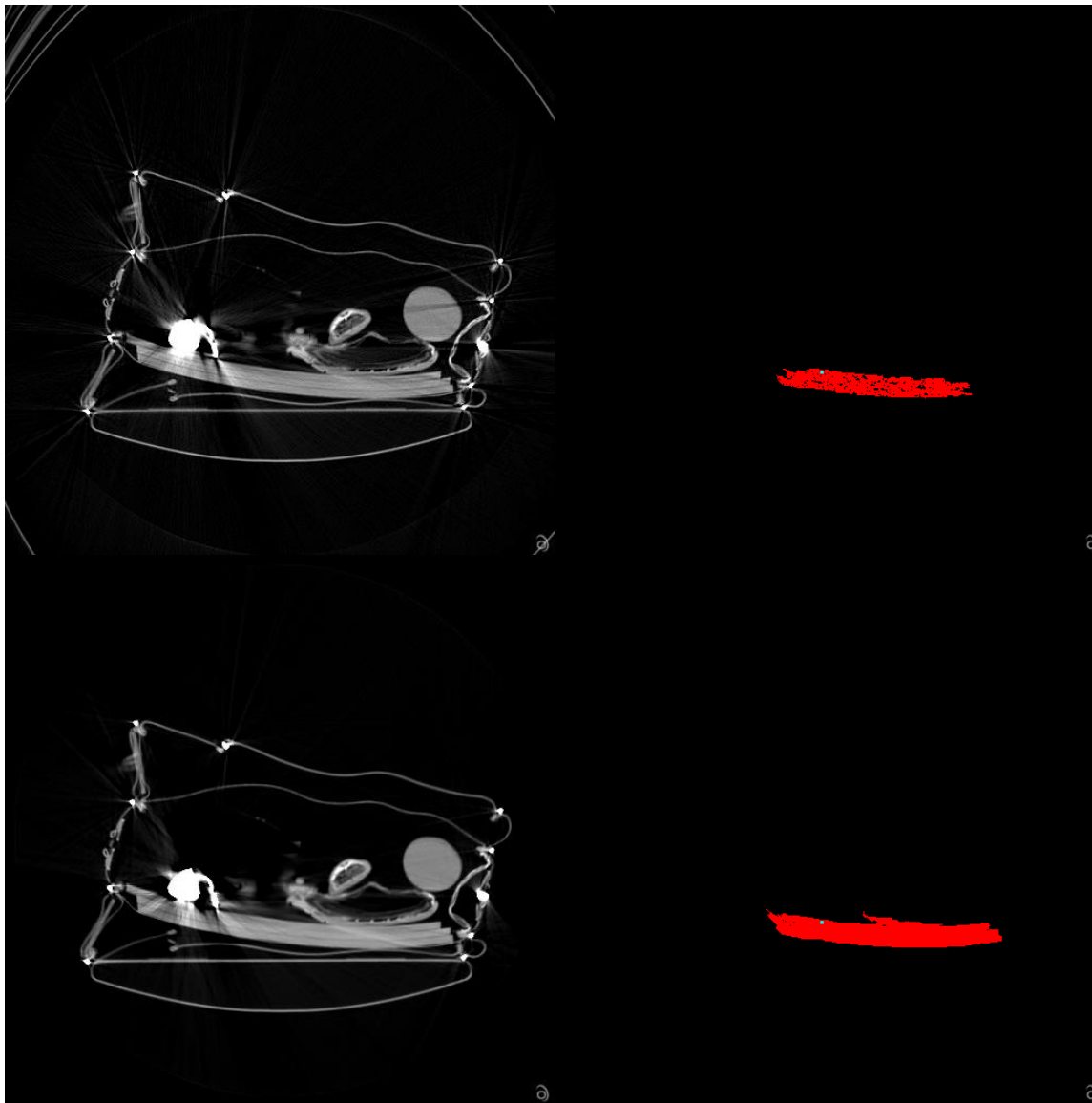
MBIR

Sample Sheet Recon/Segmentation

High Clutter (1-299)

CCL results

Xrec (FBP)



MBIR

Summary

- Positives of MBIR in TO3:
 - Good suppression of noise in bulk materials
 - Options for reduction of metal artifacts to improve segmentation
 - Improved resolution
- Downsides
 - Don't yet see “magic bullet” for metal
 - Key materials/configuration (rubber sheets + metal) remains challenging
 - Huge computational cost is barrier to entry
 - Rebinning for speed, simplicity may cost resolution available in accurate system modeling

Quo Vadis?

- More aggressive treatment of metal
 - ✓ Formulate fixed correction function for beam hardening
 - ✓ Projection replacement algorithms
- Resolution enhancement through modeling of rebinning losses
 - ✓ Expand detector in forward model
 - ✓ High frequency pre-emphasis of sinograms
- Improve *a priori* image model
 - ✓ Take advantage of 3rd spatial dimension
 - ✓ Tailor prior to discrete-valued materials
 - Total variations-like?

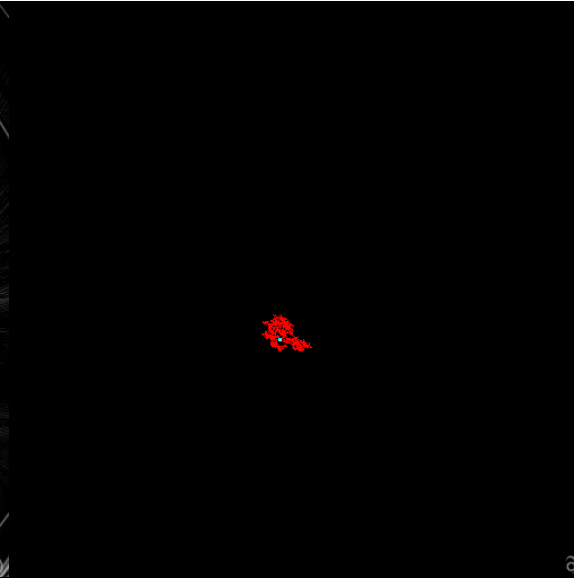
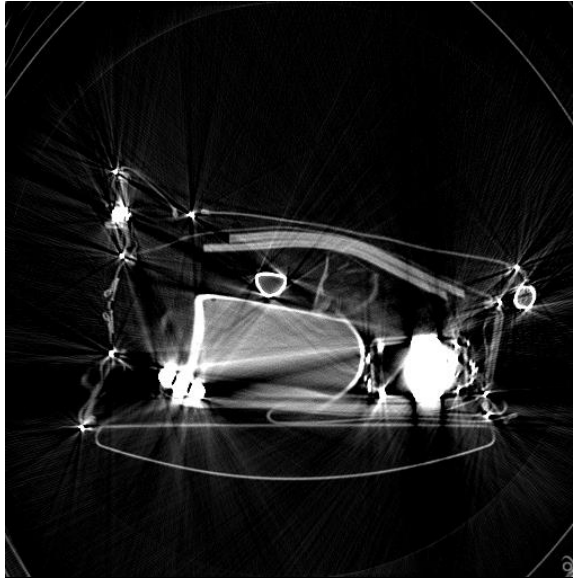
Backup Slides

Metal Artifact Reduction

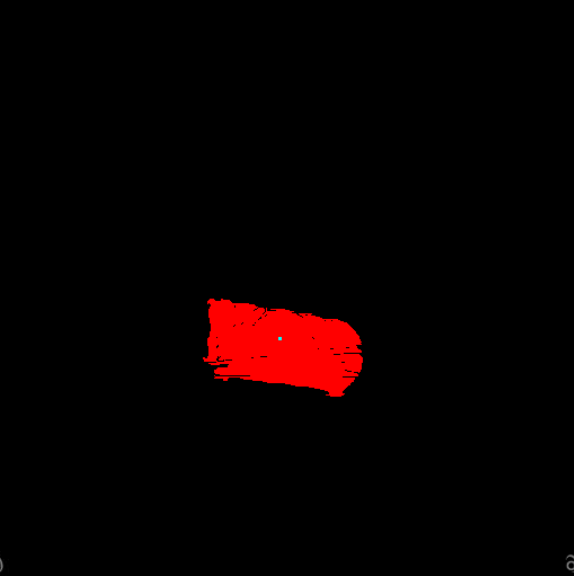
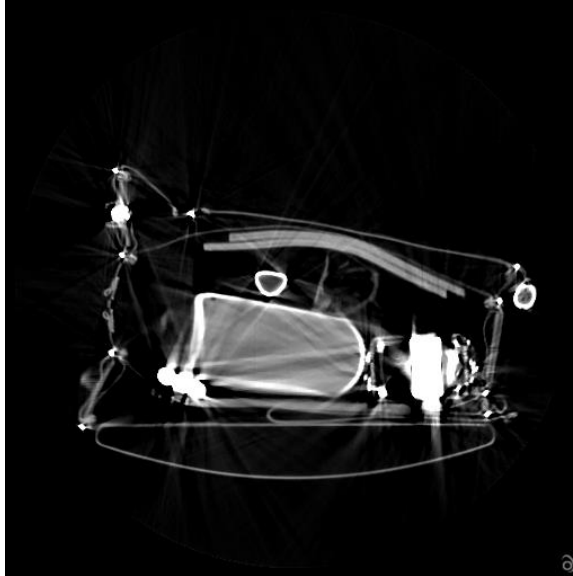
High Clutter (3-194)

CCL results

Xrec (FBP)



MBIR



Model-Based Iterative Reconstruction

- Statistical model for image reconstruction

$$\hat{x}_{MAP} = \arg \max_{x \geq 0} \{ \log p(y | x) + \log p(x) \}$$
$$= \arg \min_{x \geq 0} \left\{ \frac{1}{2} \|y - E[y | x]\|_W^2 + \sum_{\{s,r\} \in C} a_{s,r} r(x_s - x_r) \right\}$$

- $x \hat{\in} R^N$: image to be estimated
- $y \hat{\in} R^M$: sinogram, measurement
- Forward model $p(y | x)$
 - Accurate model of X-ray forward projection $E[y | x]$
 - Accurate noise model, weighting matrix W
- Image prior model $p(x)$
 - Regularize undesired image behavior, smoothing

Approach 1: Better Forward Projection Model

- Classic forward model assumes

$$E[y | x] = Ax$$

- $A \hat{\in} R^{M \times N}$: linear forward projection operator
- Energy-dependent attenuation, broadness of X-ray spectrum
- Beam hardening effect, nonlinear relationship

- Our approach

- Different materials can be separated by their densities

$$E[y | x] = h(p_{L,i}, p_{H,i}) = \underset{k}{\mathring{a}} \underset{l}{\mathring{a}} g_{k,l} (p_{L,i})^k (p_{H,i})^l$$

- Two separate “material” projections

$$p_{L,i} = \underset{j=1}{\mathring{a}}^N A_{i,j} x_j (1 - b_j), \quad p_{H,i} = \underset{j=1}{\mathring{a}}^N A_{i,j} x_j b_j$$

- $b_j \hat{\in} \{0, 1\}$: indicator of the j-th pixel that of high density

Approach 1: Joint Estimation and Correction

- Joint optimization problem

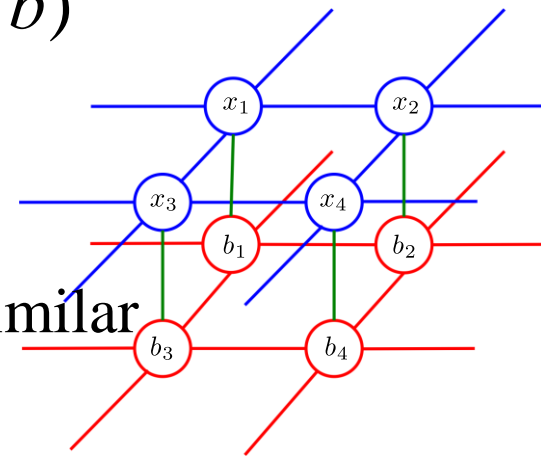
$$\{\hat{x}, \hat{b}, g\} = \arg \min_{x \geq 0, b, g} \left\{ \frac{1}{2} \sum_{i=1}^M \left(y_i - \sum_k \sum_l g_{k,l} (p_{L,i})^k (p_{H,i})^l \right)^2 + U(x, b) \right\}$$

- Simultaneous image reconstruction and beam hardening correction as a joint optimization problem
- Use alternating optimization for x , b and $g_{k,l}$ s.

- Design joint regularization scheme $U(x, b)$

$$U(x, b) = \sum_{\{s,r\} \in C} \hat{a}_{s,r} r (x_s - x_r) + \sum_{\{s,r\} \in C} \hat{a}_{s,r} h_{s,r} d(b_s - b_r) + b \sum_{j=1}^N \hat{a}_j (x_j - T)_+ (1 - b_j) + (T - x_j)_+ b_j$$

- Want neighboring pixels, and labels to be similar
- Want pixels and labels to be consistent
- Use $T = 2000$ HU



Approach 2: Better Noise Model (Weighting)

- A typical weighting from Poisson-Gaussian model*

$$w_i = \frac{I_i^2}{I_i + S_e^2} \mu \frac{e^{-2y_i}}{e^{-y_i} + C_e}$$

- Uniform weighting scheme
- Large dynamic range when metals are present
- Novel weighting scheme

$$w_i = I_i e^{-y_i} + (1 - I_i) e^{-y_i/2}$$

- $0 \leq I_j \leq 1$: “percent” of contribution from high density material
- Calculated using the initial image

$$I_i = \frac{y_{metal,i}}{y_i} = \frac{\sum_{j=1}^N A_{i,j} x_j^{(0)} d(x_j^{(0)} > T)}{y_i}$$

Approach 3: Bad Measurement Rejection

- The actual measurement can differ from the physical model significantly
 - Due to various effects coupled together, beam hardening, scattering, metal partial volume, etc.
 - Hard to integrate them individually
- Consider a modified model to reduce the influence of the defective measurement to the MBIR cost*

$$-\log p(y|x) = \frac{1}{2} \sum_{i=1}^M \mathring{a} H_{L,t} \left(\sqrt{w_i} (y_i - A_{i,*}x) \right)$$

– $H_{L,t}(\times)$ is the generalized Huber function

$$H_{L,t}(e) = \begin{cases} e^2 & |e| < L \\ 2tL|e| + L^2(1-2t) & |e| \geq L \end{cases}$$

– Use $t = 0.5$, $L = 0.5$

